

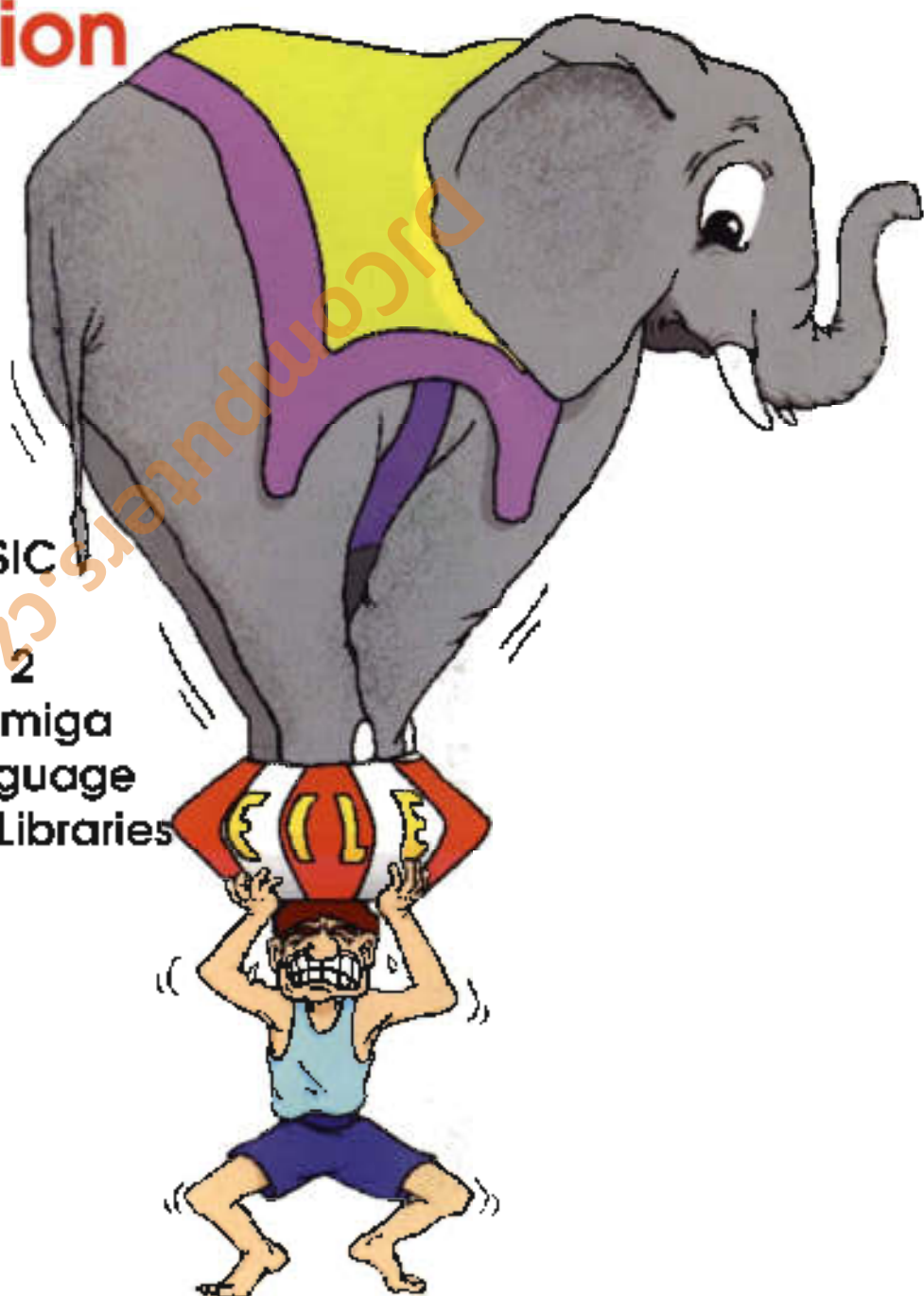


AC's TECH / AMIGA

For The Amiga 4000

Volume 4 Number 2
US \$14.95 Canada \$19.95

A Look at Compression



- True F-BASIC
- A Date with TrueBASIC
- A Better Way to C
- Huge Numbers Part 2
- Programming the Amiga
in Assembly Language
- AmigaDOS Shared Libraries



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Contents

V o l u m e 4 N u m b e r 2

- 3 True F-BASIC**
by Roy M. NUZZO
- 9 A Look at Compression**
by Dan Wells
- 14 A Date with TrueBASIC**
by T. Daniel Westbrook
- 22 Building an Audio Digitizer**
by John Iovine
- 26 A Better Way to C**
by Paul Gittings
- 42 Huge Numbers Part 2**
by Michael Grolbling
- 54 Programming the Amiga in Assembly Language: Using the Math Co-processor**
by William P. Nee
- 68 AmigaDOS Shared Libraries**
by Daniel Stenberg

Departments

- 2 Editorial**
- 40 List of Advertisers**
- 41 Source and Executables ON DISK!**

Startup Sequence

Hug A Beginner

AC's TECH is devoted to the Amiga user who wants to go deeper into the Amiga. Through hardware projects like Building an Amiga Disk Drive (on page 22 of this issue), AC's TECH readers have been able to understand more about the hardware capabilities of the Amiga and how the Amiga relates to other peripheral hardware. In addition, software has also been a major part of AC's TECH as we continue to offer programs in Tree BASIC, C, Assembly Language, and more. These articles and programs are a catalyst to users who have an understanding of the Amiga, but want examples to help them create their own works.

Teaching To Learn

A very important facet of teaching anything is that once we focus on how to explain something to another person, we gain a clearer picture of our subject for ourselves. We begin examining the project or subject from a variety of different views to be able to explain the subject in various ways so it is more readily understood by the student. This examination often opens barriers to our own understanding.

If we have become complacent with an idea or a concept, we begin to view the idea from a static angle. However, if we are challenged to look beyond (and around) mental

effort that prevented the individual for the achievement. This is not egotistical or ungenerous. These people are genuinely proud of what their friend or student has been able to do. Their pleasure being part of that is very human.

Asking More

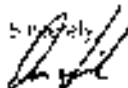
I have often asked our readers to be more involved in the Amiga market. I have asked them to talk with their dealers and with developers to offer positive suggestions on how products or services may be improved. I feel that anyone who has an investment in the Amiga, either financially or mentally, owe it to themselves to do what they can to create an Amiga marketplace that services them. What we can not target is that new users read our input over and over.

When a newly purchased Amiga (new or used) is sitting in front of its new owner, immediately there are a thousand questions to be answered. While it is important that users should learn as much as they can by themselves, it is also important that they have a source for experienced help.

A strong argument could be made that this is all the dealer is paid to do. However, a dealer cannot be available whenever the new user stands before another new concept. While most dealers strongly support their customers, none of them are available as often as a new "crisis" or "crisis" may appear.

Many new users are buying used machines from Amiga users who are trading up to more powerful Amigas such as the Amiga 4000 or 1200. These "new" machines require as much support as Amigas delivered from a showroom. While most users want to support someone who has purchased their old Amiga, there is always the call of the new Amiga to pull them away. Sometimes it is difficult to rationally explain a kickstart incompatibility when all you really want to do is fire up the latest and greatest graphics package on your fully expanded Amiga.

However, the student can surpass the teacher. The person who is just starting today can easily become your best resource in the future. Would I make a list of some to help them now? You could need them.

Sincerely,


Don Hicks
Managing Editor

Each of us can point to at least one person who helped us in the past become what we are today.

None of the products and articles discussed in AC's TECH should be taken at face value—each article is a means to an end. The staff at AC remain dedicated to creating more informed Amiga users. *Amiga Computing For The Commodore Amiga* consistently offers product reviews, new product announcements, bug fixes, hints and tips, and more. AC's *Guide To The Commodore Amiga* maintains a database of software and hardware tools available in the Amiga market.

The aim of AC's TECH is not to make everyone a hardware hacker or software guru, although we would be very excited if it did. The purpose behind AC's TECH is to make users more comfortable with the thought of creating software programs or combining hardware peripherals on the Amiga. If the ideas and projects presented here help to create superior hardware developers or software designers, then we are more than pleased.

This means that while the projects and articles presented in AC's TECH require technical knowledge and should not be attempted unless the Amiga user is aware of the possible consequences, beginners should not be dissuaded from getting a more experienced user to help them. This "buddy system" will not only create more competent users for the Amiga, but it will also challenge the more experienced user.

blocks, we begin to see the concept anew. It is as if we have found a door in our house that leads to a completely new living area.

In the movie "Stand By Me" Robin Williams plays a teacher in a rural middle school. At one point, he challenges his students to stand on the desk and look at the classroom from a different perspective. When the students discover this view of their world that they never knew existed, what they take with them is the ability to challenge the normal and consider different concepts.

Teaching informs the teacher. By becoming secure in the details and concepts, the teacher becomes more confident in the subject. This makes better teachers (as long as they remain open to different views) and it makes better hardware enthusiasts.

We All Started Empty

Fortunately none of us started life knowing everything. We have all needed to learn things through time. Each of us can point to at least one person who helped us in the past become what we are today. The fortunate of us can point to a number of people who have made a difference when they took the time to help us understand what they already knew.

There are also those individuals who can point with pride to an accomplishment or success they have helped and know that it was their

True F-BASIC?

by Roy M. Nuzzo

Do you like weird? This is weird. However, it is good weird. I will show you how to write, debug, and run F-BASIC from True BASIC.

What?

No. Really. There is method in this madness. First the reasons why. True BASIC is very intuitive and easy to dream in. It is a super fast idea testing environment. The reasons are several. The language is very coherent and unfettered. The language editor is just simply the best thing out there for any file editing purpose. The editor takes macros to an unprecedented level. It can even rubble and edit its own structure. That is what this article will show you. True BASIC has some flaws. OverScan and the new AGA modes are not supported. There is no stand alone linker for the 32 bit machines.

What
do you get
when
you cross
TrueBASIC
with
F-BASIC?

F-BASIC has a single author feel, lots of idiosyncracies, very arcane command syntax structures, and mixed model borrowing from many languages (I feel at home with the throw back to Fortran66-like string handling I grew up on that). However, what F-BASIC does, it does very well. It does overScan and AGA graphics. It does many neat things directly that other languages require you to do with nasty add on support. It also drives you crazy with the most annoying text editor on Earth.

Solution. Take the True BASIC editor and turn it into an F-BASIC editor that writes, compiles, runs, and debugs F-BASIC.

The 'TBC' (we'll call the True BASIC editor 'TBE') has a 'Do' feature. You write what is essentially a program except that it is placed at the top of an external library as a first subroutine in that library. This library is simply a sequence of subroutines saved as a separate file (compiled or uncompiled). By issuing a command to 'Do filename', the first sub in that file is activated as if it were a stand alone program and executes as would a program.

However, it operates in the editor's background. While it is running, you are looking at the text in the editor. The 'Do Program' does not replace or cover the current file that you are looking at. The 'Do machine' may be passed a string argument. If you omit the string argument, it supplies its own as a null. That string might be a complex string of a million arguments but we do not need that here.

The 'Do program' automatically has access to the code (text) currently residing in the editor, and can read it and modify it right as you are looking at it. It can also do anything that any program can do such as send out system shell commands, organize and read files, whatever.

The TBE can also load binary files and edit directly by typing from the keyboard or by way of clever 'DO' programs. It can load a copy of itself and edit its own code and resave the modified editor in working tip top shape.

⇒

True F-BASIC

FC_Do F-BASIC Compile Only

! FC_Do Do F-BASIC Compile Only Written by Roy M. Muzze

. Compile and save as 'FC' in the 'TEST' drawer.
 . This is a 'Do' program called from within the True BASIC editor.
 . Save the file to the 'FBI' directory.
 . At the command window type 'do FC, /i:command' and go back then enter.
 ! F-BASIC is case sensitive so use correct case.
 ! The True BASIC editor will launch FBI with the debugger option.
 ! If the file screws up, the debugger shows a text file read by
 ! the Do program.
 ! The Do program returns to the editor with the line number that failed.
 !
 ! At the command window type 'do /lines:numbers'

X:KQVZ

```

x&= BasicCompileLine$(1:FF10Name$)
LIBRARY "TEST\library\A digit.dbl"
    
```

```
let fileNames = Trim$(Trim$(Name$))
```

```

if fileNames = "" then
! TRY TO GET CP 0, IF ONLY LOADED FILE
ask user fileNames
when error is
open #100: name "J:\ & fileNames, organization
" K \ LIBBOLD
close #100
use
close #100
msg$=err$(1: "Load Do FB, /i:command")
end when
end if
    
```

```

when error is
when error is
do /file:delete J:\ & fileNames$ & ".FBT"
use
end when
    
```

```

call GETLINE # & F: #Name$ & " (g)-d")
ans$(100) = 0
    
```

```

of ZVCans = * DO LINE
let count = 0
    
```

```

WHEN ERROR IS
open #100: name "FBI" & F: #Name$ & ".FBT"
organization FBXT, CTMATION
let #100: ZVCANS = 0
    
```

```

do while more #100
line input #100: #
if count = count + 1
loop
    
```

```

let ZVCANS = * F: # & ZVCANS & " (count) & ".
display when done: #
count 100: #
    
```

use

```

END WHEN
close #100
    
```

```

! _____ write running name
! call GETLINE # & F: #Name$ & ".FBT"
! _____
    
```

```

ERR
cause error 1, Error(1) & " (Name$)
err: #10
err: #10
    
```

```

ERR: Error 1, Error 1 & Error(1)
ERR: #10
    
```

FR_Do F-BASIC Compile & Run

! FR_Do Do F-BASIC Compile & Run Written by Roy M. Muzze

. Compile and save as 'FR' in the 'TEST' drawer.
 . This is a 'Do' program called from within the True BASIC editor.
 . Save the file to the 'FBI' directory.
 . At the command window type 'do FR, /i:command' and go back then enter.
 ! F-BASIC is case sensitive so use correct case.
 ! The True BASIC editor will launch FBI with the debugger option.
 ! If the file screws up, the debugger shows a text file read by
 ! the Do program.
 ! The Do program returns to the editor with the line number that failed.
 . At the command window type 'do /lines:numbers'

Three ways to make your life easier:



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Amazing Computing For The Commodore Amiga is dedicated to Amiga users who want to do more with their Amigas. From Amiga beginners to advanced Amiga hardware hackers, AC consistently offers articles, reviews, hints, and insights into the expanding capabilities of the Amiga. *Amazing Computing* is always in touch with the latest new products and new achievements for the Commodore Amiga. Whether it is an interest in Video production, programming, business, productivity, or just great games, AC presents the finest the Amiga has to offer. For exciting Amiga information in a clear and informative style, there is no better value than *Amazing Computing*.



AC's TECH / AMIGA

AC's TECH For The Commodore Amiga is the first disk-based technical magazine for the Amiga, and it remains the best. Each issue explores the Amiga in an in-depth manner unavailable anywhere else. From hardware articles to programming techniques, *AC's TECH* is a fundamental resource for every Amiga user who wants to understand the Amiga and improve its performance. *AC's TECH* offers its readers an expanding reference of Amiga technical knowledge. If you are constantly challenged by the possibilities of the world's most adaptable computer, read the publication that delivers the best in technical insight, *AC's TECH For The Commodore Amiga*.



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True F-BASIC

As told by AC Tech #3.4 and Amiga World Aug. '93

The LANGUAGE For The Amiga!

One Amiga language has stood the test of time. This new package represents the fourth major upgraded release of F-BASIC since 1988. Packed with new features, F-BASIC is the fastest and fullest yet. The power of C with the friendliness of BASIC. Compatibility with all Amiga platforms through the 4000...compiled assembly...object code...with incredible execution times...features from all modern languages...an APEXX port...PA...and ECS/AGA chip set support...Free technical support... This is the FAST one you've read so much about.

F-BASIC 5.0TM

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1.3, 2.0, 2.1 and 3.0

F-BASIC 5.0TM System \$99.95

Includes Compiler, Linker, Integrated Editor Environment, User's Manual, & Sample Programs Disk.

F-BASIC 5.0TM + SLDB System \$159.95

As above with Complete Source Level Debugger.

Available from DJ COMPUTERS SYSTEMS, INC. (605) 348-0791

PO Box 2140 Fall River, MA 02722

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LIBRARY:

NAME: BASIC50
LIBRARY: F:\BASIC50

100 ***** - 111111 - *****

11 ***** - 111111

BY NAME OF CLIENT: F:\BASIC50

DATE: 11/11/88

TIME: 10:11

DATA: C:\BASIC50

DATE: 11/11/88

TIME: 10:11

DATE: 11/11/88

TIME: 10:11

DATA: C:\BASIC50

DATE: 11/11/88

TIME: 10:11

11 ***** - 111111

Complete source code and listings
can be found on the
AC's TECH disk.

Please write to:
Roy M. Nuzzo
c/o AC's TECH
P.O. Box 2140

Fall River, MA 02722

Compression

except when there is a single letter, then the code takes up more space than the original letter. In fact if you had a block of text that very few letters were next to a similar letter (just this article) then the "compressed" file would be much bigger than the original. In compression "lingo" this is known as the degenerate case, and most algorithms have some sort of worse case situation. In this algorithm we "let the air out" of the file by counting runs of information that are the same.

Counting the runs of information is known as "Run Length Encoding" or RLE for short. RLE is used in the IPT IBM standard, and is very good where there are long runs of the same value. For this reason a two color picture (black and white for instance) compresses very well where a 24 bit picture (approximately 16.8 million colors) does not. Of course if the whole 24 bit image was one particular color then it would compress very well, but usually they are not.

Another advantage of RLE is that it executes quickly and is easy to implement. The following is a block of pseudo code that implements an RLE compressor.

```
/* File compressor */
main()
{
  ifstream in;
  while (in.get() != EOF)
  {
    char c = in.get();
    if (runCount == 0)
    {
      if (runCount == 0)
      {
        cout << c;
        runCount = 1;
        c = in.get();
      }
    }
    else
    {
      runCount++;
    }
  }
}
```

The only problem with this code is that it assumes that the program that decompresses the file can tell a number from a series of data. In the previous example let's replace the letter 'A' with 1, 'H' with 2 and 'C' with 3. The data then becomes:

```
"11121122112111133333 3333333333333 333 111222112111"
```

and the compressed version becomes:

```
"113311311111211211221122112211"
```

This is clearly a problem since you can't tell the numbers from the data. We can get around this with the following convention. The first byte of the file will always be a count byte. The second byte will always be a data byte. This means that we can only do a run of at most two characters before we must define a second run of the same character. This way, the odd bytes in the file are count bytes and the even are data bytes.

Modifying the above code we get:

```
/* File compressor */
main()
{
  ifstream in;
  while (in.get() != EOF)
  {
    char c = in.get();
    if (runCount == 0)
    {
      if (runCount == 0)
      {
        cout << c;
        runCount = 1;
        c = in.get();
      }
    }
    else
    {
      runCount++;
      if (runCount == 255)
      {
        cout << "\n";
        runCount = 0;
      }
    }
  }
}
```

Now we can write the decompressor. The pseudo code would be:

```
/* File decompressor */
while (in.get() != EOF)
{
  int count = in.get();
  for (i = 0; i < count; i++)
  {
    cout << c;
  }
}
```

As you can see the decompressor is trivial, which is a desirable attribute. In most cases it is more important to be able to decompress quickly than to be able to compress quickly. In the case of high speed animation (30 frames per second) compression is used as a way to get the image to times the hard drive (or CD ROM) quickly (by having less data to load). Once the data is loaded it must be expanded quickly. This is your friend here.

But it needs a better ability to handle data that is nearly random. As mentioned in the beginning the case of every character being different than the last one would result in a doubling of the file. What we need is a way to block out these runs of randomness. Taking a page from the IPT IBM implementation of RLE we will do the following:

If the high bit is set in a count byte then clear the bit and copy the number of bytes indicated directly from the file.

If the high bit is not set on a count byte then copy the next byte the number of times indicated.

This reduces the maximum run to 127 but handles random cases much better. The modified compressor pseudo code looks like this:

```
/* File compressor with random support */
main()
{
  ifstream in;
  runCount = 0;
  runCharacter = '\0';
  while (in.get() != EOF)
  {
    char c = in.get();
    if (runCount == 0)
    {
      if (runCount == 0)
      {
        cout << c;
        runCount = 1;
        runCharacter = c;
      }
    }
    else
    {
      runCount++;
      if (runCount == 255)
      {
        cout << "\n";
        runCount = 0;
      }
    }
  }
}
```


Compression

dictionary it only needs to be built into the compressor and decompressor, not sent. This is the idea used by fax machines. When defining the Group 3 fax standard thousands of faxes were analyzed to find typical runs of white and black runs. When they were finished, a static dictionary was released, and built into every Group 3 fax machine. Here, use there is a very high chance that noise on the phone line could scramble the data, each line of the fax is treated as a separate "file". In a perfect world the whole fax would be one stream of data, but if a noise gets through then count bytes could be lost, as data and vice versa resulting in chaos. Treating each line separately limits the damage to a single line.

It would seem that every fax is very different and that a simple RLE algorithm would be better but the dictionary based compression works very well, but only for faxes. If you try to apply the fax dictionary to regular data, the results are not so good. As you would expect this is typical of all dictionary based compression methods. An optimal dictionary for one file is not optimal for another.

How then do you build an optimal dictionary? In the case where there is a logical unit of information, like words in a sentence, a dictionary can be built from these units, much like in the "IN/OUT" example. In situations where the data appears random what you choose for the entries in the dictionary don't matter. Don't matter? you say. No, it doesn't really matter. Pioneering work by Abraham

matched. Clear the buffer down to the last character read and start again.

What this does is continue to build longer and longer codes based on what has come so far. This is perfect for picking up runs of characters that repeat, like words. It may seem very inefficient to add a new code into the dictionary for every character or groups of characters encoded but it has two advantages. The first is that you never know when a sequence of data will occur. By building a large table you stand a very good chance of catching the same sequence again. Using this method you can even catch longer sequences like repetitive phrases (such as "I have a dream" from Martin Luther King Jr's famous speech). It also is very good at encoding long runs of the same data. The repeating string of 'XO' (as in NOXOXOXOXOXOXOXO) would not be compressed by RLE encoding, but the LZW version would first save the X then the O then the next letter XO, XOX, OX, OXO and finally XO. All together the data would be reduced to seven codes, a significant savings.

The second reason to encode all of the combinations is so that you do not have to send the dictionary along. Remember one of the disadvantages of dictionary based compression is having to send the dictionary. By using the a well defined method for creating the dictionary from the data you can create the dictionary from the compressed data and codes as well. Let's look at how.

Soon, they tell us, we will be able to fit 72 minutes of full motion video and sound on a CD where today we can only fit 72 minutes of sound.

Lempel and Jacob Ziv (the L and Z of LZW compression) showed in the late sixties that you can create a useful dictionary on the fly by looking at the file.

Lempel, Ziv and Welch

LZW (Lempel, Ziv, Welch) compression is the backbone of much of the general purpose file compression today. The modern V42.bis compression method is based on LZW and the GIF and TIFF graphic formats use it as well. The idea is deceptively simple yet represents a major breakthrough. The basic algorithm works as follows:

Create a dictionary array with some number of entries (2K to 4K entries is typical). Assume that the table starts with entry 256 because entries 0 to 255 are assumed to contain themselves (ie entry 291 contains 290). Read the first two bytes in the file. Place the combination of the two bytes in the dictionary as the first entry. Since there was not a match for the pair in the dictionary originally, output the first byte and shift the second one down. Read the next byte. Does the buffer now hold a combination that is in the dictionary. If not, do as the first time. If it does match a combination in the dictionary, then keep reading data until you can no longer make a match. Then make a new code out of all the data and output the last code that was

How's it done?

Copy back to our first example we start with:

```
*****A*****A*****A*****A*****A*****A*****
```

The first two characters are read in. Since no codes exist yet, the first 'A' is output and the combination 'AA' is made entry 256 per 256. Now the third 'A' is read in. Combined with the second 'A' it makes 'AA' which is code 256, so we read in another byte hoping to find an ever longer match. We don't so we output the code 256 in place of 'AA', take the current buffer of 'AA' and make it code 257. Then we remove the first two 'A's since they have been output and read in the next character. Reading in the fifth character we get 'AA' in the buffer. Since we have a match for 'AA' we read the next character hoping for a longer match. The sixth character is an 'A' so the buffer is now 'AAA'. This matches code 257 so we add another character. The seventh character is also an 'A'. There is no code for 'AAAA' so we output 257, create code 258 and remove the code 'AAA' from the buffer leaving 'A'. The next piece of data is 'B'. Combined with the 'A' we get 'AB'. There is no code for this so we have to output the 'A' by itself and create code 259. The next 'B' continues to make 'BB'. There is no code for this either so the first 'B' is output and 'BB' becomes code 260. Next is an 'A' the 'B' in the buffer

Compression

and the 'A' make 'BA' which has an code. Code 261 is created and the 'B' is output. Next to an 'A', 'AA' is a code we know so we try for more. 'AAA' is known as well so we continue. 'AAAA' is also known so we try for five 'A's. We don't have a code for five 'A's so we output code 258 and create code 262 with first 'A's. Let's stop here a minute and make a table of what we have done.

Input	Output	Code Table
'AA'	'A'	256 = 'AA'
'AAA'	256	257 = 'AAA'
'AAAA'	257	258 = 'AAAA'
'B'	'A'	259 = 'AB'
'B'	'B'	260 = 'BB'
'A'	'B'	261 = 'BA'
'AAAA'	258	262 = 'AAAAA'

As you can see it paid off later for creating the code 259 earlier. At this point any run of 'A's from two to five characters can be encoded by a single code.

But how does it look from the other end? How does the decompressor recreate the file? Working only from the data in the file we will recreate the dictionary and the file. The compressed file is:

```
0x258 0x259 0x262 0x261
```

The decompressor starts with an empty dictionary. Reading the first 'A' the decompressor places it in an empty buffer. The next code is [256]. This means that the compression program found a match on the second character. Since the first character is an 'A' and the second and third characters were the same as the first and second, the first two characters must be the same. The decompressor adds a second 'A' to the buffer and creates code 256, which it then outputs and leaves 'AA' in the buffer. The next piece of data is a code as well so again the new character must be an 'A'. Code 257 is created and output. The next piece of data is an 'A'. Since this is not a code, then we know we need to flush the buffer. The code 258 is created and the buffer is flushed except for the 'A' just read in, namely the 'A' is output. The next character is a 'B'. Again since this is a character code, the code 259 is created and the buffer is flushed except for the 'B', which is output. The next 'B' repeats the process. The code 258 causes the buffer to be loaded with the first character from the code. Code 261 is created from the 'B' and the first 'A' in code 258. Now the entire entry for code 261 is loaded and output.

As you can see, the dictionary is recreated on the fly from the order of the data and the rules used to create it. While the explanations can get a bit lengthy it actually works out to be a straight forward algorithm. It is very good at compressing files that have repetitive data in them. Text files are loaded with repetitive data as are many graphics files. For example, a black and white file that has a gray pattern (every other bit is black) does not compress using an RLE algorithm. But as shown by the "XXXXXX" example earlier, LZW will go better and better at compressing the file until it can take very large chunks of time. This ability to adapt to the data is what makes it so powerful.

What's the difference

When we first looked at dictionary compression we noted that the best results came when you understand the data you are compressing. LZW does well even when it knows nothing about the data. But if we look at the data, very often we can "help" the LZW algorithm. The best case of this is called horizontal differencing. If you look at 24 bit pictures, they tend to feature gentle transitions from one color to another unlike Deluxe Paint pictures, which offer sharp contrasts. If you think about it the transition from light to dark red is the same as from light to dark blue except for the color. To take advantage of this, we take the data and preprocess it.

Take the value of the first pixel and subtract it from the second pixel, store the original first pixel and the difference between the first and second as the second pixel. Compute the third pixel by subtracting the original second pixel from the third pixel. Continuing through out the file you will notice some things. In places where there is a gentle even change, you will end up with long strings of the same value, which compress very well. Gradients of all colors now look the same (and compress with the same codes) because the change data instead of the color data is being recorded. In the case where the colors are random, then the data is random either way. In effect, this becomes a win/win situation for very little effort. The file is easy to recompress, and it has been compressed. Simply take the first pixel and add it to the second. Add the second to third and so on.

More later

Well that concludes an overview of two of the more popular methods of data compression. There are many others, and there is even more to LZW than what we covered... In another issue of AC's Tech we will look at implementing these and other compression algorithms on 'C'. Until then, keep in touch through this magazine or via Internet at dave@delux.com.

Complete source code and listings
can be found on the
AC's TECH disk.

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A Date with TrueBASIC

by T. Darrel Westbrook

We use calendar dates in many applications. Working with dates requires planning regarding their use internally in the program and how we display or use them in a program. We must check dates entered by application users for accuracy. The checking process must make allowances for the day of the month, whether it's a leap year, and how you would like to display the date. Personally, I dislike cryptic date displays that are difficult to read at a glance. Consider 01-07-93. Is it 7 January 1993 or 1 July 1993? A displayed date (on screen or printed) should be easily read, like 1 Jul 93, and the format should be user selectable. With the ability to determine the day of the week, you can write applications that build calendars, display full date information, perform scheduling functions, etc. This article explains a True BASIC module that supplies these attributes for your programming use.

I designed the True BASIC Date Module, outlined in this article, for maximum flexibility. It returns suitable date information to the calling program for use on screen or on a printed medium. The date information is also usable for sort keys. Additionally, this article highlights a workaround for a bug in the Amiga True BASIC language date functions, which is present in both versions 1.0 and 2.0 of the language. Finally, I'll discuss error routines and how you can cheaply, code wise, trap a lot of general input errors.

You can use Listing 1 to test the Date Module capabilities. The Global Module subroutines, 'error reset' and 'make error', are necessary for the Date Module to function properly and must be included in your programs. Reference lines 93 through 114 for these two subroutines. The Date Module is Listing 2. Line numbers are for reference only.

Throughout this article I will reference a 'date template'. The date template is any combination of day, month, and year expressed as DD or DD for day, MM or MM for month, and YY or YYYY for

```
'02 Jan 94' is the system date, which is a 'Sunday'.
```

```
I used a date format of DDMMYY.
```

Left: Screen showing the current system date.

A Date with TrueBASIC

year. The date module converts any case combination of the date template into upper case. Later, I'll discuss what each part of the date template represents. But first, calendar background will provide historical insight behind the structure of the Date Module.

A calendar, according to the *Encyclopedia Britannica*, "is a means of grouping days in ways convenient for regulating civil life and religious observances and for historical and scientific purposes." An ideal calendar would be tied to the movement of the moon phases, seasonal events, and religious holidays. Astrological events, which happen every year but are slightly different each year, are the basis for most religious holidays. For example, the vernal equinox is the basis of the Christian Easter holiday. The vernal equinox occurs when the sun passes northward over the equator. It marks the first day of spring and is generally around 21 March. The exact occurrence of the many Christian holidays use the Easter holiday as a baseline. It is easy to understand why this was important to religious leaders. Other religious holidays, like the Jewish Passover, are determined by their relationship with specific astrological events, like the vernal equinox.

In February 1582, Pope Gregory XIII issued a proclamation that brought the vernal equinox back to 21 March. The proclamation abolished ten days that had accumulated over the past centuries. The Pope added the ten days to 5 October to make 11 October for the feast of St. Francis, which occurred on 5 October. The 365,2422 days per year became the new year length. The year length of 365,2422 days per year replaced the old Julian calendar year length of 365,25 days per year (the correct value is 365,24199). This was a difference of 0,00278 days from the old Julian calendar (since 484,364 and resulted in a 12 day error for every 400 years. This correction eliminated three out of every four centennial leap years in the Julian calendar. This change is why every centennial year that is evenly divisible by 400 is a leap year. For example, the year 2000 is a leap year, but the centennial year 1900 is not.

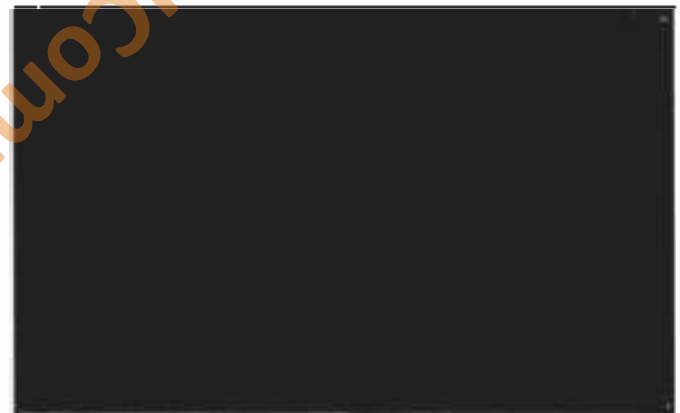
Leap years happen every four years (years that are evenly divided by four) besides the centennial leap years. The year 1900 and 1800 are both leap years. If you calculate dates before 15 October 1582, you would need to allow for the changes made by Pope Gregory XIII's proclamation. I could get quite involved. The Date Module uses 1 January 1900 as the cutoff to simplify the program. I didn't have any need for dates before 1900, but I didn't want to build to match and integrate into the module. The module determines if a year is a leap year in the subroutine (see lines 967 to 977) and sets the leap flag variable to either one (leap year) or zero (non-leap year).

You can use the Date Module to establish a specific date template for use in your programs. You can allow the user to change the date template by using the `ChangeDateFormat` subroutine. For a given date, the module subroutines return the day of the week (Sunday through Saturday) and a day of the week number (1 through 7). The day of the week number is

suitable for determining weekdays for scheduling programs, calendar generating programs, etc.

The Date Module returns similar information for the month (i.e., numbers 1 through 12 and corresponding names of January through December). Month abbreviations (Jan, Feb, etc.) are also available for your programming use. The subroutine provides ten sortable dates for internal program use. They are the string form of `and` and `YYYYDDDD`. (The date template is the format used by `parse_date` to arrange the order of day, month, and year in the date. The order of the individual items in the date template is as important as the location of the Ds, Ms, and Ys. The module will accept single or multiple Ds for the day. The subroutine pads a single digit day with a leading blank for a single D character in the date template. For multiple Ds it pads the single digit day with a leading zero. The month format is similar to the day determination.

The date template determines the returned month format and where the `parse_date` routine searches the input string for the month. If the template has one or two Ms, it will return the date as a two digit numeric month. If your date template has three Ms, the date returned will have a three character month (like Jun). When there are four Ms in the template number four or more, then you get the full spelling of the month. A similar operation occurs with the year, but it will only accept two and four digit



Above right: The cli overlay.

Right: The Change Template screen.

A Date with TrueBASIC

years. Therefore, the only valid year input is YY and YYYY leapdate. The `tu_date` variable is the returned variable in the date template format. If there are other combinations or formats of dates you would like returned to your calling programs, it is easy to modify the Date Module to get exactly what you want. Since the date template defines the contents of `tu_date`, you probably shouldn't change it. You can change any of the other returned variables without affecting the Date Module performance or you could add another variable to the argument list of the `parse_date` subroutine.

The `parse_date` subroutine (lines 334 through 510) will recognize program inputs that conform to date template delimiters. A date delimiter is a printable character that separates the day, month, and year. The module uses the `del` pointer to format the returned date values (i.e., `tu_date`). The most common delimiter is the dash (-) or colon (:), but between the day, month, and year. For example: the program code converts 1,0193 to 01-07-93 for a date template of DD-MM-YY. The Date Module will recognize any printable character except an alphabet letter or a number as a date template delimiter. If you have several delimiters in a given template, the program will recognize them all, but will use only the last one in the template string as the delimiter for the module. When you use the Date Module in a True BASIC program, lines 232 through 236 initialize the module. The `SHARED` variables (lines 232 through 235) are self-explanatory. The `Max_Day` subroutine and the date function are `PRIVATE` to the module (lines 236 and 237). These two are not callable outside the Date Module. I did this to prevent changing the year, max_day, or factor, and leap_flag outside of module control. If you want to address these procedures outside the limits of the module, remove the `PRIVATE` statements.

Lines 238 through 225 initialize Date Module variables. The `Change_Date_Format?` subroutine (line 284) initializes the date template variables `length`, `lengthm`, `lengthy`, `delimiter`, `user_date_format`, and `order_date_string`. I need these variables throughout the module as module-specific global variables. It cuts down a lot of code overhead when you `SHARED` variables within a module. I have included a small

subroutine, `Get_Date_Format`, to return the current template to the calling program.

If you want to initialize your Date Module with a different template, change line 221 to the template you want to use. You must also change the `order_date_string` variable, line 225. I used the `order_date_string` variable to resolve conflicts that occur from user input. If a fourth character string, or the blank for the first character. The following three characters must be one each of D, M, and Y. The DMY characters help module subroutines make decisions regarding user input when it doesn't exactly match the date template or other input parameters. The `parse_date` subroutine, line 334, uses the `order_date_string` to resolve a user input date to the date template. This subroutine accepts any date input (like user input) that does not originate from the computer system. The date module gets the computer system date from the `System_Date` subroutine. You must be careful when you use the Amiga True BASIC date functions. These date functions have a software bug that can make your system date seem inaccurate.

True BASIC has two built-in date functions. They are `date` and `date$`. The `date` function returns the current machine date in the form of YYDD, which is a Julian date format, and `date$` uses the YYYYMMDD format. The Amiga True BASIC version does not recognize leap years.

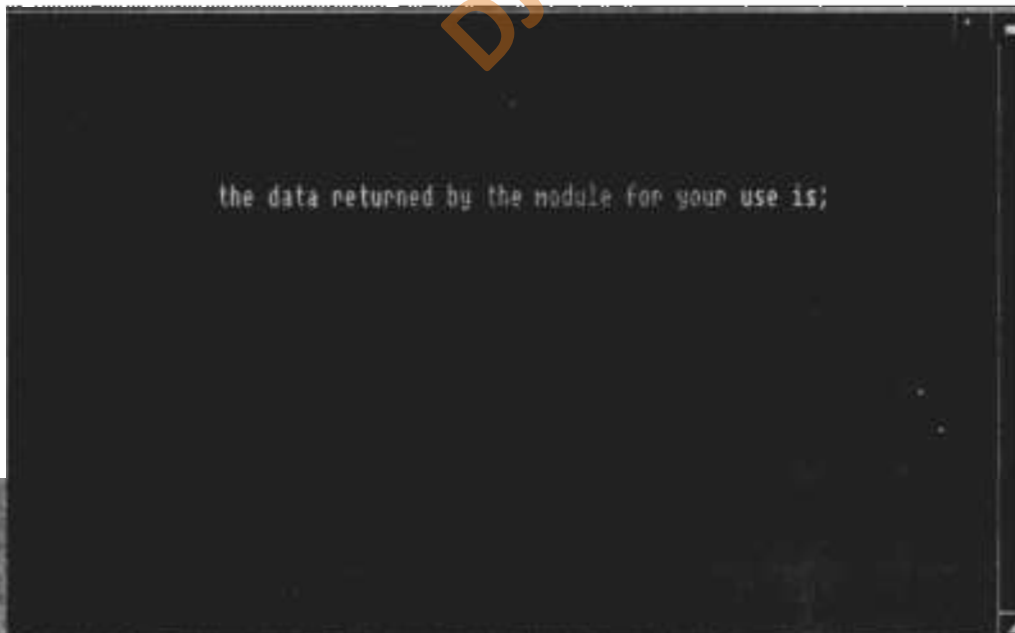
It manages dates well until 25 Feb of a leap year. On that day, the language will report 1 Mar of the leap year, even though the date returned by True BASIC is one day off throughout the remainder of the leap year. Both functions (`date` and `date$`) are off by one day.

On 31 Dec of the leap year, True BASIC gets confused and finally realizes that something is wrong. It returns the date YYYY(,0) for the `date$` function and YYYY(0) for the `date` function. This is the only instance when True BASIC returns a zero for the day. When the user enters a non-leap year date or the system date does not reflect a leap year, the language will return valid data. The code from the `date$` function (lines 249 to 253) in listing 2 corrects for True BASIC software bug. The bug is not present in the IBM version of the language. Delete lines 245 to 274, if you use this code for the IBM machines. Although the IBM True BASIC version does not need this code, the code will function as outlined in this article on an IBM compatible machine.

You can test this software bug by using a utility that allows you to change the Amiga system date like `TimeSet 2.0` by David Holt. If you don't have one of these Public Domain date/time setting programs, then use the CLI program, `date`. From a CLI, type:

```
date 23 Feb 92
```

which is a leap year. Just to see if the system accepted the date, type `tu_date`, which should display `23 on day 23-Feb-92` plus the cur-



Left: The Date Module screen.

A Date with TrueBASIC

rent time. Use the Amiga's multi-tasking capabilities and have True BASIC up and running. From True BASIC command input screen (press F2 while in the True BASIC editor), type:

```
print date$
```

which will print out 19930301, which translates to 1 Mar 93. You can check the YYYYMMDD True BASIC output by setting the system date to 01-Dec 92. Be aware that the AmigaDOS date program will not accept dates before 1 Jan 78. This is the date the software recognizes as the base line of its existence. The Date Module does not share this limitation. It will accept dates between 1 January 1700 to 31 December 2199.

The Date Module Date_ Data subroutine returns the following information to the calling program.

year, the numeric year in YYYY format
month, the numeric month (i.e., 1 through 12)
day, numeric day of the month
julian, julian date in the YYYYDDD format
month\$, full alphanumeric month name, like June, m_abbrev\$, abbreviation for the month, like Jun, dow_factor\$, numeric day, 1 to 7 (Sunday to Saturday)
dow_name\$, alphanumeric day of the week, like Sunday, m_date\$, date based on the module date (e.g., 001_01_01\$, YYYYMMDD format)

As you can see, any program which uses dates can use the Date Module. The program also uses a novel means to pass error information back to the calling program without creating a runtime error.

True BASIC has three global variables that it uses for error reporting. They are EXLINT\$, EXTYPE\$, and EXTYP\$. These are normally null and zero, but when an error occurs they are set to the line number, the type of error, and the error number. Appendix C of the True BASIC Reference Manual lists all the language built-in error information. Since the language is expandable, there are commands that allow you, the programmer, to create your own error traps and handlers.

To create your own error traps, you use the WHEN ERROR IN ... USE ... END WHEN structure. If you cause an error, by using the CAUSE ERROR or CAUSE EXCEPTION commands within this structure the program will not experience a fatal runtime error and stop the program. By using the subroutines error_reset and

make_error, you can cause an error of your choosing, then check the EXLINT\$, EXTYPE\$, and EXTYP\$ variables in your calling program. If EXTYP\$ is anything but zero, an error of some type has occurred. Using these global variables releases you from passing error messages back and forth from calling routines to the module and back again.

Line 242 is an example of how this module handles error management. If the value of the system date is zero, then the system date is not



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A Date with TrueBASIC

set. There is no error built into the language that reports that the system date is not set. Line 341 creates an error by passing an error number and an error message to the `make_error` subroutine. This subroutine sets `EXTYPE` to 254 and the `EXTYPE` to "Computer system date is not set". The `EXLINE` variable is set to either line 104 or line 109, depending on the `msg` variable. Program flow then returns to the calling routine which only needs to check the `EXTYPE` to determine if the system date is set. Line 125 and lines 506 to 509 are other examples of using this technique to avoid errors in your program.

The True BASIC Date Module in this article should be a valuable addition to your programming library. The Date Module will decrease your programming time and provide flexibility in handling date variables. It and the error routines are valuable tools to add to your True BASIC library.

Listing One

```

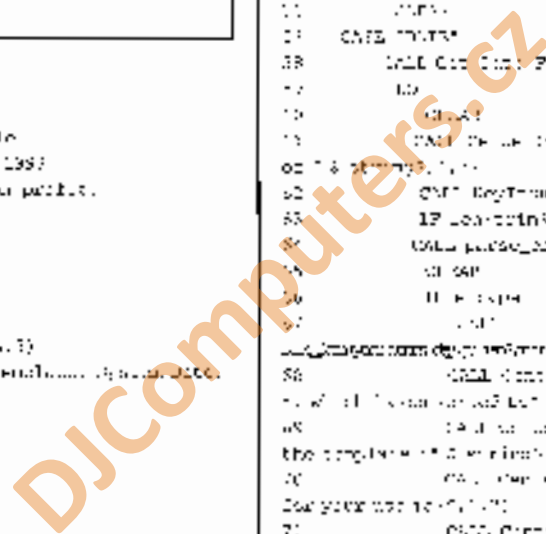
41  REMARK:  This program sets date and time
      time set only in the manual modebook, 1997
51  REMARK:  This is a demo of the date module.
52  ADD SOMEONE.DEM
61
71
81
91
101  GOTO 1
111  CALL DATESET(ENTER_DATE, ENTER_TIME, ENTER_DATE)
121  CALL DATESET(ENTER_DATE, ENTER_TIME, ENTER_DATE)
131  PRINT "DATE: ";
      PRINT "TIME: ";
141  GOTO 1
151  CALL DATESET(ENTER_DATE, ENTER_TIME, ENTER_DATE)
161  PRINT "DATE: ";
      PRINT "TIME: ";
171  GOTO 1
181  CALL DATESET(ENTER_DATE, ENTER_TIME, ENTER_DATE)
191  PRINT "DATE: ";
      PRINT "TIME: ";
201  GOTO 1
211  CALL DATESET(ENTER_DATE, ENTER_TIME, ENTER_DATE)
221  PRINT "DATE: ";
      PRINT "TIME: ";
231  GOTO 1
241  CALL DATESET(ENTER_DATE, ENTER_TIME, ENTER_DATE)
251  PRINT "DATE: ";
      PRINT "TIME: ";
261  GOTO 1
271  CALL DATESET(ENTER_DATE, ENTER_TIME, ENTER_DATE)
281  PRINT "DATE: ";
      PRINT "TIME: ";
291  GOTO 1
301  CALL DATESET(ENTER_DATE, ENTER_TIME, ENTER_DATE)
311  PRINT "DATE: ";
      PRINT "TIME: ";
321  GOTO 1
331  CALL DATESET(ENTER_DATE, ENTER_TIME, ENTER_DATE)
341  PRINT "DATE: ";
      PRINT "TIME: ";
351  GOTO 1
361  CALL DATESET(ENTER_DATE, ENTER_TIME, ENTER_DATE)
371  PRINT "DATE: ";
      PRINT "TIME: ";
381  GOTO 1
391  CALL DATESET(ENTER_DATE, ENTER_TIME, ENTER_DATE)
401  PRINT "DATE: ";
      PRINT "TIME: ";
411  GOTO 1
421  CALL DATESET(ENTER_DATE, ENTER_TIME, ENTER_DATE)
431  PRINT "DATE: ";
      PRINT "TIME: ";
441  GOTO 1
451  CALL DATESET(ENTER_DATE, ENTER_TIME, ENTER_DATE)
461  PRINT "DATE: ";
      PRINT "TIME: ";
471  GOTO 1
481  CALL DATESET(ENTER_DATE, ENTER_TIME, ENTER_DATE)
491  PRINT "DATE: ";
      PRINT "TIME: ";
501  GOTO 1
511  CALL DATESET(ENTER_DATE, ENTER_TIME, ENTER_DATE)
521  PRINT "DATE: ";
      PRINT "TIME: ";
531  GOTO 1
541  CALL DATESET(ENTER_DATE, ENTER_TIME, ENTER_DATE)
551  PRINT "DATE: ";
      PRINT "TIME: ";
561  GOTO 1
571  CALL DATESET(ENTER_DATE, ENTER_TIME, ENTER_DATE)
581  PRINT "DATE: ";
      PRINT "TIME: ";
591  GOTO 1
601  CALL DATESET(ENTER_DATE, ENTER_TIME, ENTER_DATE)
611  PRINT "DATE: ";
      PRINT "TIME: ";
621  GOTO 1
631  CALL DATESET(ENTER_DATE, ENTER_TIME, ENTER_DATE)
641  PRINT "DATE: ";
      PRINT "TIME: ";
651  GOTO 1
661  CALL DATESET(ENTER_DATE, ENTER_TIME, ENTER_DATE)
671  PRINT "DATE: ";
      PRINT "TIME: ";
681  GOTO 1
691  CALL DATESET(ENTER_DATE, ENTER_TIME, ENTER_DATE)
701  PRINT "DATE: ";
      PRINT "TIME: ";
711  GOTO 1
721  CALL DATESET(ENTER_DATE, ENTER_TIME, ENTER_DATE)
731  PRINT "DATE: ";
      PRINT "TIME: ";
741  GOTO 1
751  CALL DATESET(ENTER_DATE, ENTER_TIME, ENTER_DATE)
761  PRINT "DATE: ";
      PRINT "TIME: ";
771  GOTO 1
781  CALL DATESET(ENTER_DATE, ENTER_TIME, ENTER_DATE)
791  PRINT "DATE: ";
      PRINT "TIME: ";
801  GOTO 1
811  CALL DATESET(ENTER_DATE, ENTER_TIME, ENTER_DATE)
821  PRINT "DATE: ";
      PRINT "TIME: ";
831  GOTO 1
841  CALL DATESET(ENTER_DATE, ENTER_TIME, ENTER_DATE)
851  PRINT "DATE: ";
      PRINT "TIME: ";
861  GOTO 1
871  CALL DATESET(ENTER_DATE, ENTER_TIME, ENTER_DATE)
881  PRINT "DATE: ";
      PRINT "TIME: ";
891  GOTO 1
901  CALL DATESET(ENTER_DATE, ENTER_TIME, ENTER_DATE)
911  PRINT "DATE: ";
      PRINT "TIME: ";
921  GOTO 1
931  CALL DATESET(ENTER_DATE, ENTER_TIME, ENTER_DATE)
941  PRINT "DATE: ";
      PRINT "TIME: ";
951  GOTO 1
961  CALL DATESET(ENTER_DATE, ENTER_TIME, ENTER_DATE)
971  PRINT "DATE: ";
      PRINT "TIME: ";
981  GOTO 1
991  CALL DATESET(ENTER_DATE, ENTER_TIME, ENTER_DATE)
1001  PRINT "DATE: ";
      PRINT "TIME: ";
1011  GOTO 1
1021  CALL DATESET(ENTER_DATE, ENTER_TIME, ENTER_DATE)
1031  PRINT "DATE: ";
      PRINT "TIME: ";
1041  GOTO 1
1051  CALL DATESET(ENTER_DATE, ENTER_TIME, ENTER_DATE)
1061  PRINT "DATE: ";
      PRINT "TIME: ";
1071  GOTO 1
1081  CALL DATESET(ENTER_DATE, ENTER_TIME, ENTER_DATE)
1091  PRINT "DATE: ";
      PRINT "TIME: ";
1101  GOTO 1
1111  CALL DATESET(ENTER_DATE, ENTER_TIME, ENTER_DATE)
1121  PRINT "DATE: ";
      PRINT "TIME: ";
1131  GOTO 1
1141  CALL DATESET(ENTER_DATE, ENTER_TIME, ENTER_DATE)
1151  PRINT "DATE: ";
      PRINT "TIME: ";
1161  GOTO 1
1171  CALL DATESET(ENTER_DATE, ENTER_TIME, ENTER_DATE)
1181  PRINT "DATE: ";
      PRINT "TIME: ";
1191  GOTO 1
1201  CALL DATESET(ENTER_DATE, ENTER_TIME, ENTER_DATE)
1211  PRINT "DATE: ";
      PRINT "TIME: ";
1221  GOTO 1
1231  CALL DATESET(ENTER_DATE, ENTER_TIME, ENTER_DATE)
1241  PRINT "DATE: ";
      PRINT "TIME: ";
1251  GOTO 1
1261  CALL DATESET(ENTER_DATE, ENTER_TIME, ENTER_DATE)
1271  PRINT "DATE: ";
      PRINT "TIME: ";
1281  GOTO 1
1291  CALL DATESET(ENTER_DATE, ENTER_TIME, ENTER_DATE)
1301  PRINT "DATE: ";
      PRINT "TIME: ";
1311  GOTO 1
1321  CALL DATESET(ENTER_DATE, ENTER_TIME, ENTER_DATE)
1331  PRINT "DATE: ";
      PRINT "TIME: ";
1341  GOTO 1
1351  CALL DATESET(ENTER_DATE, ENTER_TIME, ENTER_DATE)
1361  PRINT "DATE: ";
      PRINT "TIME: ";
1371  GOTO 1
1381  CALL DATESET(ENTER_DATE, ENTER_TIME, ENTER_DATE)
1391  PRINT "DATE: ";
      PRINT "TIME: ";
1401  GOTO 1
1411  CALL DATESET(ENTER_DATE, ENTER_TIME, ENTER_DATE)
1421  PRINT "DATE: ";
      PRINT "TIME: ";
1431  GOTO 1
1441  CALL DATESET(ENTER_DATE, ENTER_TIME, ENTER_DATE)
1451  PRINT "DATE: ";
      PRINT "TIME: ";
1461  GOTO 1
1471  CALL DATESET(ENTER_DATE, ENTER_TIME, ENTER_DATE)
1481  PRINT "DATE: ";
      PRINT "TIME: ";
1491  GOTO 1
1501  CALL DATESET(ENTER_DATE, ENTER_TIME, ENTER_DATE)
1511  PRINT "DATE: ";
      PRINT "TIME: ";
1521  GOTO 1
1531  CALL DATESET(ENTER_DATE, ENTER_TIME, ENTER_DATE)
1541  PRINT "DATE: ";
      PRINT "TIME: ";
1551  GOTO 1
1561  CALL DATESET(ENTER_DATE, ENTER_TIME, ENTER_DATE)
1571  PRINT "DATE: ";
      PRINT "TIME: ";
1581  GOTO 1
1591  CALL DATESET(ENTER_DATE, ENTER_TIME, ENTER_DATE)
1601  PRINT "DATE: ";
      PRINT "TIME: ";
1611  GOTO 1
1621  CALL DATESET(ENTER_DATE, ENTER_TIME, ENTER_DATE)
1631  PRINT "DATE: ";
      PRINT "TIME: ";
1641  GOTO 1
1651  CALL DATESET(ENTER_DATE, ENTER_TIME, ENTER_DATE)
1661  PRINT "DATE: ";
      PRINT "TIME: ";
1671  GOTO 1
1681  CALL DATESET(ENTER_DATE, ENTER_TIME, ENTER_DATE)
1691  PRINT "DATE: ";
      PRINT "TIME: ";
1701  GOTO 1
1711  CALL DATESET(ENTER_DATE, ENTER_TIME, ENTER_DATE)
1721  PRINT "DATE: ";
      PRINT "TIME: ";
1731  GOTO 1
1741  CALL DATESET(ENTER_DATE, ENTER_TIME, ENTER_DATE)
1751  PRINT "DATE: ";
      PRINT "TIME: ";
1761  GOTO 1
1771  CALL DATESET(ENTER_DATE, ENTER_TIME, ENTER_DATE)
1781  PRINT "DATE: ";
      PRINT "TIME: ";
1791  GOTO 1
1801  CALL DATESET(ENTER_DATE, ENTER_TIME, ENTER_DATE)
1811  PRINT "DATE: ";
      PRINT "TIME: ";
1821  GOTO 1
1831  CALL DATESET(ENTER_DATE, ENTER_TIME, ENTER_DATE)
1841  PRINT "DATE: ";
      PRINT "TIME: ";
1851  GOTO 1
1861  CALL DATESET(ENTER_DATE, ENTER_TIME, ENTER_DATE)
1871  PRINT "DATE: ";
      PRINT "TIME: ";
1881  GOTO 1
1891  CALL DATESET(ENTER_DATE, ENTER_TIME, ENTER_DATE)
1901  PRINT "DATE: ";
      PRINT "TIME: ";
1911  GOTO 1
1921  CALL DATESET(ENTER_DATE, ENTER_TIME, ENTER_DATE)
1931  PRINT "DATE: ";
      PRINT "TIME: ";
1941  GOTO 1
1951  CALL DATESET(ENTER_DATE, ENTER_TIME, ENTER_DATE)
1961  PRINT "DATE: ";
      PRINT "TIME: ";
1971  GOTO 1
1981  CALL DATESET(ENTER_DATE, ENTER_TIME, ENTER_DATE)
1991  PRINT "DATE: ";
      PRINT "TIME: ";
2001  GOTO 1

```

```

17  MAKE_DATE DATESET
18  END
19  END
20  END
21  END
22  END
23  END
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```



A Date with TrueBASIC

```

299      IF ds$ = ""
300      THEN END PROCEDURE
301      LET ds = ds & " "
302      LET length = LEN(ds) : determine type of
year to return
303      CASE 10
304      LET ds = ds * 100
305      CASE TIME_ZONE
306      LET ds = ds & "T"
307      LET length = LEN(ds) : determine type of
year to return
308      CASE " "
309      LET ds = ds & " " : use only the last
character to be
310      LET ds = ds * 10 : keep up the
under_data_strings character
311      LET ds = ds * 10 : characters to allow for
delimiter
312      END CASE
313      NEXT ds
314      IF LEN(ds) > 0 THEN LET ds = ds * 10 : use
315      IF length = 2 OR length = 4 THEN ! length year OK
316      IF year < 0 OR year > 10000 THEN ! invalid year OK
317      IF length = 2 AND ds < "01" THEN
318      ! length day OK
319      LET under_data_strings = string$
320      LET under_data_strings = ds
321      CASE 10
322      END IF
323      END IF
324      END IF
325      CASE ERROR 104 "Date format string is & strings
& is in use on disk."
326      WITH TIME_ZONE
327      LET counter = 1 : count number of times Y, M, or D
occurs
328      FOR each IN ds:IF ! time ok GOTO
329      IF ISDIGIT% = 0 THEN LET counter = counter + 1
NEXT IN ds
330      NEXT IN ds
331      LET m = 1 : use 1 with under_data_strings
using
332      END SUB : end of 'Date Procedure'
333      END SUB : end of 'Change_Data_Points'

334 PROCEDURE detect$(year, month, day)
335      ! EXCEPTIONS: Let "Date be in the standard 1-5
delimiter$ & " "
336      ! (26, "Invalid date string."
337      TRY year, month, day = 0
338      LET ds = trim$(ds)
339      SELECT CASE ds:IF 1 GOTO
340      CASE 0 : call explicit date/time code
341      WHEN error IN
342      IF year < 1 OR year > 10000 AND flag = 1
month is numeric
343      USE
344      LET flag = 1
345      CALL under_data_strings : add year number
346      END WHEN
347      IF flag = 0 THEN ! year is a string, so link
348      FOR i = 2 TO 1 : step through the order of
the strings
349      LET ds = under_data_strings + ds
350      END FOR

```

```

WITH error IN
351      IF year < 1 THEN LET year =
val$(trim$(ds(1:length))) : else let year = val$(trim$(ds))
352      GOTO
353      CALL parse_date_error
354      END SUB
355      END WHEN
356      LET ds = trim$(ds) : length = LEN(ds)
! keep old year
357      CASE "T"
358      WHEN error IN
359      IF ds < "00000000"
val$(trim$(ds(1:length))) : else let month = val$(trim$(ds))
360      USE
361      CALL under_data_strings
362      END SUB
363      END WHEN
364      LET ds = trim$(ds) : length = LEN(ds)
! keep old month
365      CASE " "
366      WITH error IN
367      IF ds < "00000000"
val$(trim$(ds(1:length))) : else let day = val$(trim$(ds))
368      USE
369      CALL parse_date_error
370      END SUB
371      IF ds < "00000000"
val$(ds) = trim$(trim$(trim$(trim$(ds))))
! keep old day
372      END SELECT : ! or CASE
under_data_strings(1)
373      CASE 1
374      ! if 1 is character used for the month
375      FOR i = 2 TO 4 : step through the order of
the strings

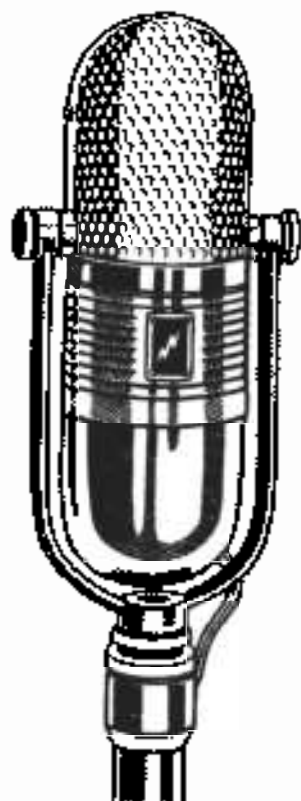
```

THIS IS NOT A COMPLETE LISTING

Complete source code and listings can
be found on the
AC's TECH disk.

Please write to:
T. Darrel Westbrook
c/o AC's TECH
P.O. Box 2140
Fall River, MA 02722

SOUND



by John Irvine

MOST OF US HAVE HEARD THE AMAZING sound capabilities of the Amiga computer. The ability to play digitized sound is one of the favorite features of the computer. To record your own sound you need an audio digitizer. The sound digitizer project described in this article allows the computer to sample sound. The sound sampler is compatible with most commercial software packages (QuaserSound, Audiomaster & others) as well as some PD software available on Fish disks (i.e. PerfectSound on Fred Fish #50).

The advantage of this project is that the electronics and components are kept to a bare bones minimum. This simplifies construction, lowers cost and improves the likelihood that you will actually build the project and that it will work successfully.

The heart of every digitizer is the ADC (Analog to Digital Converter) chip. This chip is responsible for reading an analog signal and outputting a binary number equivalent. In this case

the analog signal to be sampled (digitized) is the audio input from a standard microphone. The binary number outputted by the ADC chip is read by the Amiga computer via its parallel port and stored in memory.

The ADC chip in this project is capable of digitizing 50,000 samples per second with an 8 bit (0-255) resolution.

Sound Sampling

When recording, the ADC chip reads the voltage of the waveform at that particular instant and presents the binary number to the Amiga. The Amiga reads the number, stores it in memory, and signals the chip for the next sample. This continues for as long as sound is being recorded. The ADC chip follows and the computer records the basic shape of the original waveform.

During playback, the computer reads the binary numbers in sequence and outputs a proportional voltage via a sound channel. The output voltage varies in synchronization to the recorded signal, thereby playing back the digitized sound.

Cycle Time

Sampling speed of the digitizer is important. It determines the fidelity and maximum frequency of the analog signal that the computer can record. Fortunately for us this has all been worked out long ago, its call the Nyquist criterion. It simply states that to digitally record an analog signal accurately you must sample at twice the maximum frequency of the analog signal. If you fail to meet this criterion you can not be sure of the accuracy (fidelity) of the digitized sound.

Our ADC chip can sample at 50,000 samples per second which exceeds the sampling speed of the sound software to date.

DIGITIZER

If you have not tried digitized sound on the Amiga, use this hardware project to make your Amiga "listen up."

Typically to record voice or simple sounds (i.e. bang, bell or tone) slow digitizing speed may be employed. More complex sounds like music and higher fidelity require faster sound digitizing. Sampling speed is determined by the software.

Circuit Description

Look at the schematic illustrated in Figure 2. The circuit is easy to understand. The microphone input is fed into an 8-pin audio amplifier chip (LM386). The output from the audio amplifier IC is fed to the signal input on the ADC chip. The 8-bit number from the ADC connects to the Amiga 8-bit parallel (printer) port. The parallel port also supplies power to the audio digitizer circuit by lines 14 (-5V) and 22 (Ground).

Pins 2 through 9 on the parallel port are 8 bi-directional data lines. These pins are usually labeled DBD4-DB7 in computerese. The Amiga computer reads the 8-bit binary number outputted from the ADC chip using these pins. Pin 14 supplies the -5 volts needed to power the project. Pin 22 is the ground. Pin 1 is a strobe pin that connects to the ADC's CE (chip enable) and RD (ready) pins.

The project is simple enough to build and wire without using a custom made PC board.

Testing the Circuit

Testing the circuit depends upon which audio software you are using. Adjust the volume control until you have the appropriate recording level in your software.

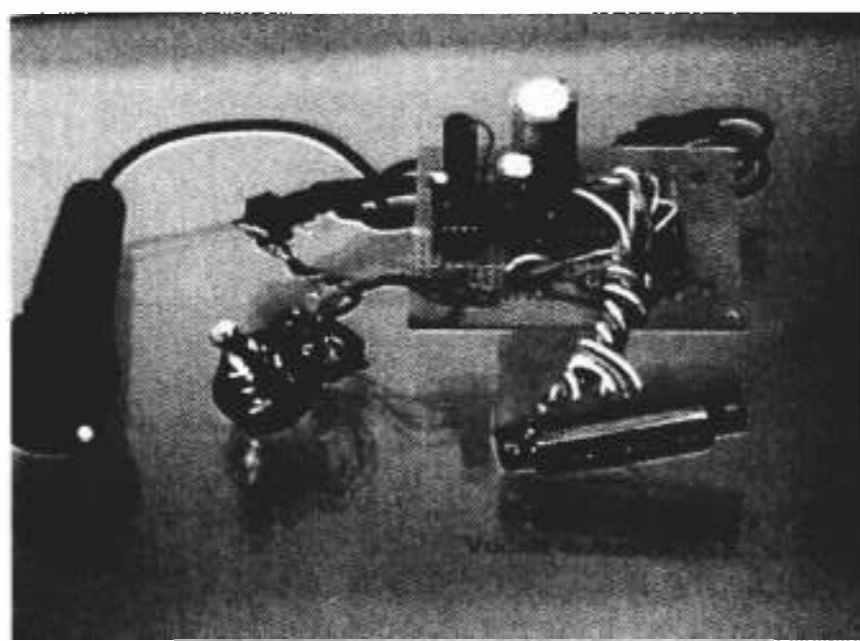
If the circuit doesn't work, check your wiring against the schematic.

Right: This "bare bones" project will allow you to produce sound files for other projects.

Voice Recognition

There is an interesting voice recognition program you can run using this digitizer. The magazine and accompanying program disk is available from PIM Publications, Inc. The magazine to order is AC's TECH Volume 2 Number 2. An updated version of the software is also available on the AC's TECH Volume 3 Number 4's accompanying disk.

Caution: All projects are supplied on an "as is" basis. Although the author has built and tested this project for this article, neither the author, PIM Publications, Inc., or its employees bear any responsibility for this project or its intended use.



Build Your Own SOUND DIGITIZER

Parts List

- U1 Maxim 165 ACPN Chip
- U2 LM-386 Audio Amp Chip
- Q1 PN2222 Transistor
- R1 100K ohm 1/4 watt
- R2,R4 4.7K ohm R3 16K
- R5 1K
- R6 10K Potentiometer
- R7 220 ohm C1 100 p²
- C2 4.7 uF
- C3 220 uF
- C4 10 uF
- C5 100 uF
- C6 1000 uF
- Misc:
 - 1/8" input jack
 - microphone
 - DB-25 Male connector
 - PC board
 - project case

U1 Maxim 165 ACPN @\$15.95 each are available from:
Images Company
POB 140742
Staten Island NY 10314
(718) 698 8305
add \$5.00 Postage & Handling NYS residents add
8.25% sales tax
All other parts and components are available from
your local Radio Shack.

Statement of Ownership, Management and Circulation

1A. Title of Publication: AC's TECH for the Commodore Amiga 1B. Publication No.: 1054229 3. Date of Filing: 10/1/93 4. Frequency of Issue: Quarterly 3A. No. of Issues Published Annually: 4 3B. Annual Subscription Price: \$44.95 US. 4. Complete Mailing Address of Known Office of Publication: P.O. Box 2140, Fall River, MA 02722-2140. 5. Complete Mailing Address of the Headquarters or General Business Office of the Publisher: P.O. Box 2140, Fall River, MA 02722-2140. 6. Full Names and Complete Mailing Address of Publisher, Editor and Managing Editor: Publisher: Joyce A. Huss, P.O. Box 2140, Fall River, MA 02722-2140; Editor: Donald D. Hicks, P.O. Box 2140 Fall River, MA 02722-2140. Managing Editor: Donald D. Hicks P.O. Box 2140 Fall River, MA 02722-2140. 7. Owner: PDM Publications, Inc., P.O. Box 2140 Fall River, MA 02722-2140; Joyce A. Hicks, P.O. Box 2140 Fall River, MA 02722-2140. 8. Known Bondholders, Mortgagees and Other Security Holders Owning or Holding 1 Percent or More of Total Amount of Bonds, Mortgages and Other Securities: None. 9. For Completion by Nonprofit Organizations Authorized to Mail at Special Rates: Not Applicable. 10. Extent and Nature of Circulation: (X) Average No. Copies Each Issue During Preceding 12 Months: (Y) Actual No. Copies of Single Issue Published Nearest to Filing Date: 10A. Total No. Copies: (X) 7,136 (Y) 6,382. 10B. Paid and/or Requested Circulation: 1. Sales Through Dealers and Carriers, Street Vendors and Counter Sales: (X) 2,783 (Y) 4,518 2. Mail Subscriptions: (X) 1,573 (Y) 242. 10C. Total Paid and/or Requested Circulation: (X) 5,756 (Y) 4,760. 10D. Free Distribution by Mail, Carrier or other Means: Samples, Complimentary, and other Free Copies: (X) 0 (Y) 0. 10E. Total Distribution: (X) 5,756 (Y) 4,760. 10F. Copies Not Distributed: 1. Office Use, Leftovers, Unaccounted, Spoiled after Printing: (X) 2,074 (Y) 1,632. 2. Return from News Agents: (X) 351 (Y) 130. Total: (X) 7,785 (Y) 6,382.

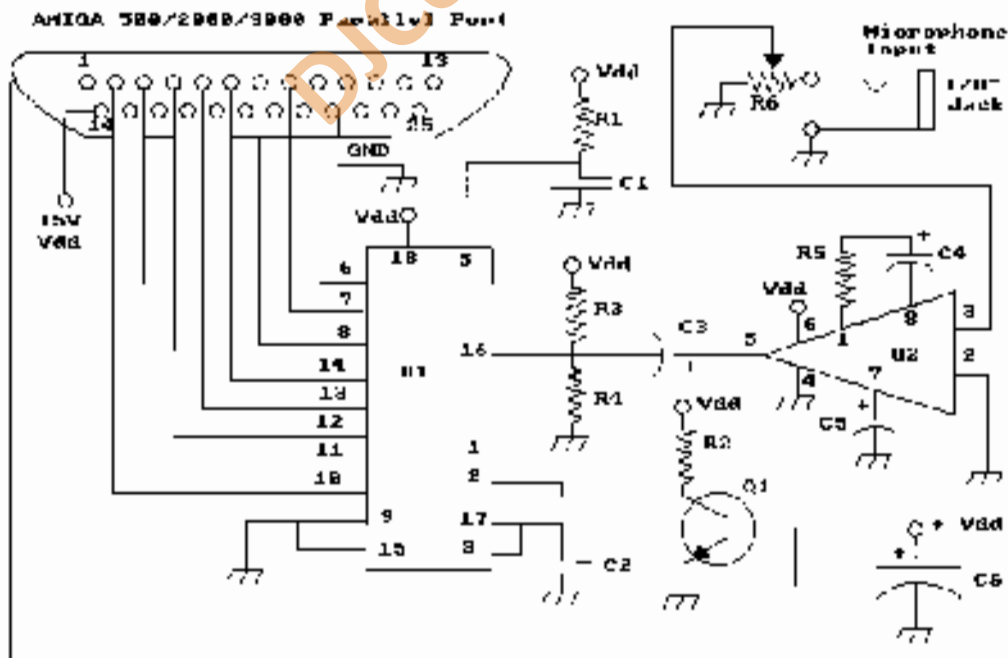


Figure 2

Technical Writers Hardware Technicians Programmers Amiga Enthusiasts

Do you work your Amiga to its limits? Do you create your own programs and utilities? Are you a master of any of the programming languages available for the Amiga? Do you often find yourself reworking a piece of hardware or software to your own specifications?

If you answered yes to any of those questions, then you belong writing for *AC's TECH*!

AC's TECH for the Commodore Amiga is the only Amiga-based technical magazine available! We are constantly looking for new authors and fresh ideas to complement the magazine as it grows in a rapidly expanding technical market.

Share your ideas, your knowledge, and your creations with the rest of the Amiga technical community—become an *AC's TECH* author.

For more information, call or write:

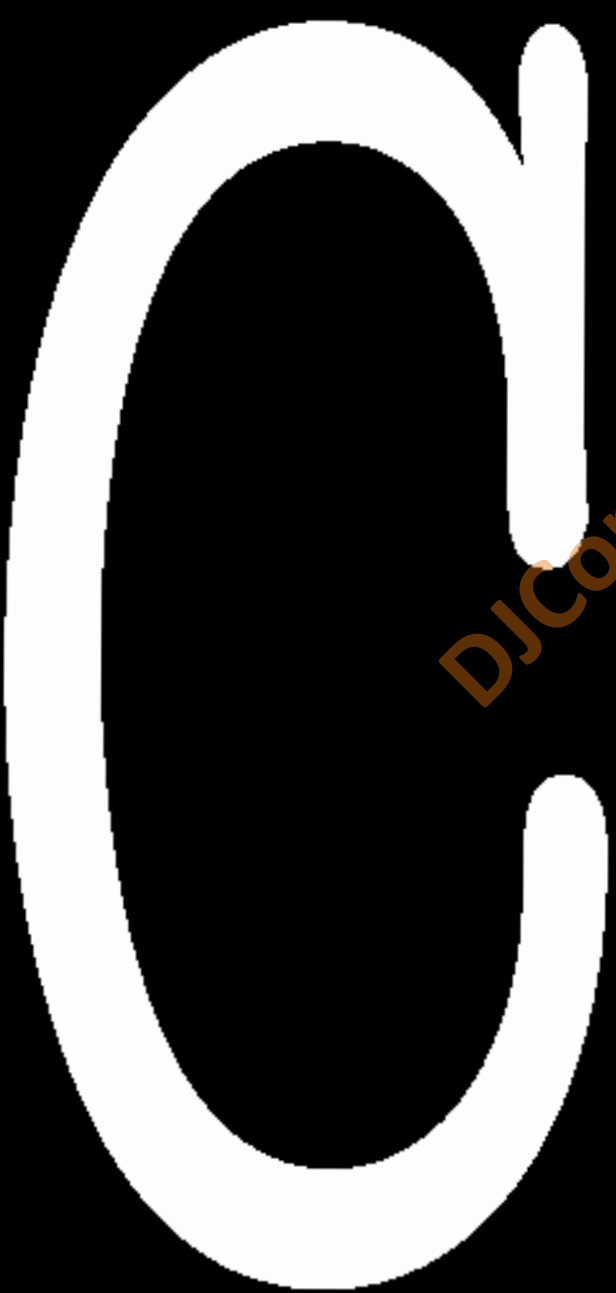
AC's TECH

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Fall River, MA 02722-2140

1-800-345-3360

A better way to



When most people think of C++, they think of the support it provides for Object-Oriented Programming (OOP). They forget that C++ is an extension of C and can, with some effort, be used instead of C. Advantages to a C programmer in using C++ include stronger type checking, more consistent treatment of user defined and built-in types, and some powerful extensions to C. The purpose of this article is to demonstrate how C++ can be used as a better version of C, and to show that C++ is useful in a C programming environment without the need to learn the OO paradigms that are supported by C++. I do not mean to imply by this that Object-Oriented Programming is in some way inferior, or even that the way that C++ implements OO concepts is incorrect. I just feel that at this time, with the lack of C++ tools in the Amiga community and the heavy emphasis on C, that this method is the most logical way to start using C++.

by Paul Gittings

A variety of options await the C programmer

I would even go so far as to recommend that all C programmers get a C++ compiler and start using it to compile their C code. In a short C++ has stronger type checking than C and this will require extra discipline on the part of the programmer, but she will be rewarded with wasting less time finding irritating bugs. C++ also has some simple extensions to standard C programming concepts. Hopefully I will convince readers that using C++ as a better C is a useful way to introduce oneself to C++. Also, I hope that I have generated these extensions that you will go on and explore the full power and benefits of all the features in C++.

C Compilers for the Amiga, with the exception of some of the public domain compilers, are ANSI C compatible. Since most C programmers tend to be more familiar with K&R C, I will explain new C++ features relative to K&R C. Programmers already familiar with ANSI C will have encountered some of the features discussed in this article. But be warned, there are subtle differences between the way ANSI C and C++ implement some of them.

The reference I used for K&R C is "The C Programming Language", first edition, by Brian W. Kernighan and Dennis Ritchie. For ANSI C I used the following three books: "The C Programming Language Guide", second edition, by Brian Kernighan and Dennis Ritchie; "The Waste Group's Essential Guide to ANSI C" by Nelson Barkakali; and "Standard C" by P. Plauger and Jim Brodie. During the writing of this article I used two ANSI C compilers to verify the operation of ANSI C, a registered version of Matt Dillon's DICE C compiler (version 2.0a.16, with the DCT pre-processor supplied with Coreau C++), and Markus Wild's port of version 2.3.3 of the Free Software Foundation's gcc compiler (see sidebar article "Swiss Army Knife Compiler") using the "-ansi" option (this option disables many extensions in the gcc compiler and results in a closer performance to the ANSI C standard).

The reference I used for C++ is "The Annotated C++ Reference Manual" by Margaret Ellis and Bjarne Stroustrup, May 1992 (it will refer to this book as ARM). Currently, use both Coreau C++ (with DICE as a back end, see sidebar article) and Markus Wild's port of version 2.3.3 of gcc. There are some areas places where gcc does not conform to the C++ language as defined in the above book; I will identify such discrepancies.

The first new feature of C++ (which is also supported by DICE) we will look at is very simple to understand and use. It is a new comment style. This is a comment to end of line: `//`. Anything that appears after the `//` up until the end of line is treated as a comment.

```
int main() { // rest of the code goes
// here -> #bug_fix; }
```

A simple feature, but one that I find most useful.

Arguably the most important extension of ANSI C over K&R C is function prototyping. A function prototype is used to specify the number and type of arguments required by a function. Function prototypes can be used in both function declarations and function definitions. Without the information supplied by a function prototype a compiler cannot make a decision on whether or not a function call has the correct number of arguments or if they are the correct type. No such capability exists in K&R C. So a K&R C compiler cannot know if a call to a function has the correct number or type of arguments. Consider the following example of a function declaration in K&R C:

```
int main() {
    int something(); // declare function
    something(1, 2, 3, 4); // call
}
```

The K&R compiler would not know how many arguments `something()` expects, so the compiler could make no decision as to whether the call specifies the correct number and type of arguments. In K&R C the only thing that function declarations can be used for is to specify that a function returns something other than an `int`. In the above example the declaration of the `something` function specified that the function returned a `long`. There is no way K&R C, by the use of function declarations, can inform the compiler of the correct type or number of arguments that a function is expecting. This changed in C++ with the addition of function prototyping and a watered down version was also later included in the ANSI C standard.

In C++ and ANSI C, a declaration can now be used to specify the number and type of arguments. Declarations of this type are used by the compiler to check that function calls have the required number of arguments and are of the correct type. A function declaration in C++ and ANSI C for the `something` function above might look like:

```
void something(int, int, int, int);
```

As you can see the declaration states the type of each of the arguments and a name for each argument is supplied. The argument names used in the declaration do not need to be identical to the names used in the actual function definition, only the types need to match. In fact the names can be left out of a function declaration:

```
void something(int, int, int, int);
```

For readability it is usually a good idea to leave the names in. In ANSI C and C++ the function prototyping format is also used in the function definitions themselves. For example, the `main` function is

A Better Way to C

usually defined as:

```
int result; int args; int i; int n;
char *p; int res; int n;
int main(int argc, char *argv[]) {
    ...
}
```

Undeclared functions in ANSI C are treated as they would be in K&R C, that is, the function is assumed to have a return type of int and an arbitrary number of arguments. C++ is stricter than this, and a function can be called only if it has already been declared or defined in the scope of the call. The following file would compile successfully under ANSI C and K&R C but would result in a compile-time error when compiled with a C++ compiler:

```
int function() {
    return result;
}
```

g++ is as strict as it should be and it will compile the above treating unknown() as a function which returns an int. It will, however, generate a warning, which states that unknown() is an undeclared function.

C++, unlike ANSI C, also requires that a function declaration must contain a function prototype. The sig. of the argument types must be specified in the function declaration. By making this mandatory, a C++ compiler is always assured of being able to check function calls for the correct number and type of arguments.

This is all well and good but suppose you want to write a function like printf() which uses a variable number of arguments.

In K&R C (and in ANSI C) to declare such a function is easy since the compiler requires an unknown number of arguments anyway. Since C++ now forces you to declare the number and type of each argument is how can you write a function with a variable number of arguments? Well, both C++ and ANSI C have a standard way of declaring a function with a variable number of arguments. Such definitions use ellipses, "...", to indicate zero or more additional variables of an unknown type. For example:

```
int printf(const char *format, ...);
```

Define a function with one or more arguments. Note there should be at least one argument specified before the ellipsis. The leading argument is required by a set of macros used to access the trailing arguments.

Accessing a variable number of arguments in the early days of C programming required machine-specific tricks which were nearly always non-portable between different machines. I once spent the better part of two days trying to figure out why a compiler, which worked on a 68020 based machine, would not work when recompiled on a Sun SPARCStation. The problem was due to the tricks used to access a variable number of arguments in a function. To get around this portability problem, ANSI C defines a set of macros that can be used to access a variable number of arguments. The macros are defined in the header file <stdarg.h>. The C++ Reference Manual also recommends that these macros be used when accessing a variable number of arguments from within a C++ function. For these macros to work

Using Comeau C++ 3.0 with DICE

COMEAU C++ 3.0 FOR THE AMIGA officially supports SAS/C version 5.10a and above as well as Marx Aztec C version 5.0d and above. The manual states that other C compilers should be able to work as back ends to Comeau C++. The manual also warns that Comeau Computing will not guarantee that Comeau C++ will work with any but the supported compilers. I took a bit of a gamble when I ordered Comeau C++ since I do not own one of the supported C compilers. I do however own a registered version of Matt Dillon's DICE C compiler (version 2.06.19).

I was actually very surprised at how easy it was to incorporate DICE into Comeau C++. I followed the standard procedure of installing Comeau C++ onto my hard drive. However, when the install script asked me which of the supported compilers I used, I respond no to each of the compilers listed. After the install script had finished, everything had been copied from the distribution disks to my hard drive except for the header files.

Part of the installation procedure is to create a set of C++ header files based on the C header files used by the C compiler on the system. Since the install script does not support DICE I had to create the C++ header files myself. I first created a directory into which the C++ header files would be stored, called dinclude (this directory was created in the same directory as the rest of the Comeau directories on my hard drive). Next I used the supplied utility c30/include to convert my DICE and Commodore header files.

This program takes two arguments; the first argument is the name of the directory in which you want to store the C++ files, the second is

where the C files can currently be found. On my system I used:

```
c30/include @include DICEHOME
```

This worked up to a point. On my system there is a symbolic link in the DINCLUDE directory to where I keep the Commodore AmigaDOS include files; apps/cc/2.0/include. The include utility seemed to have a problem with this symbolic link and terminated before converting all the files. To get around this problem I removed the symbolic link from the DINCLUDE directory and then repeated the conversion process in two steps:

```
c30/include @include DICEHOME; mkdir @include/amiga20; c30/
include @include/amiga20 apps/cc/2.0/include
```

This seems to have worked. However, as the include utility seems to always print out what appears to be an error when it finishes processing, I am not a hundred percent sure if everything is correct.

The next step was to copy the standard Comeau C++ headers from the first installation disk onto my hard drive. This was easily achieved with:

```
copy 20:/include/87.3 @include
```

As part of the installation the install script creates a file called forS, into which it puts various assigns; it is intended that this file should be added

A Better Way to C

however, there must be at least one fixed argument. Good examples of using `stdarg.h` can be found in the second edition of "The C Programming Language" pages 155-156 and the AKM pages 146-148. The use of these macros is the only guaranteed way to write portable code to access a variable number of arguments.

It's possible in C++ to declare a function with an unknown number of arguments and no leading argument:

```
int main() {
```

which states that `main` has any number of arguments including zero. Since there is no fixed argument, the `stdarg.h` macros cannot be used. Thus there is no guaranteed way to access the arguments to function `main`. This was included in C++ to provide an equivalent to `std::C`'s unstacked function `call`, and has the same portability problems. Don't use it!

In C++ and ANSI C you can also explicitly tell the compiler there are no arguments in a function by use of the `void` type. The following declares a function which has no arguments:

```
int main() {
```

In C++ the following also declares a function with no arguments:

```
int main() {
```

where as in ANSI C it would be interpreted as a declaration of a function with any number of arguments.

`void` is a new type in C++ and ANSI C. As well as its use in the above declaration, it can also be used to indicate that a function does not return anything:

```
extern void nonreturning(void),  
*void  
nonreturning(void);  
...  
return; }  
return; }
```

Also, in C++ and ANSI C a pointer to a void should be used as the generic pointer. This is a role that was fulfilled by `char*` in K&R C. For instance in K&R C the function `malloc` was declared to return `char*`. In C++ and ANSI C it is declared to return `void*`.

While both C++ and ANSI C support the `void` type there is however a difference in their treatment of void pointers. In ANSI C a pointer to a void can be assigned to a pointer of any other type without a cast:

```
... char *buff;  
buff = (char *) malloc (sizeof (char) * 10); return void*
```

In C++, however, this is an error; you have to explicitly cast the void pointer to the appropriate type:

```
... * buff = (char *) malloc (sizeof (char) * 10);
```

Again, `void*` differs to the "C++ Reference Manual" as it will accept such assignments without a cast; it does, however, produce a warning,

to the `scuser-startup` file. I had to change the assigns for `CC30` include: in this file to point to the `dinclude` directory:

```
assign CC30include: CC30comms/dinclude
```

Part of the installation process also installs a version of Matt Dillon's C pre-processor, `dcpp`, into the `c30` directory. I checked the version number of this copy of `dcpp` (`dcpp -v`) and since it was newer than the version I currently had installed on my system I moved it from `c30` to `DCC/bin`. I then had to change another assign in the file for `S`:

```
assign DCC: DCC/bin
```

At this point I decided to actually try out Comeau C++. I did not really expect anything to work since I thought I would still have to change the `ARExx` script, `ARExx30/como.rexx`, to work with `DICE`. First I executed for `S` to set up the assigns required by Comeau C++. Then I tried to compile one of the test programs supplied with Comeau C++, `rx` `ARExx30/como.rexx -V cctest.c`. I was a bit surprised by the result. While the compile did not work, the `como` script had identified the fact that I used `DICE` and had used the `DICE` compiler with what, at first glance, looked like the correct arguments. The compile failed because the `DICE` linker, `dlink`, could not find the link libraries specified by the `como` script. On my system the `DICE` standard link libraries are called `c.lib` and `amiga20.lib`. The `como` script, however, was using `cl.lib` and `amiga20.lib`. This was easily fixed by editing the `como.rexx` file and making the appropriate changes (I also changed the `ARExx/c.rexx` file but I'm not sure what this is used for). There are two spots in `como.rexx`

from which a call to `dlink` is made, and the library names in each of them had to be changed.

I copied the modified `como.rexx` script file to `REXX` where I keep all my `ARExx` scripts. I added the file for `S` to my systems `scuser-startup` file. Then I added the following alias to my systems `sshell-startup` file:

```
alias como c30REXX/como.rexx
```

I then rebooted my machine and Comeau C++ has worked fine on my system ever since (with the one caveat that I cannot use structure return types since the version of `DICE` that I use does not support them). I have not had to make any changes since I made the above few. I may however do a few modifications to the `como.rexx` file to get it to print out fewer messages and to hard code the fact I use `DICE` into it (it currently scans the system list of assigns to figure out which compiler is installed). Also I may change the `como.rexx` script to use the `+a1` flag as a default option rather than `+a0`; this causes the Comeau C++ compiler to output ANSI function declarations rather than K&R style declarations, `DICE` seems to work better with the ANSI declarations.

So you can see that configuring Comeau C++ to work with `DICE` is a fairly easy procedure. But I must again repeat that `DICE` is not supported by Comeau Computing as a back end to Comeau C++ and neither they, nor I, can guarantee that you won't have any problems. However, in my current use of Comeau C++ I have not encountered any problems with this combination.

—PG

A Better Way to C

message.

Since I have used malloc in the above examples I should point out that C++ has two new operators which replace malloc and its companion function free, called new and delete. new is used to allocate memory and delete is used to free it up again.

```
int *p;
int *p = new int(10); // allocate and initialize to 10
delete p; // deallocate array
```

In the above fragment note that the new operator accepts the name of the type that you are trying to allocate space for as an operand. You do not need to cast the result of the new operator as it returns a pointer of the correct type (i.e. pointer to the operand type). Unlike malloc you do not have to specify how big a space to allocate for simple types or structures. However, as with malloc, you should check that the allocation of space was successful by checking that the pointer returned is not equal to zero. Also, the space allocated by new is not guaranteed to be initialized, but this can be accomplished for simple types by using a slightly different syntax:

```
int *p;
p = new int(10); // allocate and initialize to 1
```

The allocation and deallocation of arrays also requires a different syntax:

```
char *buf; // declare pointer
char *buf = new char[10]; // allocate array of 10 bytes
delete [] buf; // deallocate array
```

Note that when deallocating an array you have to invoke the delete operator or this by specifying [] before the pointer name. In older C++ compilers you also had to put in the size of the array, but this is no longer required. You cannot use new to allocate an array, or structure, as is possible when allocating space for simple types.

There are a number of things to be aware of when using the delete operator. If the pointer you are deleting is not zero, it must be a pointer that was returned by new. The result of calling delete on a pointer not obtained from the new operator is undefined in C++ and the outcome will usually be harmful. Consider:

```
void buff() {
    char *buff;
    buff = new char[10]; // allocate array of 10 bytes
    delete buff; // deallocate array
}

int main() {
    buff();
    delete buff; // error: delete called on pointer returned by new
}
```

In addition the result of deleting an array without specifying the [] is undefined, as is deleting an individual item with the delete syntax. It is unlikely that a C++ compiler will always be able to detect the occurrence of all such errors. It is safe to assume that only damage will result from such operations and it is wise to do everything possible to avoid such situations.

It is possible to delete a pointer with the value zero, this is guaranteed to be harmless. Thus, deleting allocated space does not require checks to see if the memory being deleted was in fact successfully allocated by new. This can simplify error recovery code:

```
void guess() {
    char *p = new char[10];
}
```

GCC: The "Swiss-Army Knife" Compiler

In the world of Unix the GCC compiler is one of the best known compilers around. One reason for this is that it is excellent value for money. In the first place it is not one but three compilers; a C compiler (both K&R and ANSI standards are supported via command line options), a C++ compiler and an Objective-C compiler. It is also freely distributable. Who would produce such an item for free?

GCC is a product, if you can call it that, of the Free Software Foundation (FSF). The FSF is a collection of programmers who are trying to combat software hoarding (ie copyright) of large software houses by writing quality software and making it freely distributable. While freely distributable they are not in the Public Domain; they are instead covered by the GNU PUBLIC LICENSE which some people refer to as the "copyleft". As a recipient of a program covered by the "copyleft" you are free to change it, redistribute it, even sell it. You are however under certain obligations, these include:

- informing anybody receiving your program of their rights under the "copyleft"
- in the case of modification, make it clear that you have modified the program.
- make the source code of your program available to people who use it.

The GNU in the name of this license stands for "Gnu is Not Unix". The GNU project is one of the major projects of the FSF, the aim of which is to create a freely redistributable operating system which is compatible with Unix. Since you need a compiler to write an OS, one of the first programs to make an appearance out of the GNU project was the GNU C compiler, gcc. Each new release of gcc has seen it grow better and more powerful.

Version 2.0 included not only the C compiler but also incorporated g++ (which is the GNU C++ compiler) and an Objective-C compiler. Due to a mammoth piece of work, Markus Wild has ported several versions of GCC to the Amiga; the latest version I am aware of is version 2.3.3.

Markus not only ported the compiler (the core C compiler and the C++ and the Objective-C compilers) but also numerous support tools (assembler, linker, archive maintainer, libg++ etc). He also wrote a library to emulate many functions available in Unix libraries. As required by the copyleft, Markus included the source to all his changes in the form of diff files; they list the differences between the FSF release and Markus' version; another program called patch can be used to apply the diffs to the FSF files to produce the Amiga specific version. NOTE: neither diff or patch are supplied with Markus' distribution of GCC, however both are available on various Fish Disks.

To give you some idea of what you get in the GCC distribution here is a list of the major components:

- 1) GCC 2.3.3. This compiler will compile C (both ANSI and K&R), C++ and Objective-C (there is a problem with Objective-C however).

A Better Way to C

```

1  struct limit {
2      int p, m;
3      int n;
4      int r;
5  };
6  int main() {
7      struct limit l;
8      return 0;
9  }

```

Of course, wanting to delete the value of the pointer after a delete operation may or may not be changed. Don't assume that it is set to zero and never use a pointer after it is deleted.

The new and delete operators can of course be used to allocate and deallocate structures:

```

1  struct limit {
2      int p, m;
3      int n;
4      int r;
5  };
6  int main() {
7      struct limit *l;
8      l = new limit;
9      delete l;
10     return 0;
11 }

```

In the above, the call to new is made when initializing the pointer `limit_p`. Also, notice that `limit_p` was declared to be a pointer to `limit` and not a pointer to `struct limit` as it would in ANSIC. This is because C++ automatically creates a new type for any tagged structure. This does away with one of the common uses, in C, of the typedef statement.

C++ and ANSIC both allow structures to be passed as arguments to, or returned as a result from, a function (BUT, at least the version I know, does not support structure return types). In K&R C, this was not allowed and a pointer to a structure would have to be passed instead. Passing in the structures can be inefficient since, when a variable is passed to a function, the function effectively has its own private copy of the structure and this copying of large structures can incur a heavy price. An advantage of passing a structure, or any variable for that matter, rather than a pointer, is that any changes the function makes

to the structure it makes to its own private copy; the changes are not made to the structure in the calling program. This type of argument passing is called "pass by value" and is the only way the K&R and ANSIC C allow arguments to be passed to a function. This is why, in K&R and ANSIC, if a variable in a calling program is to be changed by a function call then a pointer to the variable has to be passed to the function. This places the onus on the person writing the function call to ensure that a pointer, rather than a variable, is passed. To place the responsibility for such decisions back where it should be, C++ introduces another method of argument passing, "pass by reference".

When an argument is passed by reference no local copy is made, in fact the local variable is a reference to (sometimes) the variable in the calling program. Changing the value of the local variable will change the value of the variable in the calling function.

To indicate that an argument is to be passed by reference the `&` operator is used in function definitions and definitions. The use of call by reference arguments removes the need for passing the address of a variable in function calls and explicit pointer dereferencing within the function. The following is a very simple example of a function which accepts one argument that is passed by reference:

```

1  #include <stdio.h>
2
3  void my_function(int *my_value) {
4      *my_value = 2;
5  }
6
7  int main() {
8      int my_value = 1;
9      my_function(&my_value);
10     printf("my_value = %d\n", my_value);
11     return 0;
12 }

```

- 2) gas. The GNU assembler.
 - 3) gld. The GNU linker, this links Unix style object files not Amiga object files.
 - 4) hunk2gcc. A program written by Markus Wild to convert Amiga link libraries (eg. `amiga.lib`) into a form that gld can handle.
 - 5) ar and ranlib. Programs to manage Unix style link libraries.
 - 6) libg++. The GNU C++ library, containing many useful classes and libraries including a streams library.
 - 7) ixemul.library. An Amiga shared library written by Markus which contains many of the standard Unix functions. There are also various link libraries included to allow access to this library.
 - 8) Unix style man pages are supplied for most programs and ixemul.library routines. A program called "man" is also supplied to read them.
 - 9) various header files (C and C++). Does not include Commodore Header files (which have to be obtained from Commodore).
 - 10) Various documentation in the form of info files, and infview, a program to browse this online information.
- There are however a number of things to be aware of with this release of gcc 2.3.3:

- 1) There are no Objective-C includes; therefore as far as I can tell there is no way to use it since all the Objective-C programs I have seen start with `#import <objc/Object.h>`
- 2) The only information supplied on g++ is a man page.
- 3) There is no documentation on the Objective-C compiler.

- 4) The object files produced by gcc/g++ are not the same as Amiga object files; ie, you can't use an Amiga linker to link them. Also the GCC linker gld does not understand the format of Amiga object files (or libraries). To help get around this problem Markus has included a utility called hunk2gcc, which will take an Amiga object file and convert it to a form which can be used with GCC's Unix style linker.

Due to the size of this distribution you are unlikely to see this compiler on a Fred Fish disk. There was some talk awhile back on the Internet about this compiler being included in a CD-ROM containing various non-commercial Amiga programs (PD, Freeware, Shareware etc), but I do not know if the CD-ROM was ever released. It is, however, freely available on the Internet; check the ftp site `amiga.physik.unizh.ch`. To install and run this compiler you will need: a hard drive with at least 8MB of disk space free, about 5MB of memory, and AmigaDOS 2.04 or later is recommended.

Markus has done a first rate job on porting GCC and related tools to the Amiga. If you need a low cost C or C++ compiler and you are willing to put up with the problems of the strange (to Amiga eyes anyway) format of the object files, Markus' port of GCC could just be what you need. —PG

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A Better Way to C

will produce the output:

```
my_val = 3
```

In general you should declare arguments to be pass-by-reference when you wish changes made to the variable in the function to be propagated back. On the other hand, when you don't want such changes propagated back you should use the standard C method of argument passing, pass-by-value.

As stated earlier, pass-by-value can be an inefficient way to pass large structures. If the function requires *read-only* access to the structure it might be better to define the argument as pass-by-reference and also specify, with the `const` type specifier, that it is not to be modified. `const` is new to C++ and ANSI C; it indicates to the compiler that a variable is to be treated as if it is read-only. Any attempt to modify a variable specified as `const` will generate a compile-time error. In the following C++ example, the routine `print_ptr()` demonstrates how to use a combination of `const` and pass-by-reference as a more efficient version of pass-by-value.

```
struct my_struct {
    int i;
    char *s;
};

void print_ptr(const my_struct &my_struct_ptr) {
    cout << "i = " << my_struct_ptr.i << endl;
    cout << "s = " << my_struct_ptr.s << endl;
}

int main() {
    my_struct my_struct_obj;
    my_struct_obj.i = 123;
    my_struct_obj.s = "my_struct_obj";
    print_ptr(my_struct_obj);
    return 0;
}
```

If an attempt were made in `print_ptr()` to modify the values of

range a compile-time error would occur indicating that an attempt had been made to modify a read-only value.

Another use of `const` is as a replacement of pre-processor macros used to define constant values. The following macro:

```
#define MAX_BUFFER_SIZE 1024
could be replaced by
const int MAX_BUFFER_SIZE = 1024;
```

A `const` without a type specifier is assumed to be an `int`, so the above could have been written as:

```
const int MAX_BUFFER_SIZE = 1024;
```

This use of `const` variables has a number of advantages over macros; they can be type checked by the compiler and the name of the variable will show up in a symbolic debugger and, of course, the usual accepting rules apply to such variables. In ANSI C however, such `const` variables cannot be used as the size of an array. For example, the following will not compile under ANSI C:

```
const int MAX_BUFFER_SIZE = 1024; char buffer[MAX_BUFFER_SIZE];
```

As far as ANSI C is concerned `MAX_BUFFER_SIZE` is still a variable. In C++, however, the above will compile correctly.

Another feature of C++ which is sometimes used instead of `enum` to construct enumerated types. An example of an enumerated type in C++ and ANSI C:

A Brief History of C & C++

C++ is first and foremost an extension to C. A C++ compiler will compile many C programs without any changes having to be made, and it will compile many more with just minor changes. The reason for this is that C++ has evolved from C and some thought was given to backwards compatibility during the design of the C++ language.

The C programming language in one form or another has been around since the late seventies. The C language was originally designed and implemented by Dennis Ritchie on a DEC PDP-11 at AT&T's Bell Laboratories. About 1978 the "standard" reference for this language was published; "The C programming Language", first edition, by Brian Kernighan and Dennis Ritchie. This version of the C language became known as "K&R" C, after the authors, and later in some quarters as "Classic" C (this name was probably inspired by a cola advertising campaign).

C was then implemented on a large number of machines under various operating systems. It was found that the original C standard was ambiguous in places and even incomplete in some areas (for instance it did not specify the C library). This resulted in many compiler implementors using differing interpretations of the standard. In addition, a number of new features were being added to some implementations. The result, a whole swarm of various C dialects with many

incompatibilities between them. Many of the new features been added had being developed in another AT&T language project.

In 1980 Bjarne Stroustrup added classes, function argument type checking and several other features to K&R C; the resulting language was called "C with Classes". This was a fore runner of C++. Stroustrup continued with the development of "C with Classes" until about 1983 when it was redesigned, extended, reimplemented and renamed as C++. C++, after a few refinements, became generally available in 1985. C++ is still evolving and being refined. While an ANSI (ANSI X3J16) and ISO (ISO WG21) committee have jointly been working on a C++ language standard since 1991 (ANSI has been working on a standard since 1989) a standard has not yet been finalized. The current pseudo standard for C++ is the book "The Annotated C++ Reference Manual" by Margaret Ellis and Bjarne Stroustrup; this book is usually referred to in most C++ literature as the ARM. This book is also the base document for the ANSI C++ standardization effort; chapter 19 lists the resolutions made by ANSI/ISO standardization committee so far. These resolutions aid compiler implementors in their implementation of various language features so that when the standard is finalized their implementations stand a better chance of conforming to that standard.

Currently when C++ compiler implementors say that their compiler conforms to version 3.0 of C++ they are usually referring to the C++ language as implemented by Release 3.0 of AT&T's C++ to C translator, `ccfront`, which in turn is based on the current content of the ARM. Comeau C++ 3.0 With Templates for the Amiga is a licensed port of the

A Better Way to C

```
enum days { Monday, Tuesday, Wednesday, Thursday,
           Friday, Saturday, Sunday };
```

The enumeration constants Monday-Sunday are assigned, by the compiler, integer values starting at 0. It is possible to determine their values for the enumeration constants and they do not have to be unique. The following is valid in both ANSI C and C++:

```
enum days { Monday, Tuesday, Wednesday, Thursday,
           Friday, Saturday, Sunday };
```

The enumeration constants can be used in much the same way as macro constants are usually used. You can, of course, declare variables of enumerated types.

A variable of type enum days can be declared in both ANSI C and C++ with

```
enum days a_days;
```

Just as with struct, C++ automatically creates a type when it encounters an enum. So the above declaration can be written in C++ (and this is the preferred way) as

```
days a_days;
```

The enumerated type can, as with struct types, be used in cast operations:

```
enum days a_days = (days) 1; /* C++ or ANSI C++ */
enum days a_days; /* C++ only
```

version 3.0 of front. On the other hand g++ is not a port of front and it is a bit difficult to figure out what version of front, if any, it does conform to. g++ does seem to have the features of front 3.0, but some of these features do not work as specified in the C++ Reference Manual. However, g++ improves with each release and it is free.

While as yet there is no standard for the C++ language, the C crowd now have an ANSI/ISO standard for the C language (which specifies a number of features that were originally found in C++), preprocessor and the C library. This version of C is usually called ANSI C or standard C. Compilers for the Amiga, with the exception of some of the public domain compilers, are all ANSI C compatible. It should be noted that some compiler implementors will add features to their compiler which are not in the ANSI standard. This is permissible but they should make it clear in their compiler documentation which features are not ANSI compatible. Many implementors also have a flag for their compiler which, when set, will produce an error during compilation if a non-ANSI feature is used; gcc for instance has -ansi flag, which will disallow non-ANSI features.

Having standards and compilers that conform to that standard enables programmers to write code that is portable to other machines. However, having a language standard does not mean that that language will not evolve in the future. Standard groups will continue to evaluate new features and, if it is found necessary, a new standard will be released, or maybe, as in the case of C++, the changes may be too radical and a new language may be spawned. —PG

It is not overexposed in ANSI C to create an enumerated type with the typedef statement and achieve similar results to C++. If days had been declared as follows, the enum could also be dropped in ANSI C variable declarations and casts:

```
typedef enum { Monday, Tuesday, Wednesday, Thursday,
             Friday, Saturday, Sunday } days;
```

The treatment of enumerated types differs somewhat between C++ and ANSI C. As stated earlier, when a compiler of either type encounters a definition of an enum type it assigns an integer value to each enumeration constant (Monday through Sunday above), starting at the left with 0. Since any enumerated type is a sub-type of int it is possible to assign an enum value to an integer variable. So in ANSI C and C++ the following is legal, since Monday will be promoted to the int value of 0:

```
int i = Monday;
```

However, ANSI C and C++ will treat the following differently:

```
int i = 0;
```

This is valid in ANSI C but not in C++. The above will generate a "type mismatch" error in C++ (however gcc seems to treat such a statement identically to ANSI C). In C++ a distinct integer type is created for each enumeration type; variables of one type cannot be assigned values directly from another type; variables of type days can only be assigned values of type days, i.e. Monday through Sunday, or from other variables of type days. This is another example of C++'s stricter type checking over ANSI C. To cope with such an assignment, if you really need to, you would have to cast the value to the appropriate type.

C++ even has an alternative to the standard cast operator called explicit type conversion. This new operator looks like a function call and takes the form:

```
explicit type (value to be converted);
```

In the following example a float value is cast to an int value:

```
int i = (int) 3.14; /* cast float constant to an int
```

Explicit type conversion also works for simple types you create. It is to assign an integer value to a variable of our enumerated type days any of the following could be used:

```
enum days a_days = (int) days; /* C++ or ANSI C or C++ */
enum days a_days = (days) 1; /* C++ only
```

Since struct ones are not considered simple types, explicit type conversion in C++ will not work with structures. Thus the following line will produce an error:

```
enum days a_days = (days) {1,1};
```

In fact that'll produce a rather cryptic error message:

```
***error: too many arguments
```

A Better Way to C

Explanation of this error message requires that I slow up to a little while like I do above. Explicit type conversion for structures can in fact be made to work in C++. This requires the use of a new and powerful feature in C++ called a class, which can be thought of an extension of a struct; actually in C++ a struct is just another name for class. In a class you can define functions, called member functions, as well as data fields. If limits had been declared with an appropriate member function, called a constructor, the above type conversion would have worked. The lack of such a function cause the above error message. An explanation of classes and constructors is beyond the scope of this article, but if there is enough interest an explanation of classes may form part of a future article.

C++ has yet another feature which can also be used as a replacement for some macros, the inline function specifier. This indicates to the compiler that a function so specified be considered for inlining; that is, when a call to the function is encountered, rather than generating code to actually perform the call the compiler will insert a slightly modified version of the function in place of the call. The compiler may, however, choose not to perform the inlining due to the outcome of some built-in heuristics. Also, most C++ compilers have an option to turn inlining off (don't Comment C++); this option is useful when you want to debug a program. When using inlining, suitable candidates for inlining are small functions of a few lines. The benefit is a speed, inlined functions are executed faster and in some cases even memory is saved.

As you have probably guessed, inlined functions can be used for each of macros. Consider:

```
printf("Age: %d\n", (int) * age);
```

which can be replaced with the inline function:

```
inline int age(int * age) { return * age; }
```

Inline functions have a number of advantages over macros. First, like functions, they use the standard function syntax and, since the types of the returned value and arguments are specified, the compiler can type check calls to the function.

A major addition to C++ functions is that function names can be overloaded. This means that more than one function can have the same name as long as they can be distinguished by argument types. Consider the following:

```
int add(int a, int b) { return a + b; }
float add(float a, float b) { return a + b; }
int add(int a, int b, int c) { return a + b + c; }
float add(float a, float b, float c) { return a + b + c; }
```

The above C++ code defines two different functions called add. In total, one of which accepts an int value, the other a float. As long as the compiler can distinguish between all instances of the function by the number and type of their arguments any number of definitions can be given. You could, if you were perverse, have all your functions called gl. Needless to say, such an occurrence is not what this feature was designed for. An example of a better use would be in a sort library; rather than have functions called such things as sortInt, sortInt, sortFloat, etc, you could have all the functions called sort. The compiler would be able to identify which routine should be called by the type of argument given in a function call.

The more technically inclined readers may wonder how a C++ compiler keeps track of the different versions of the function and passes this information to the linker; especially across compilation units. C++ encodes all function names. This encoding, depending on the function name and the type of each of its arguments, is referred to as name mangling. In this way a unique identifier is generated by the compiler for each of the overloaded functions. These encodings also allow for type-safe linkage across compilation units. Since the function names that the linker will see actually includes information on the function arguments, it guarantees that function calls will only be linked to a function if the arguments in the final call and the function are of the same type (ie, they have the same name). You can actually see these encodings in assembly output from a C++ compiler or via a symbolic debugger. Currently there is no debugger available for the Amiga which is C++ aware, hence as we know knowledge of the encoding scheme will be required so that you will be able to code the encoded function names debugged by the current symbolic debuggers. A full description of the encoding scheme is beyond the scope of this article, however to get a feel for this encoding system, here is a simple example. The following function declaration:

```
void main(int argc, char * argv[]) { ... }
```

would be encoded as:

```
main@arg@int@
```

The encoding is made up of two parts, the function name and the function signature (encoding of arguments). The two parts are separated by "@" (two underlined), and it is recommended that you do not use "@" in your own function names. In our example the first character in the function signature is "T"; this indicates that the function is global (or has file scope). This is then followed by four lower case characters, one for each argument; "i" for an int, "c" for char, "c" for char and an "e" for the ellipsis. Things get a bit more complicated with user defined types. Comeau C++ comes with a utility called `conv2c` which will read in mangled names from standard input until EOF, and then it will output the mangled names together with the demangled equivalents (see the 2.1B files file on disk one of the Comeau C++ distribution for more information on `conv2c`). For a more detailed description of function name encoding see the following ACM page 122-127. The Comeau C++ User's manual pages 16-17.

Note this function name encoding while necessary for C++ functions will cause problems if you are trying to call C functions from your C++ program. To be able to call a C function to C++ you have to tell the compiler that the function is a C function so that the compiler will know not to mangle the name. You do this by use of a linkage specifier in an extern declaration:

```
extern "C" int somefunction(); // declares a C function
```

The "C" tells the compiler that `somefunction` is a C not a C++ function. Note to do this for all AmigaDOS functions would be a bit laborious to say the least. There is an easier way; an `extern` statement can be applied to an include file to indicate that it contains C function definitions:

```
#include "somefile.h" // include a C prototype file
extern "C" { // Use C++ linker
```

A Better Way to C

You can even avoid this with Compaq C++ as it comes with a utility, `clib/include`, which will make C++ versions of all C include files. Basically it creates a C++ header file of the same name as the C version but which contains an extern "C" statement which then includes the C version of the header file. For example the C++ version of `exec/types.h` on my system contains:

```
#ifndef __C__
#include "exec/2.0/include/exec/types.h"
#endif
```

If you want to create header files to use in C and C++ programs you can make use of the `extern "C" const __cplusplus`.

```
#ifndef __cplusplus
extern "C" {
/* C function declarations */
}
#endif
```

Another common problem encountered when using C++ in a C environment is that C++ requires that a function be declared before it can be used. If C++ encounters a function call prior to a definition or declaration of that function, it will report an error. You must ensure that you include the appropriate header files containing function declarations for all functions that you call. The "Native Developers Kit" available from Compaq (Part Number: NAJDEV22), contains header files which have declarations or prototypes for all A-riga Libraries. These can be found in the `include/dlib` directory. These header files are not C++ ready and you will have to use an extern "C" wrapper when including them in your C++ program.

In C++ as well as overloading your function names you can also have several declarations of your functions which specify default values for some or all of the arguments. These default values are substituted for missing trailing arguments. For instance the following declaration is for a function with two default values:

```
void moveTo( int x = 1, int y = 1);
```

The following are all valid calls to this function.

```
moveTo( 1, 2, 3); // moves to x = 1, y = 3
moveTo( 1, 2); // moves to x = 1, y = 1
moveTo( 1); // moves to x = 1, y = 1
```

It is only possible to define default values for leading declarations. The following is not a valid function declaration:

```
void moveTo( int x = 1, int y);
void moveTo( int x, int y = 1);
```

is legal.

It is also only possible to call a function with trailing arguments missing. The following which you might think would be equivalent to `moveTo(1)` is illegal.

```
moveTo( 1); // illegal in C++
```

In general I think that default values should be avoided. I always believe that when programming you should be as specific as possible and the idea that you can leave out arguments to a function just because the compiler will fill them in with default values goes a bit against the grain. However, one use for default values that I would endorse would be their use to support backwards compatibility in new versions of library routines. Suppose you had a library function called `plotWindow` which accepted four arguments, `x`, `y`, `width` and `height`:

```
void plotWindow( int x, int y, int width, int height);
```

which had been around for a long time and is used in a lot of code. You now decide you need to add some extra functionality to the function which requires an extra argument. You have a number of options: you could create a new function called `newPlotWindow`, you could go around all your code and modify all calls to the function or you could use default arguments in the new version of the function and its declarations:

```
void plotWindow( int x, int y, int width, int height,
int defaultColor);
```

Old code which calls `plotWindow` with only four arguments when recompiled with the above declaration will pick up a default value of 0 for the fifth argument `defaultColor`. This assumes that a value of 0 for `defaultColor` will produce the old behaviour of `plotWindow`.

Default value function declarations can be combined with scoping rules to allow the behaviour of function calls to be changed somewhat in different scopes:

```
void plotWindow( int x, int y, int width,
void setDefaultColor( int defaultColor);
void plotWindow( int x, int y, int width,
int defaultColor);
```

will generate warning messages on the second call to `plotWindow`.

While using default values it is possible to change the way functions are called within different scopes, you cannot have functions defined within functions, as you can in such languages such as Pascal. C++ like C is not really a block based language in the same manner as Pascal. However, both C++ and ANSI C have had, if you like, their blockiness extended at least with regards to variables with the introduction of new scope rules for variables.

In ANSI C the scope of variables could be local to a function, local to a file (compilation unit) or to the whole program. It is now possible in both C++ and ANSI C to define variables which are local to a block. A block being three statements contained within curly brackets (a block is also, more formally, called a compound statement).

In ANSI C the declarations of any variables in a block must appear before any non-declaration statements. C++ extends this so that a variable can be declared anywhere within a block prior to its first use (the C/C++ compiler also supports this feature even though it is not in the ANSI C standard). This feature was added to allow variables to be declared when a initial value for the variable became available. Blocks can of course be nested, here is a C++ example of some nested blocks with each block having its own declaration of the variable `i`. (GCC will also compile this example):

```
void main(void) {
    int i;
    // declare block 1
    // start another block
    print(" Starting Block 2\n");
    {
        int j = 10; // declare second i
        // start another block
        // start block 3
        // i is declared in "for" statement
        for (int k = 1; k < 10; k++) {
            print(" Starting Block 3\n");
            print(" i = %d\n", i);
            print(" j = %d\n", j);
            print(" k = %d\n", k);
        } // end block 3
        print(" Starting Block 1\n");
        return;
    }
}
```

A Better Way to C

If this function was called it would produce the following as output:

```
Entering Block 1          Entering Block 2          Entering Block 3
int                     int                     int
1                       1000                    1000
                        Exiting Block 1          Exiting Block
```

Note that changing the value of `i` in a block does not effect the value of `i` in any other block. Just like changing a variable local to a function does not change the value of a global variable with the same name. In the above code also notice that the third `i` is initialized in the for statement itself.

If you declare variables in blocks as described above, be careful when modifying code. Removing a declaration of a variable within a block, but forgetting to remove a reference to that variable may not necessarily generate a compiler error if the variable name is also defined in an outer block. Strange errors can result.

A potential problem would occur in C programs compiled with a C++ compiler results from C++'s automatic creation of a type for a tagged struct. In C++ it is possible for a structure defined in an inner scope to conceal a variable of the same name as the struct over an outer scope. Consider the following (which is based on the example on page 461 of the ARM).

```
#include <stdio.h>
int main()
{
    int main_size, char_size = 1;
    printf("the size is %d", sizeof(char_size));
}
```

If the above is compiled by a C++ compiler the resulting program will print out "the size is 4". If it were compiled with an ANSI C compiler it will output "the size is 386". In the ANSI C case the `sizeof` refers to the array. If you wanted to refer to the struct's size, it would have to be changed to `sizeof(struct)`. In C++, however, because a new type is created when the struct is defined it takes the array. If the `sizeof` was meant to reference the array then it could be rewritten as `sizeof(arr)`. What may you ask does this do?

In K&R and ANSI C, a function had a local variable with the same name as a global variable the function would not be able to access the global variable directly. Put another way, you usually do not give your local variables the same names as global variables if you need to access the global variables. With C++ has a remedy for that. A new operator was introduced in C++ which is called the scope resolution operator. This allows a function to access variables of file scope (global) even if that function has a local variable of the same name. For example

```
int set_err(int &error){          return int &error;
int main(){ declare global variable
            void &error(void) {          int error = 1; //
declare local variable
            int error = &error();      0;          error =
set_err();
            if(error == 1)              error = error;
return error;
}
```

The above function will, if it gets a non-zero return value from either of the two functions it calls, set the global variable `error` to the returned error value plus an offset value. As a matter of style some C++ programmers always use the scope resolution operator when referencing a global variable. This aids people reading the code in letting them that a global variable is being accessed.

As stated above, the scope resolution operator can only be used to access file scope variables; that is, global variables. In the nested blocks example discussed earlier you could use use this operator from an inner

block to access the variable in an outer block.

The final C++ feature that we will look at in this article is anonymous unions. In C++, like K&R and ANSI C, each union does not have to have a name. The fields of such an unnamed or anonymous union may be unique from the names of variables or the names of the fields in other anonymous unions within its scope. An example of a definition of an anonymous union:

```
union {
    struct {int a; int b;};
};
```

`packint` and `packbytes` can be referenced just like ordinary non-constant variables eg:

```
packint = 2;
```

In K&R and ANSI C you would have had to use

```
int a; int b; int b; int b;
typedef struct { int a; int b; };
```

and accessed the union members via `pack` eg:

```
pack.bytes = 2;
```

If you define a global anonymous union it must be declared as static; that is, a global anonymous union cannot be accessed "outside" its compilation units. Failure to declare a global anonymous union as static will result in a compile time error. g++ does complain if a global anonymous union is not declared static, however it crashes any machine while compiling a trivial example containing a global static anonymous union.

Due to the addition of new features to C++ over ANSI and K&R C a number of new reserved keywords were introduced. These keywords cannot be used as variable names, type names etc. Here is a list of the new keywords:

```
new delete static inline namespace
private protected public volatile
constexpr
```

These may cause problems when including C header files in your C++ program as it is possible that these keywords could have been used as C argument names, type names or function names. If you do come across such instances then they will have to be changed.

The stronger type checking present in C++ is at times a two edged sword. On the one hand it brings your attention to possible and real errors (and the potential for error). While on the other hand it can seem to be a nuisance, having the compiler always complaining about assignments etc which seem perfectly valid. I personally prefer a stronger type checked language. Anything that can help me eliminate errors early is well worth the inconvenience of some extra typing. As well as stronger type checking C++ is also stricter about the use of user defined and built in types than C. This has resulted in a couple of differences in implementation with searching on the

1) Character constants have a size of `char` in C++ (`sizeof('a')` will equal 1) the size of `char` in C (`sizeof('a')` will equal `sizeof(char)`). Note in general here we have suggested by compiler vendor C and C++ treatment of char, except for the above case. 2) Enumerations are declared `enum` in C++.

A Better Way to C

and C++. In our example of main days, in C size of Monday is equal to size of int, in C++ this is not true since we can write any integer of equal size(int).

I also mention all the C++ features that I wish to cover in this article. I hope you agree that they supply some useful and well needed extensions to C. Now there is a lot more to C++ than I have covered in this article. Leave only diseases. The features which could be thought of as simple enhancements to C. In Wiener and Pisoni's books they refer to these features as "How C++ Enhances C in Small Ways". Well there are any number of larger ways in which C++ enhances C but they are left for you to discover or for possible future articles.

I have included a bibliography which consists of the various books I referenced during the writing of this article, which cover C and C++. If you are interested in adding a couple of books on C++ to your library I highly recommend the ARM and Ciollietti's book "Advanced C++". Also, while this article does not cover Object Oriented Programming, anybody who seriously wants to use C++ will require knowledge of OOP concepts. To this end I have included a reference to Timothy Budd's excellent book "An Introduction to Object-Oriented Programming".

ANNOTATED BIBLIOGRAPHY

K&R C

"The C Programming Language" by Brian W. Kernighan and Dennis M. Ritchie, first edition, 1978, Prentice-Hall ISBN 0-13-1-0161-1 The classic book on C programming. Deserves to be one of the best selling computer books around. Divided into two sections; a tutorial section and a language reference section.

ANSI C

"The C Programming Language" by Brian W. Kernighan and Dennis M. Ritchie, second edition, 1988, Prentice Hall ISBN 0-13-1-0623-1 This is a rewrite of their original book to cover the new ANSI version of C.

"The White Group's Annotated Guide to ANSI C" by Nabiyouni Barkakati, 1988, Howard W. Sams & Company, ISBN 0-672-22673-1 A great little book. This is a quick reference guide to ANSI C and the standard library. Well organized and written.

"Standard C" by P.H. Plauger and Jim Riddle, 1989, Microsoft Press ISBN 0-441-51593-6 Another quick reference guide. I don't like this as much as the "Annotated Guide", mainly for style reasons. However, it does have detailed descriptions of each of the header files in the standard library and a useful table indicating what header files include to pick up definitions of specific types and functions.

C++

"The Annotated C++ Reference Manual" by Margaret A. Ellis and Bjarne Stroustrup, May 1992, Addison-Wesley ISBN 0-201-14966-1 I have to emphasize that this book is a reference manual, not a tutorial. However, as reference books go this one is not among the best. The supplier "commentary" is a good read in itself and explains why certain features are implemented the way they are and, more usefully, what pitfalls to watch out for. This is not the sort of book you are likely to read from start to finish and if you intend to do lots of C++ programming it

will prove invaluable. This book is the ANSI base document for the ANSI standardization of the C++ language. In various C++ literature this book is referred to as the ARM.

"Advanced C++ Programming Techniques and Idioms" by James Coplien, 1992, Addison-Wesley ISBN 0-201-42993-0 If you have the books of C++ under your belt this is the book to get. People with little formal knowledge in computer programming may find the discussion in some parts a bit of a tough slog, but this is a book where the more effort expended for greater the rewards. It includes an appendix on interfacing C and C++ code which to some extent inspired this article. For people interested in moving to object oriented programming for chapters on Object-Oriented Programming and Object Oriented Design are well worth reading. Anybody really serious about programming in C++ should own this book.

"An Introduction to Object-Oriented Programming and C++" by Richard Wiener and Lewis Pisoni, 1988, Addison-Wesley, ISBN 0-201-15413-7 This book differs, in my opinion, from a normally out and out choice of textbooks. It also is based on an older version of C++. However, it is written in fairly plain language and lots of examples and diagrams are used to explain some concepts. Also, unlike some of the C++ books, this book does explain some of the terminology and goals of Object Oriented programming before starting into the language itself.

"C++: A Guide for C Programmers" by Bharan, Hestiarputra, 1992, Prentice Hall, ISBN 0-13-1-23467-1 This book has many examples, the last four chapters are in fact case studies. The solutions to exercises are included. The examples were written in g++ if I remember, as the title suggests, that you have knowledge of C. One thing I didn't like was that it just did not get on to the C++ language, no attempt was made to try to explain the goals of object oriented programming and no real outline of C++ and its features was given. Again, this book is based on an older version of the C++ language (and the examples are based on an older g++ compiler) and some of the newer features (such as templates) are not mentioned. However, there is a new version of the book which comes with disk (PC) containing the source to all the examples. I do not know if this version is based on a newer C++ language definition.

OOP

"An Introduction to Object-Oriented Programming" by Timothy Budd, 1991, Addison-Wesley, ISBN 0-201-51704-0 An excellent book on OOP. Starts off with general concepts and then goes on to show how these concepts are supported in four languages: C++, Objective C, Object Pascal and Smalltalk. Describes the advantages and disadvantages of each language. Gives clear examples and case studies. Unfortunately the book was written before templates were introduced to C++, so only cursory mention of events made. Well worth getting if you want to understand what OOP is all about.

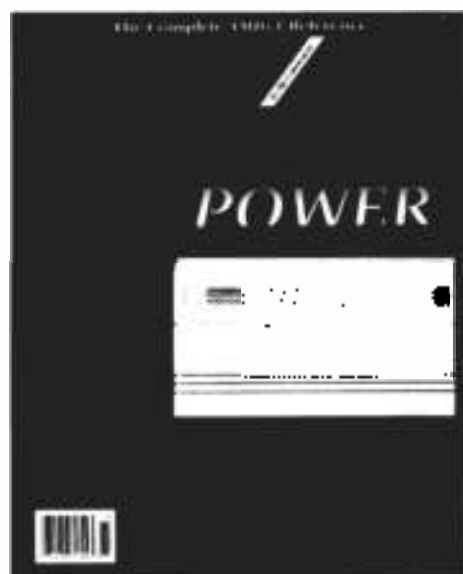
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HUGGE NUMBERS

By MICHAEL GREBLING

Introduction

Last article I covered the basic arithmetic operations of addition, subtraction, multiplication, and division and described a practical application of ExNumbers in a CLI-based calculator.

This article extends the ExNumber library functions by introducing an ExInteger module which performs logical, bit, and shift operations (e.g., AND, BSET, SHR, etc.) on ExNumbers and can also convert an ExNumber to/from various based representations (e.g., hexadecimal, binary, octal strings). I also add an ExMathLib0 module which provides an ExNumber interface to the Amiga's built-in libEE 64-bit math library. Finally, all these new functions are integrated into the CLI-based calculator from last time to vastly improve its functionality.

ExIntegers

The most obvious extension for the ExNumbers is a way of performing logical operations on them. Doing so requires that we restrict the vast dynamic range (i.e., $-9.9E11000$ to $9.9E11000$) of the ExNumbers into a more manageable range that can be exactly represented within the 172 digits or so of ExNumbers. As well, to give easily discernable ExInteger limits when performing based arithmetic, a further constraint is imposed so that ExIntegers are within the range (2^{172}) to 2^{172} or $-5.98E51$ to $5.98E51$. ExIntegers can thus exactly represent any 172-bit integer.

The simplest implementation of ExIntegers to support logical operations in Modula-2 is a mathematical set implementation. (Table 1 shows the relationship between set operations and logical operations.) ExIntegers are built up using an array of the 16-bit set data type (BI16E1). Figure 1 illustrates the structure of the ExInteger data type.

ExInteger Conversions

To give us logical operations on ExNumbers several conversion routines are defined which translate ExNumbers into ExIntegers and vice versa. These conversions are hidden from the user of the ExInteger functions (Listing 1) so that the parameters which are passed in and out of the procedures are always seen as ExNumbers. Thus, the ExInteger package interface is simplified so users don't have to perform explicit conversions every time they wish to perform a logical operation on ExNumbers. We see later that this calling convention simplifies the interface to the Calculator as well.

The ExNumberToExInt procedure near the end of Listing 1, converts ExNumbers to ExIntegers. This algorithm first constrains the ExNumber to the valid ExInteger range (i.e., -2^{172} to 2^{172}). Next, a loop generates ExInteger set elements by taking the modulo 2^{16} remainder of the ExNumber to effectively strip out a 16-bit chunk of the ExNumber, and then type-casts this number into a 16-bit set (LONGBI16E1), stored in the ExInteger. After each loop iteration, the ExNumber is divided by 2^{16} and truncated to an integer to give access to the next 16-bit chunk. The loop terminates when all the ExNumber Quads are zero.

The reverse operation of converting ExIntegers to ExNumbers is performed by the ExIntToExNumber procedure. A similar loop scans through the ExInteger chunks, in reverse order (i.e., from highest to lowest), converts each set into a 16-bit unsigned number, multiplies an accumulated total by 2^{16} , and adds the converted number to the total. The conversion is complete as soon as each ExInteger set has been addressed.

PART II

Logical Operations

The ExInteger module performs the standard logical operations of AND, OR, XOR, NOT on a bit's complement, bit setting, bit clearing, bit toggling, logical shifts, arithmetic shifts, and rotations. These functions are grouped according to the algorithm which implements each operation. For example, the AND, OR, XOR, and NOT functions all call the LOP procedure to perform the detailed logical processing of the ExInteger. For this reason, I will describe the central procedure for each grouping (i.e., LOP in this case) with the understanding that the other procedures which also use this algorithm have similar properties.

The ExAnd procedure serves as the representative of the first grouping which calls the LOP procedure, by passing in a customization function (the And function) which returns the intersection (equivalent to logical AND) of two BITSET arguments. The LOP procedure first translates the two operands to ExIntegers; then the passed function is used, on a 16-bit chunk basis, to logically AND (in this case) together both ExInteger arguments. The result is converted back to an ExNumber and is returned to the ExAnd procedure.

The second class of operations uses the LBI procedure to perform single-bit manipulations such as setting, clearing, and toggling bits. The ExSetBit procedure is used as an example to illustrate the general bit algorithm. As before, the ExNumber is converted to an ExInteger. LBI then causes use of the power procedure 'mini' from the ExMathLib0 module (described below) which implements the raising of the ExNumber, x, to the jth integral power, where j is an integer. The stoi routine is used here to produce a single-bit mask (base 2 on the principle bit 2^j) to be ANDed with an integer. In this case, the bit mask is ORed with the ExInteger, using the passed 'Oper' function in a call to LOP. Consequently, the ExNumber returned by this procedure, after conversion from an ExInteger, has its nth bit set.

Shifting operations are more awkward in an ExInteger format so they are implemented as multiplications and divisions by powers of two on ExNumbers. There are three different flavors of shifting algorithms: signed or arithmetic shifts, unsigned or logical shifts, and rotations. Figure 2 shows how these shifting operations differ.

The simplest shifting operation is the logical shift as implemented by the LShift algorithm (Listing 1). The ExNumber is first constrained to a valid ExInteger range. Next, if the bit shift quantity is greater than MaxBase2Bits (172), a zero is returned and the algorithm is aborted, since the number has been shifted out of the ExInteger number range; otherwise, a shift mask is calculated using stoi, and, for the ExSh procedure, is multiplied times the number to be shifted. This shifting operation is characterized by the equation $Result = n * 2^m$, where n represents the number to be shifted and m represents the number of bit positions to be shifted.

The rotation operations, implemented by the LRotate procedure, are slightly more complicated because the bit which is rotated out of the ExInteger range must be wrapped around and shifted back into the ExNumber. To help sense the state of a given bit in an ExNumber, the IsBitSet function was created. It returns a mask for a selected bit, ANDs this mask with a number, and then returns true if the bit was set. In ExROR, LRotate calls this function to extract the least significant bit before shifting the number. After the shift, if the detected bit was set, the most significant bit of the result is set using the ExSetBit procedure. The above process is repeated until as many bits have been rotated as were specified by the 'bits' parameter. Note: The worst case shift has been reduced, using a modulus operation, to the number of bits in an ExInteger since rotations always preserve the original number.

The final shifting procedure, ExASh, performs an arithmetic shift right on the integer. What this means is that the sign bit of the ExInteger is replicated each time the ExInteger is shifted right so that the number's sign is preserved. Since ExNumbers are implemented with a separate sign bit, this value is easily extracted by setting a SavedBit flag if the sign is negative. The ExInteger is then shifted right one bit at a time (using ExDiv by two) until 'times to' have been shifted. For each shift, if the SavedBit flag was set, the upper bit of the ExInteger is set using ExSetBit to restore the number's sign.

Based String Conversions

To enable the calculator to deal with numbers in other bases (e.g., hexadecimal, binary, and octal) I need to introduce two new procedures called StrToExInt and ExIntToStr. The first of these routines converts a based string into an ExNumber and the second routine performs the inverse operation of converting an ExNumber into a based string. Both procedures work only with Integers; StrToExInt returns an illegal number error if requested to convert a floating point string and ExIntToStr constrains the ExNumber to a legal integer range before performing a conversion. I won't go into the details of these algorithms since they are very similar to the earlier string conversion routines you saw in the ExNumbers module. The chief difference is that the divisor becomes a power of the conversion base instead of a power of ten. Listing 1 has the complete source code for StrToExInt and ExIntToStr if you are interested. In the algorithms used for these conversions,

An ExNumber Math Library

Everyone knows that a calculator has transcendental (e.g., sine, cosine), logarithmic (e.g., log, ln), and power (e.g., x^y) functions. But these operations are usually very costly in terms of performance and

Set Operations	Equivalent Logical Operations
A+B	A or B
A-B	A and not B
AxB	A and B
A/B	A xor B

Table 1: Set Operations vs Logical Operations

Chunk Index	16-Bit Set Elements (Chunks)
Highest 0	0100 1001 1001 0110
1	0000 0010 1101 0010
2	0000 0000 0000 0000
	•
	•
	•
Lowest 10	0000 0000 0000 0000

Figure 1: ExInteger representation of the number '1234567890'.

Huge Numbers Part II

have algorithms which can become very complicated—especially since our calculator has up to 52 digits of precision. In fact, during my literature search, the best algorithms I could find had only from 16 to 25 digits of accuracy. There were a number of alternatives: 1) come up with the algorithms from scratch which would give 52 digits of accuracy; 2) use a lower-accuracy algorithm; 3) use existing lower-accuracy functions from the Amiga's IEEE math libraries. I opted for the third choice since I didn't have the time to invest in producing and testing the required precision algorithms and the speed penalty could be horrendous. As well, there was no point in reinventing the wheel when algorithms of comparable precision already existed on the Amiga.

I essentially created an interface (E6MathLib module in listing 2) to the double-precision IEEE floating-point library. The calculator could thus have 52 digits of precision at hardware speeds (if you have a floating-point processor). Several functions such as square root, cube root, integral powers/roots, and factorial do have the full PeNNum precision because the algorithms were easily extended to give 52-digit accuracy. If you have the ability and time to extend the precision of any other functions, I would appreciate hearing from you so that I can update this module with the new algorithms. Any algorithms I receive will be placed in the public domain—with the author's permission.

The heart of the IEEE floating-point interface lies in the ExNumToLongReal and LongRealToExNum conversion routines. To simplify the conversion process and demonstrate the power of reuse, I used several compiler-supplied conversion routines: LongRealToLongReal which translates a string into a double-precision IEEE floating-point number; and LongRealToStr which performs

the inverse operation. As well, ExNumToStr and StrToExNum, from the ExNumber module, provide string to PeNumber translations.

An IEEE number is converted to an ExNumber through an intermediate step of translating the number into a string. StrToExNum takes this string and produces a valid ExNumber. To reverse this process and produce an IEEE representation from an ExNumber, ExNumToStr uses an ExNumber to produce a string which ConvertStringReal then translates into the double-precision IEEE floating-point number. The expX procedure shown below demonstrates the conversion process and the IEEE interface. The expD function is a compiler-supplied library function which ties directly into the Amiga's double-precision IEEE library.

```
03000000 expX VAR Result : ExNumber; x : ExNumber; 030001  
longRealToLongReal(longRealToLongReal(x), 250 expX)
```

While many routines can be obtained using the IEEE library, some, like the inverse hyperbolic trigonometric operations, are not available in this library. I had to develop these algorithms from their basic definitions which follow:

```
Arctanh(x) = (Ln(1 + x) - Ln(1 - x)) / 2  
Arctanh(x) = (Ln(1 + x) - Ln(1 - x)) / 2
```

where Ln represents the natural logarithm of a number and Sqrt represents the square root of a number.

Several other functions such as integral roots and powers have algorithms which were easily extended to give full 52-digit precision.

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Huge Numbers Part II

The integral root algorithms are based on Newton's iterative method of finding roots of a function, whose basic equation is $y_{n+1} = y_n - f(y)/F'(y)$ where y_n is the n -th iterative solution, y_0 is the initial solution, $f(y)$ is the function whose root is required, and $F'(y)$ is the derivative of $f(y)$. I applied this equation to obtain the general root-finding algorithm shown below:

```
powerX := (x, n) = 1 - (1 - x) * (x + n) * (x + n - 1) / 2
```

where y_{n+1} and y_n are defined as before, n represents the root power (e.g., $n = 2$ for a square root), and x is the number whose root we wish to determine. The root procedure (top of Listing 2) implements this general algorithm and also adds the capability of finding negative roots (e.g., the cube root of -8 is 2). Both the sqrtX and rootX exported procedures use this general-purpose Root routine.

Integral powers are calculated using an algorithm published by Donald Knuth in his work, "The Art Of Computer Programming", the second volume. I have adapted his algorithm to also work for negative powers. The resulting implementation is shown in the xInt procedure in Listing 2. The beauty of Knuth's approach is that the calculation of any integral power involves only about $\log(n)/\log(2)$ multiplications where n represents the number's integral power. For example, this algorithm calculates 15^464 using only six multiplications. The expX and powerX procedures use the sqrt routine whenever they evaluate integral powers.

The last routine for which I have an extended precision algorithm is the factorialX procedure which computes the factorial of a number. Because EsNumbers have a much larger dynamic range ($\pm 1.11^*10^{333}$ to $\pm 1.11^*10^{600}$) than most other floating point numbers, factorials can be calculated of numbers as large as 3249! Compare this with the typical calculator which only gives factorials as large as 69! However, calculating this large a factorial also normally requires 3248 multiplications which could take quite a while even on the faster Amiga. To reduce this time, precalculated factorials at 500!, 1000!, 2000!, and 3000! have been stored in the EsMathLib module. Thus, to calculate 3249!, only 245 multiplications are required since the algorithm starts with 333!. Calling a routine 1000 times recursively can take a lot of stack space so the factorial procedure calculates factorials using an iterative algorithm rather than the recursive algorithm everyone is taught in school to keep the calculator's stack requirements to the CLI default.

CLI Calculator Revisited

Listing 3 shows the source code for the new CLI calculator which uses all the new functions discussed above and introduces a few new features such as access to 16 EsNumber storage locations, persistent state between invocations, an argument-passing interface, and a choice of numerical display formats. I'll take you on a brief excursion of the features which make up this new calculator.

Remembering

The first addition is that the calculator now can store and recall up to 16 EsNumbers using the syntax $STK(n)$ where n represents a number or expression to be stored and n is the location (0 to 15) where the result should be stored by the StoreMemory routine. To recall the value type $MA(n)$ where n represents the EsNumber location to recall via the RecallMemory routine. The EsNumbers are stored in a simple array which can be easily extended to allow number storage which is only limited by available memory.

All these storage locations and other calculator state variables are stored in the RAM drive (via the StoreState procedure) between calculator invocations so results from previous calculations can be reused during later sessions. The persistent memory also helps get around the problem of losing expressions which are longer than the maximum allowable input string of 250 characters. They can simply be split up and calculated in pieces, with intermediate results stored in the calculator's memory.

Argument Interface

In addition to the interactive mode, it is possible to use the calculator much like the Amiga's Eval program where the expression to be evaluated is passed to the calculator when it is invoked. For example, typing "Calculator 2000" produces the result "1024". The command line argument is extracted by the GetCLI procedure and then is processed just as if you had typed the expression interactively. Because the memory is retained between calculator invocations, you could store the results of one calculation in memory and then use those results in a following calculation. Some other than command line arguments are automatically separated by the operating system so spaces are left between words and quotation marks must be placed around expressions. For example, to calculate the sum of the last five factorials, from the CLI:

```
Calculator "3249 - 3199 * 5 + 3194 * 5"
```

The answer "153" is displayed when the CLI prompt returns. Of course, the spaces are optional, and "1 - 2 + 3 + 4 - 5" (with no spaces) would produce the same result without requiring quotations.

Output Formats

You can toggle the format of the calculator's output numbers between the default floating point notation and scientific notation. Just type SC to toggle between these two modes. Be careful to type the exact name as shown because all the calculator functions are case-sensitive. If you type in a number like 2 and then switch to scientific notation you may be shocked at all the trailing zeros that get displayed. Several commands let you suppress these extra digits: DP(n) lets you enter the number of decimal point digits which should be displayed where n can be a number between 0 and 52. Specifying a value of 0 selects the default floating decimal point notation while any other number fixes the decimal point at n digits. DEC(n) selects the number of digits that the calculator uses when performing its calculations. Valid values for n are from 0 to the default of 52. All calculator format definitions are saved to the RAM disk between calculator sessions.

Other Functions

The calculator allows evaluation of any trigonometric function (SIN, COS, TAN). The default angular units are in degrees. The command DEG toggles between angular units in degrees, radians, and grads.

Base6 numbers, as discussed above, represent a subset of the EsNumbers. To get the calculator into the base6 number mode, type BAS6 where n represents the numerical base from 2 to 16. The value for n is always specified in decimal no matter which base the calculator is using. Numbers containing decimals and exponents are illegal when in a numeric base other than 10. Base6 numerical systems greater than 10 use the uppercase alphabetic characters A-7 to represent numbers in addition to the standard digits but every number must

Huge Numbers Part II

```

END SUB;

FUNCTION LogicalToBinary (Logical: LogicalType) AS Byte;
    (* Convert a logical value to binary. The logical value is
    not 0.)
    CONST Min=0, Max=255;

    (* Initialize an array of 8 bits *)
    Dim arr(8) AS Byte; arr(0) = 0; arr(1) = 0; arr(2) = 0; arr(3) = 0; arr(4) = 0; arr(5) = 0; arr(6) = 0; arr(7) = 0;

    (* get a conversion factor *)
    Logical = Logical * 255;
    Logical = Logical / 255;
    WHILE NOT Logical=0;
        arr(7) = Logical / 255; arr(7) = arr(7) * 255;
        Logical = Logical - arr(7);
        arr(6) = Logical / 255; arr(6) = arr(6) * 255;
        Logical = Logical - arr(6);
        arr(5) = Logical / 255; arr(5) = arr(5) * 255;
        Logical = Logical - arr(5);
        arr(4) = Logical / 255; arr(4) = arr(4) * 255;
        Logical = Logical - arr(4);
        arr(3) = Logical / 255; arr(3) = arr(3) * 255;
        Logical = Logical - arr(3);
        arr(2) = Logical / 255; arr(2) = arr(2) * 255;
        Logical = Logical - arr(2);
        arr(1) = Logical / 255; arr(1) = arr(1) * 255;
        Logical = Logical - arr(1);
        arr(0) = Logical / 255; arr(0) = arr(0) * 255;
        Logical = Logical - arr(0);
    END;

    RETURN arr;
END FUNCTION;

FUNCTION LogicalToHex (Logical: LogicalType) AS String;
    Dim Hex: String = "";
    Dim Temp: LogicalType;
    Dim Bits: Integer = 1;

    (* Initialize an array of 8 bits *)
    Dim arr(8) AS Byte; arr(0) = 0; arr(1) = 0; arr(2) = 0; arr(3) = 0; arr(4) = 0; arr(5) = 0; arr(6) = 0; arr(7) = 0;

    (* convert conversion *)
    Hex = Hex & "0";
    FOR Logical = Logical / 255 TO 255 BY 255;
        arr(7) = Logical / 255; arr(7) = arr(7) * 255;
        Logical = Logical - arr(7);
        arr(6) = Logical / 255; arr(6) = arr(6) * 255;
        Logical = Logical - arr(6);
        arr(5) = Logical / 255; arr(5) = arr(5) * 255;
        Logical = Logical - arr(5);
        arr(4) = Logical / 255; arr(4) = arr(4) * 255;
        Logical = Logical - arr(4);
        arr(3) = Logical / 255; arr(3) = arr(3) * 255;
        Logical = Logical - arr(3);
        arr(2) = Logical / 255; arr(2) = arr(2) * 255;
        Logical = Logical - arr(2);
        arr(1) = Logical / 255; arr(1) = arr(1) * 255;
        Logical = Logical - arr(1);
        arr(0) = Logical / 255; arr(0) = arr(0) * 255;
        Logical = Logical - arr(0);
    END;

    (* ----- *)
    (* local procedure to get a number *)
    (* logical to hex function on EXAMINER *)

    PROCEDURE GetHexResult: EXAMINER;
        Dim Hex: String = "";
        Dim Hex: LogicalType;
        Dim Hex: LogicalType;
        Dim Hex: LogicalType;

    AND
        Hex: LogicalType;
        Hex: LogicalType;
        Hex: LogicalType;
        Hex: LogicalType;

    BEGIN
        (* Transfer the logicals *)
        Hex = Hex & arr(7);
        Hex = Hex & arr(6);
        Hex = Hex & arr(5);
        Hex = Hex & arr(4);
        Hex = Hex & arr(3);
        Hex = Hex & arr(2);
        Hex = Hex & arr(1);
        Hex = Hex & arr(0);

        (* Generate an arr(0) to arr(7) and give it a name *)
        Dim Hex: String = Hex;
        Hex = Hex & arr(7);
        Hex = Hex & arr(6);
        Hex = Hex & arr(5);
        Hex = Hex & arr(4);
        Hex = Hex & arr(3);
        Hex = Hex & arr(2);
        Hex = Hex & arr(1);
        Hex = Hex & arr(0);

        (* Convert the hex to decimal *)
        Logical = Hex * 255;
    END;

```

```

END SUB;

(* ----- *)
(* local procedure to get a number *)
(* logical to hex function on EXAMINER *)

PROCEDURE GetHexResult: EXAMINER;
    Dim Hex: LogicalType;
    Dim Hex: LogicalType;
    Dim Hex: LogicalType;
    Dim Hex: LogicalType;

AND
    Hex: LogicalType;
    Hex: LogicalType;
    Hex: LogicalType;
    Hex: LogicalType;

BEGIN
    (* Transfer the logicals *)
    Hex = Hex & arr(7);
    Hex = Hex & arr(6);
    Hex = Hex & arr(5);
    Hex = Hex & arr(4);
    Hex = Hex & arr(3);
    Hex = Hex & arr(2);
    Hex = Hex & arr(1);
    Hex = Hex & arr(0);

    (* Generate an arr(0) to arr(7) and give it a name *)
    Dim Hex: String = Hex;
    Hex = Hex & arr(7);
    Hex = Hex & arr(6);
    Hex = Hex & arr(5);
    Hex = Hex & arr(4);
    Hex = Hex & arr(3);
    Hex = Hex & arr(2);
    Hex = Hex & arr(1);
    Hex = Hex & arr(0);

    (* Convert the hex to decimal *)
    Logical = Hex * 255;
END;

(* ----- *)
(* local procedure to get a number *)
(* logical to hex function on EXAMINER *)

PROCEDURE GetHexResult: EXAMINER;
    Dim Hex: LogicalType;
    Dim Hex: LogicalType;
    Dim Hex: LogicalType;
    Dim Hex: LogicalType;

AND
    Hex: LogicalType;
    Hex: LogicalType;
    Hex: LogicalType;
    Hex: LogicalType;

BEGIN
    (* Transfer the logicals *)
    Hex = Hex & arr(7);
    Hex = Hex & arr(6);
    Hex = Hex & arr(5);
    Hex = Hex & arr(4);
    Hex = Hex & arr(3);
    Hex = Hex & arr(2);
    Hex = Hex & arr(1);
    Hex = Hex & arr(0);

    (* Generate an arr(0) to arr(7) and give it a name *)
    Dim Hex: String = Hex;
    Hex = Hex & arr(7);
    Hex = Hex & arr(6);
    Hex = Hex & arr(5);
    Hex = Hex & arr(4);
    Hex = Hex & arr(3);
    Hex = Hex & arr(2);
    Hex = Hex & arr(1);
    Hex = Hex & arr(0);

    (* Convert the hex to decimal *)
    Logical = Hex * 255;
END;

```

Huge Numbers Part II

```

number      : EX8intType
degree      : EX8intType
bits        : CARDINAL
end

VAR
  Temp : EX8intType;
begin
  label;
  (* Const. result number to be within the logical number set *)
  C := val(Temp) + 1;

  (* Const. result number from 0 to MaxBase2Bits *)
  if bits > MaxBase2Bits THEN
    (* Shifted out of range *)
    result := -2;
  else
    C :=
      (C + bits - 1) DIV bits;

  (* Const. result number *)
  Construct(Result, number, Count);

  (* Const. result number to be within the logical number set *)
  Construct(ExhaustResult);
END Result;

(* ----- *)
(* local procedure to perform general *)
(* routine addition operations on TNumbers *)

PROCEDURE Result (VAR Result : EX8intType;
                 number     : EX8intType;
                 ShiftRight : EX8intType;
                 bits       : CARDINAL);
VAR
  C : TNumber := 0;
  temp : EX8intType;
  Shift : EX8intType;
begin
  (* Const. result number to be within the logical number set *)
  Construct(Result, number);

  (* Const. result number from 0 to MaxBase2Bits *)
  bits := bits MIN (MaxBase2Bits + 1);
  Shift := 0; C := 0;

  while ShiftRight <= 1 TO bits DO
    -- ShiftRight then
    (* Save the bit to be shifted *)
    savedBit := bit(number, Shift);

    (* Add 1, the number is 1 bit *)
    Result := number + number * 2;
    Shift := Shift + 1;

    IF SavedBit THEN
      Result := number + number * MaxBase2Bits;
    end;
  end;
end;

(* Save the bit to be shifted *)
savedBit := bit(number, MaxBase2Bits + 1);

(* Shift the number 1 bit *)
Shift := number * 2;
end;

```

```

(* Const. the saved bit *)
if savedBit THEN
  (* Set 1, number, number, 0,
  bits *)
  Temp;
end;

(* Const. result number to be within the logical number set *)
Result := number;
Construct(Result);
END Result;

(* ----- *)
(* repeated procedures *)

PROCEDURE Result (VAR Result : EX8intType;
                 op1, op2 : EX8intType);
VAR
  Result;
begin
  C := Result; op1 := op2;
end;

(* Const. result number to be within the logical number set *)
op1, op2 := EX8intType;
Result := Result; op1 := op2;
end;

(* Const. result number to be within the logical number set *)
op1, op2 := EX8intType;
Result := Result; op1 := op2;
end;

(* Const. result number to be within the logical number set *)
op1, op2 := EX8intType;
Result := Result; op1 := op2;
end;

(* Const. result number to be within the logical number set *)
op1, op2 := EX8intType;
Result := Result; op1 := op2;
end;

(* Const. result number to be within the logical number set *)
op1, op2 := EX8intType;
Result := Result; op1 := op2;
end;

(* Const. result number to be within the logical number set *)
op1, op2 := EX8intType;
Result := Result; op1 := op2;
end;

(* Const. result number to be within the logical number set *)
op1, op2 := EX8intType;
Result := Result; op1 := op2;
end;

(* Const. result number to be within the logical number set *)
op1, op2 := EX8intType;
Result := Result; op1 := op2;
end;

(* Const. result number to be within the logical number set *)
op1, op2 := EX8intType;
Result := Result; op1 := op2;
end;

(* Const. result number to be within the logical number set *)
op1, op2 := EX8intType;
Result := Result; op1 := op2;
end;

```

Integer Numbers Part II

```
PROCEDURE ExDiv (VAR Result : IntegerType;
                number : IntegerType;
                Divisor : IntegerType);
```

```
BEGIN
    DivResult := number / Divisor;
    DivRemainder := Mod(number, Divisor);
```

```
TRUNCATEDiv (VAR Result : IntegerType;
             number : IntegerType;
             Divisor : IntegerType);
```

```
BEGIN
    DivResult := number / Divisor;
    DivRemainder := Mod(number, Divisor);
```

```
PROCEDURE SetSign (VAR Result : IntegerType;
                  number : IntegerType);
```

```
BEGIN
    (* Convert number to result in the logical number set *)
    ConvertInteger(number, Result);
```

```
    ConvertInteger(number, Result);
    IF number < 0 THEN
        (* Subtract from the maximum number *)
        DivResult := MaxNumber - number;
    ELSE
        (* Subtract from the minimum number *)
        DivResult := MinNumber + number;
    END;
```

```
    (* Complement the sign bit *)
    Result := Result;
```

```
PROCEDURE ExM (VAR Result : IntegerType;
               number : IntegerType;
               exponent : Cardinal);
```

```
BEGIN
    DivResult := number / Divisor;
    DivRemainder := Mod(number, Divisor);

    IF exponent < 0 THEN
        (* Shift right *)
        DivResult := DivResult / 2;
    ELSE
        (* Shift left *)
        DivResult := DivResult * 2;
    END;
END ExM;
```

```
PROCEDURE ExR (VAR Result : IntegerType;
               number : IntegerType;
               exponent : Cardinal);
```

```
BEGIN
    DivResult := number / Divisor;
    DivRemainder := Mod(number, Divisor);
END ExR;
```

```
PROCEDURE ExS (VAR Result : IntegerType;
               number : IntegerType;
               exponent : Cardinal);
```

```
BEGIN
    DivResult := number / Divisor;
    DivRemainder := Mod(number, Divisor);
    DivSign := Sign(number);
END ExS;
```

```
PROCEDURE ExD (VAR Result : IntegerType;
```

```
                number : IntegerType;
                divisor : IntegerType);
```

```
VAR
    ShiftCnt : Cardinal;
    SavedBit : Boolean;
```

```
BEGIN
    (* Determine number to be shifted in the logical number set *)
    ConvertInteger(number, Result);
```

```
    (* Must shift bits from 0 to MaxBase-1 bits *)
    IF number < MaxBase-1 THEN
        (* Shift out of range *)
        Result := 0;
        RETURN;
    END;
```

```
    (* Set the saved bit to the current sign bit *)
    SavedBit := number < 0;
```

```
    (* Shift the number *)
    FOR ShiftCnt := 0 TO MaxBase-1 DO
        (* Shift the number right *)
        ExDiv(number, Result);
```

```
    (* Restore the saved bit *)
    IF SavedBit THEN
        Result := -number;
    ELSE
        Result := number;
    END;
END;
```

```
    (* Complement any fraction bit *)
    Result := -Result;
    DivResult := DivResult;
    DivRemainder := Mod(number, Divisor);
END ExD;
```

```
PROCEDURE ExM (VAR Result : IntegerType;
               number : IntegerType;
               exponent : Cardinal);
```

```
BEGIN
    DivResult := number / Divisor;
    DivRemainder := Mod(number, Divisor);
END ExM;
```

```
PROCEDURE ExR (VAR Result : IntegerType;
               number : IntegerType;
               exponent : Cardinal);
```

```
VAR
    ExCnt, Total : Integer;
    Multiplier : Integer;
    Scale, Temp : IntegerType;
```

```
PROCEDURE ExS (VAR Result : IntegerType;
               number : IntegerType;
               exponent : Cardinal);
```

```
VAR
    Str : ARRAY [0..1] OF Char;
    Digits : IntegerType;
    ExCnt : IntegerType;
    Total : IntegerType;
```

```
IF Result < 0 THEN
    ExCnt := -Total;
    ExSign := -1;
    RETURN;
END;
BEGIN
    ExCnt := Total;
```

Huge Numbers Part II

THE MAIN PROGRAM

```

BEGIN
  A := 100;
  B := 1000;
  C := TRANSFORM(S,
  TRANSFORM(S, B), C) SCALE(1);

  (* Write leading blank *)
  WRITE(LOCALS & ENDLINE, 'A := 100 B := 1000 C :=
END;

W := (LOCALS & TRANSFORM(TRANSFORM(A, 10) * (B + C) * 100
SCALE(10) * TRANSFORM(S, B), C) SCALE(1)
  B := (LOCALS & SCALE(1)
  TRANSFORM(S, C) * B);
END;
END THE MAIN PROGRAM
  
```

```

PROCEDURE EXERCISES;
  USES 'IO, MATH, STR, TRANSFORM';
  VAR S : ARRAY OF CHAR;
  
```

```

BEGIN
  S := 'STRINGS';
  WRITE(S, 'SINCE, TRAN, TRANS : EXERCISES');
  
```

```

PROCEDURE TRANSFORM(S: STRING; SCALE: REAL);
  VAR
    STR : ARRAY OF CHAR;
    OK : BOOLEAN;
  BEGIN
    OK := CONVERT(STR, S, 10, SCALE, FALSE, 4, 10);
    WRITE(STR);
  END TRANSFORM;
  
```

```

BEGIN
  (* Convert a number to be within the action number set *)
  CONVERT(LOCALS);
  
```

```

  S := 'A';
  TRANSFORM(S, 10);
  TRANSFORM(S, 10, 100);
  TRANSFORM(S, 10, 100, 100);
  TRANSFORM(S, 10, 100, 100);
  
```

```

  (* Scale a number to a certain
  scale *)
  (* TRAN := TRANSFORM *)
  TRANSFORM(LOCALS, A, 100);
  TRANSFORM(TEMP1);
  TRANSFORM(TEMP2, 100);
  TRANSFORM(TEMP3, 100);
  
```

```

  (* Scale a character *)
  TRANSFORM(S, 100);
  
```

```

  (* Round A by scaling factor *)
  A := TRANSFORM;
  UNTIL LOCALS;
END EXERCISES;
  
```

```

BEGIN
  (* Write the number 2 *)
  TRANSFORM(S, 2, 10, 100);
  
```

```

  (* Initialize the location of the
  xbit (XbitNumber, Two, Max XbitNumber);
  TRANSFORM(XbitNumber, XbitNumber, Two);
  
```

```

  (* Initialize the number of
  digits (N := XbitNumber;
  TRANSFORM(N, XbitNumber);
  
```

```

  (* Initialize the base (logical) *)
  FOR N := 1 TO LOGICAL(1) DO
    LOGICAL(N) := 1;
  END;
END INTEGERS;
  
```

+	Addition
-	Subtraction
*, x	Multiplication
/, ÷	Division
^	Squared
^3	Cubed
1/x	Reciprocal
()	Brackets
^n	Power
x 0.01	x 0.01
!	Factorial
&, AND, .	Logical And
, OR	Logical Or
XOR	Logical Exclusive Or
CPL	Logical Complement
MOD	Modulo
DIV	Integer Division
SQRT	Square Root
CBRT	Cube Root
ROOT	Any Root
e	Natural Log Base
e^	Power of e
LN	Natural Logarithm
LOG	Base 10 Logarithm
(A)SIN	(Arc)Sine
(A)COS	(Arc)Cosine
(A)TAN	(Arc)Tangent
(A)SINH	(Arc)Hyperbolic Sine
(A)COSH	(Arc)Hyperbolic Cosine
(A)TANH	(Arc)Hyperbolic Tangent
SBIT	Set Bit
CBIT	Clear Bit
TBIT	Toggle Bit
SHR	Shift Right
SHL	Shift Left
ASR	Arithmetic Shift Right
ROR	Rotate Right
ROL	Rotate Left
Mn	Memory Location n
STM n	Store to Memory n
Pi	Constant Pi
SCI	Toggle Scientific/Floating Pt.
BAS n	Change to Base n
DIG n	Use n Digits
DP n	Use n Decimal Places
DRG	Toggle Degree/Radian/Grad

Table 2: Calculator Operations and Commands

Huge Numbers Part II

Listing Two

```

TYPEFORM(EN, EX, MODULUS, EXPONENT);

FROM EN: Number, LHS, OP, RHS, Type, A, T, Z, Coef, ExpType,
  ND, N;
FROM EX: Sign, ExAbs, ExFormate, E,
  EXCoef, ExpType, Exp, ExSig, ExS;

ENL;

ENL;

ENL;

CONVERTION;

FROM EN: Sign, EX: ExAbs, EX: ExFormate,
  EX: EXCoef, EX: ExSig, EX: ExS;

FROM EN: Type, SignType, EX: ExFormate;

L232 L233 L234 L235 L236 L237 L238 L239 L240 L241 L242 L243 L244 L245 L246 L247 L248 L249 L250 L251 L252 L253 L254 L255 L256 L257 L258 L259 L260 L261 L262 L263 L264 L265 L266 L267 L268 L269 L270 L271 L272 L273 L274 L275 L276 L277 L278 L279 L280 L281 L282 L283 L284 L285 L286 L287 L288 L289 L290 L291 L292 L293 L294 L295 L296 L297 L298 L299 L300 L301 L302 L303 L304 L305 L306 L307 L308 L309 L310 L311 L312 L313 L314 L315 L316 L317 L318 L319 L320 L321 L322 L323 L324 L325 L326 L327 L328 L329 L330 L331 L332 L333 L334 L335 L336 L337 L338 L339 L340 L341 L342 L343 L344 L345 L346 L347 L348 L349 L350 L351 L352 L353 L354 L355 L356 L357 L358 L359 L360 L361 L362 L363 L364 L365 L366 L367 L368 L369 L370 L371 L372 L373 L374 L375 L376 L377 L378 L379 L380 L381 L382 L383 L384 L385 L386 L387 L388 L389 L390 L391 L392 L393 L394 L395 L396 L397 L398 L399 L400 L401 L402 L403 L404 L405 L406 L407 L408 L409 L410 L411 L412 L413 L414 L415 L416 L417 L418 L419 L420 L421 L422 L423 L424 L425 L426 L427 L428 L429 L430 L431 L432 L433 L434 L435 L436 L437 L438 L439 L440 L441 L442 L443 L444 L445 L446 L447 L448 L449 L450 L451 L452 L453 L454 L455 L456 L457 L458 L459 L460 L461 L462 L463 L464 L465 L466 L467 L468 L469 L470 L471 L472 L473 L474 L475 L476 L477 L478 L479 L480 L481 L482 L483 L484 L485 L486 L487 L488 L489 L490 L491 L492 L493 L494 L495 L496 L497 L498 L499 L500 L501 L502 L503 L504 L505 L506 L507 L508 L509 L510 L511 L512 L513 L514 L515 L516 L517 L518 L519 L520 L521 L522 L523 L524 L525 L526 L527 L528 L529 L530 L531 L532 L533 L534 L535 L536 L537 L538 L539 L540 L541 L542 L543 L544 L545 L546 L547 L548 L549 L550 L551 L552 L553 L554 L555 L556 L557 L558 L559 L560 L561 L562 L563 L564 L565 L566 L567 L568 L569 L570 L571 L572 L573 L574 L575 L576 L577 L578 L579 L580 L581 L582 L583 L584 L585 L586 L587 L588 L589 L590 L591 L592 L593 L594 L595 L596 L597 L598 L599 L600 L601 L602 L603 L604 L605 L606 L607 L608 L609 L610 L611 L612 L613 L614 L615 L616 L617 L618 L619 L620 L621 L622 L623 L624 L625 L626 L627 L628 L629 L630 L631 L632 L633 L634 L635 L636 L637 L638 L639 L640 L641 L642 L643 L644 L645 L646 L647 L648 L649 L650 L651 L652 L653 L654 L655 L656 L657 L658 L659 L660 L661 L662 L663 L664 L665 L666 L667 L668 L669 L670 L671 L672 L673 L674 L675 L676 L677 L678 L679 L680 L681 L682 L683 L684 L685 L686 L687 L688 L689 L690 L691 L692 L693 L694 L695 L696 L697 L698 L699 L700 L701 L702 L703 L704 L705 L706 L707 L708 L709 L710 L711 L712 L713 L714 L715 L716 L717 L718 L719 L720 L721 L722 L723 L724 L725 L726 L727 L728 L729 L730 L731 L732 L733 L734 L735 L736 L737 L738 L739 L740 L741 L742 L743 L744 L745 L746 L747 L748 L749 L750 L751 L752 L753 L754 L755 L756 L757 L758 L759 L760 L761 L762 L763 L764 L765 L766 L767 L768 L769 L770 L771 L772 L773 L774 L775 L776 L777 L778 L779 L780 L781 L782 L783 L784 L785 L786 L787 L788 L789 L790 L791 L792 L793 L794 L795 L796 L797 L798 L799 L800 L801 L802 L803 L804 L805 L806 L807 L808 L809 L810 L811 L812 L813 L814 L815 L816 L817 L818 L819 L820 L821 L822 L823 L824 L825 L826 L827 L828 L829 L830 L831 L832 L833 L834 L835 L836 L837 L838 L839 L840 L841 L842 L843 L844 L845 L846 L847 L848 L849 L850 L851 L852 L853 L854 L855 L856 L857 L858 L859 L860 L861 L862 L863 L864 L865 L866 L867 L868 L869 L870 L871 L872 L873 L874 L875 L876 L877 L878 L879 L880 L881 L882 L883 L884 L885 L886 L887 L888 L889 L890 L891 L892 L893 L894 L895 L896 L897 L898 L899 L900 L901 L902 L903 L904 L905 L906 L907 L908 L909 L910 L911 L912 L913 L914 L915 L916 L917 L918 L919 L920 L921 L922 L923 L924 L925 L926 L927 L928 L929 L930 L931 L932 L933 L934 L935 L936 L937 L938 L939 L940 L941 L942 L943 L944 L945 L946 L947 L948 L949 L950 L951 L952 L953 L954 L955 L956 L957 L958 L959 L960 L961 L962 L963 L964 L965 L966 L967 L968 L969 L970 L971 L972 L973 L974 L975 L976 L977 L978 L979 L980 L981 L982 L983 L984 L985 L986 L987 L988 L989 L990 L991 L992 L993 L994 L995 L996 L997 L998 L999 L1000

```

```

(* program to solve quadratic equation, The Art of
Computer Programming, Vol 1 #2
1978
C: 1978, 1979
negative: LOGICAL;
RTN;

X := -B;
negative := (-b + a);
X := X/2;

DOOR;
IF COEF(1) THEN EXABS(X), Y, XI END;
X := X/2;
IF (-b, THEN EXABS(X);
401 20, 21;

END;
IF negative THEN
402 20, 21, 22;
ELSE
403 20 = Y;
404;
END;

PROCEEDAs root (with result: L, R, Type);
X := B/COEF(1);
I := COEF(1);

(* The iterative solution of a general root equation *)
V;
Y, YP, L, G, C, LEXP, NPM;
FROM COEF(1);
negative := LOGICAL;

DOOR;
IF (X, Sign, negative) & COEF(1) OR (L & X) THEN
405 20 = L;
406;
ELSE
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999 L1000

```

Huge Numbers Part II

complex: bool;

```

7900 int read() {scanf("%d", &angle); return angle;
81   const double pi = 3.141592653589793;
82   int n;
83   while (read() < angle) {}
84   double ans;

```

```

85   while (angle < pi) angle = pi - angle; return ans;
86   const double pi = 3.141592653589793;
87   int n;
88   while (angle < pi) angle = pi - angle;
89   double ans;

```

```

90   double ans;
91   while (angle < pi) angle = pi - angle;
92   int n;
93   while (angle < pi) angle = pi - angle;
94   double ans;

```

```

95   double ans;
96   while (angle < pi) angle = pi - angle;
97   int n;
98   while (angle < pi) angle = pi - angle;
99   double ans;

```

```

100   double ans;
101   while (angle < pi) angle = pi - angle;
102   int n;
103   while (angle < pi) angle = pi - angle;
104   double ans;

```

```

105   double ans;
106   while (angle < pi) angle = pi - angle;
107   int n;
108   while (angle < pi) angle = pi - angle;
109   double ans;

```

```

110   double ans;
111   while (angle < pi) angle = pi - angle;
112   int n;
113   while (angle < pi) angle = pi - angle;
114   double ans;

```

```

115   double ans;
116   while (angle < pi) angle = pi - angle;
117   int n;
118   while (angle < pi) angle = pi - angle;
119   double ans;

```

```

120   double ans;
121   while (angle < pi) angle = pi - angle;
122   int n;
123   while (angle < pi) angle = pi - angle;
124   double ans;

```

double ans;

```

125   double ans;
126   while (angle < pi) angle = pi - angle;
127   int n;
128   while (angle < pi) angle = pi - angle;
129   double ans;

```

```

130   double ans;
131   while (angle < pi) angle = pi - angle;
132   int n;
133   while (angle < pi) angle = pi - angle;
134   double ans;

```

```

135   double ans;
136   while (angle < pi) angle = pi - angle;
137   int n;
138   while (angle < pi) angle = pi - angle;
139   double ans;

```

```

140   double ans;
141   while (angle < pi) angle = pi - angle;
142   int n;
143   while (angle < pi) angle = pi - angle;
144   double ans;

```

```

145   double ans;
146   while (angle < pi) angle = pi - angle;
147   int n;
148   while (angle < pi) angle = pi - angle;
149   double ans;

```

```

150   double ans;
151   while (angle < pi) angle = pi - angle;
152   int n;
153   while (angle < pi) angle = pi - angle;
154   double ans;

```

```

155   double ans;
156   while (angle < pi) angle = pi - angle;
157   int n;
158   while (angle < pi) angle = pi - angle;
159   double ans;

```

```

160   double ans;
161   while (angle < pi) angle = pi - angle;
162   int n;
163   while (angle < pi) angle = pi - angle;
164   double ans;

```

```

165   double ans;
166   while (angle < pi) angle = pi - angle;
167   int n;
168   while (angle < pi) angle = pi - angle;
169   double ans;

```

```

170   double ans;
171   while (angle < pi) angle = pi - angle;
172   int n;
173   while (angle < pi) angle = pi - angle;
174   double ans;

```


PROGRAMMING THE AMIGA IN ASSEMBLY LANGUAGE

BY WILLIAM P. NEE

There's a lot to cover in this article. We'll discuss using the math co-processor, a new assembler, another way to tighten up your code and two programs that demonstrate the beauty of Chaos. I'll also show you how to color cycle each of the ten available palettes we'll use. To run this program you'll need at least an Amiga 3000 or a modified Amiga that includes the 68881/68882 math chip.

68881/68882

First the co-processor. There are eight additional registers (F10 to F17) in the 68882, all designed for high-precision, high-speed math operations. A special advantage of these registers is that you don't have to open any library to use them so there are no effects to worry about. Be sure though, to have the MATHLIBDOUBBAS and MATHLIBDOUBTRANS libraries available in your Libs: directory. While these two libraries are not called directly by the math co-processor, they are used indirectly by the various commands.

The commands for these registers are very easy to use and usually involve putting a F in front of most of the single-precision commands I've previously written about (see AC's TECH Volume 9 Number 2). The extensions, however, are a little different since we can now handle numbers in several formats at one time. In addition to the usual D, W, and L extensions we'll use:

- .R (extended-precision)
- .D (double-precision)
- .X (extended-precision)
- .O (signed numbers)

Any operation can be performed on any fp register. While this doesn't sound like such a big deal, remember that with double-precision all commands used d0/d1 or d0/d1 and d2/d3. It not only took four registers to add two numbers, but you could only use the first four; multiple operations required you to save the result in two more registers or use a variable. With the fp registers you can move a value to any register, add any two registers, and add a variable/constant and a register. And, they're fast! They're a lot faster than single-precision and, of course, a lot more precise.

Using the Math Co-Processor

Let's look at some of the more common fp commands.

<code>FMOVE.D V1(255668),FP1</code>	- move a double-precision value directly into a fp register
<code>FMOVE.D 2(A5),FP1</code>	- move the double-precision value at 2(A5) into a fp register
<code>FMOVE.D FP0(A5)</code>	- move the value in the fp register to a double-precision value at 0(A5)
<code>FMOVE.X FP0,FP1</code>	- move the fp value from one fp register to another
<code>FMOVE.L FP2,ACROSS</code>	- move the integer value in the fp register to a long-word variable
<code>FMOVE.L FP6,D1</code>	- move the integer value in the fp register to a data register

The rest of the commands are variations of the SP or DP commands

<code>FADD.D 2(A5),FP1</code>	- add a dp variable and an fp register
<code>FSUB.X FP1,FP2</code>	- subtract two fp registers
<code>FMLT.D 4(A5),FP0</code>	- multiply a dp variable and an fp register
<code>FDIV.X F25,F10</code>	- divide two fp registers
<code>FSIN.X FP1</code>	- get the sin of the value in an fp register

Well, you can see how the commands would go. I've included a list of the major commands in Table 1 although this article doesn't use most of them. If the command uses multiple registers, the second fp register contains the results. So in `FADDX FP0,FP1` `fp0` would contain the result of adding the two fp registers; `fp0` would still contain it's original value.

ANOTHER CODE TECHNIQUE

You'll notice that several of the examples above use an offset from register `a5` as the variable to add to the fp register. That's because most of the variables in the program for this article are referenced relative to `a5`. Initially, each variable is equated to it's distance from a starting variable `V1` or `V2`. If the first variable is `E1`'s distance is zero so `E1 EQU 0`. In the second half of the program there are several `long-word` double-precision values. At the end of the program they are stored as:

```
V2
E DC.B 0.0
M DC.L 0.0
W DC.L 0.0
...
M1 DC.L 0.0
...
M2 DC.L 0.0
...
```

At the beginning of the program I equate all of these variables to their distance from `V2`:

```
E EQU 0
M EQU 4
W EQU 8
...
M1 EQU 40
...
M2 EQU 72
...
```

Now, all I have to do is include the line `FA V2(C),A5` and all variables can be referenced by name as an offset from `a5`. For example, `FADDL B11(A5),FP0` will add the variable `B11` to the value in `fp0`. This cuts down on code length since variables are now considered as an offset instead of having to reference their actual locations. Of course, values can be moved in the variables using the same method, `FMOVE.D FP1,F(A5)`

moves the value in `fp0` to the copy-able `F1`. Just remember to equate your variables as a distance from the initial variable, store your variables in order and put the first variable location in an address register (usually `a4` or `a5`) that won't be used again, if the register must be used, keep it's original value location.

Look at the difference in code for these four lines:

```
MOVE.L EQU(0%),FP0      0000 0000 0000
FMOVE.D EQU(0%),FP1    0100 4000 0000
MOVE.L EQU(0%),FP0     0000 0000 0000
FMOVE.L EQU(0%),FP1    0100 0000 0000
```

You can see that PHXASB tries to optimize the code and succeeds except in the last case. Using `LABE(A5)`, however, keeps the code length down to 4 bytes. In a future article we'll see how PHXASB can optimize all these examples.

ANOTHER ASSEMBLER

Now for a new assembler. This article uses `PHXASB` and `PHLINK` from Fish 766 #453, by Frank Wille. This is the only PH/Shareware assembler I know about that uses the 58881/68882 DPCP. It will also accept the various different commands for the 68000/10/20/40/401. There are some specific things you need to do with your code when using PHXASB. First, if you're going to use the math chips, include the command `FPU` for the beginning (the "U" is actually optional), and if you're going to use any specific 68000/10 commands, also include `MACHINE 68000` or `MACHINE 68040` at the beginning. It's well of course, keep your program from running on a 68300/10/20.

Some peculiarities of this assembler are:

- 1) All include files must be in quotes - this took me several weeks to figure out!
- 2) References cannot include a `?` such as `NEWBASE ?ORJ?` must use `NEWBASE?ORJ`. I rewrote all of my include files to be written this way.
- 3) A macro cannot begin with `@"` to show it is different. In my program I'm using a special `PS?T` as I tried to `ps?t 687577`, but `ps?t` deleted `GFX/ACVOL` and put all graphics macros at the beginning of the program.
- 4) There is a problem with some macros that use `NARG`. If there are no arguments passed, `NARG` may be 1 instead of 0. Just re-write that portion as code instead of as a macro.
- 5) The assembler will accept `MOVE.L #7LD0` instead of `#57D`; it only stores the 47, however, in `D0`.
- 6) You may have to include `SECTION` macros `CODE` at the beginning of your program to avoid an "out of memory" error.

The good news is that all of these bugs and others have been corrected by Mr. Wille. I acquainted with him by sending him \$15.00 and got a new PHXASB version (V4.08) in a zip or two weeks. Since I'll only be using, however, the version on the fish disk, this program is written to compensate for the bug-in that version. I urge you to register with Mr. Wille if you're going to do any assembly language programming. PHXASB is fast! Also, for your convenience, I've included `JASB` - a script file that will assemble your `ASM` file, `PHLINK` and delete the `.O` file. The `DXC` files for PHXASB and PHLINK are also included on the magazine disk.

CHAOS AND BEAUTY

To demonstrate the use of fractal geometry numbers I combined two different programs that graphically display `Chaos and Beauty`. Chaos is a fairly new theory that demonstrates how nothing can be perfect, that there are always subtle changes to everything. But, in the long run, these

Programming the Amiga in Assembly Language

changes still produce an overall effect that can be predicted. Most of the Chaos equations show how you can start with random values and eventually settle down to some type of organized display.

The first program comes from the book "Symmetry in Chaos" by Field and Golubitsky. In their equations using complex numbers (those numbers with i , the square root of -1) they make extensive use of the conjugate of a complex number Z . If $Z=X-iY$ then the conjugate of Z , called $Zbar$, is $X+iY$. Z squared is X^2-Y^2+2iXY while $Zbar$ squared is X^2-Y^2-2iXY , and $Z*Zbar$ is X^2+Y^2 .

Their equations produce very complex but symmetrical patterns. The variables used are: L, A, B, O, G, and N where N is the degree of symmetry, at least 3. Once an original Z with X and Y coordinates has been selected the next Z value is found by the rather formulaic equation:

```
Z:= (1+A*(2+cos(2*real(Z)*PI-O))*2+O*(2+cos(2*PI-N))
```

Not to worry though, this equation can be simplified in Basic as:

```
CODE
  vchrcas=ccsr
  Sscale=X:Yscale=Y
  newx=0: newy=0
  for i=0 to 1000
    Z=Zcos+Y: Sscale*Y
    newx=2+cos(2*real(Z)*PI-O)
    Zbar=Z: Yscale*X
    newy=2+cos(2*PI-N)
  next i
  for i=0 to 320
    newx=320+newx: Xscale: Yscale
    newy=320+newy: Yscale: Xscale
  next i
  for i=0 to 320
    newx=320+newx: Xscale: Yscale
    newy=320+newy: Yscale: Xscale
  next i
  for i=0 to 320
    newx=320+newx: Xscale: Yscale
    newy=320+newy: Yscale: Xscale
  next i
```

What gets plotted is $(320+X*Xscale, 200+Y*Yscale)$. The scale factors need to be computed for each set of display values. There are 12 data lines of values near the end of the program for you to experiment with. You can change L through G or just N. If you change N, however, it usually must increase or decrease by multiples of 2. We'll go over this equation in more detail when I discuss the listing.

The other equation is a completely different approach to Chaos. It's from an article by James Yorke entitled "Quasiperiodicity versus Chaos" given in 1984 when this was written. Chaos was an item of interest. In this program 16 constants are initially selected and then three random constants (L, W1, and W2) are used to create different displays. The formula uses a modified Fourier series to sum the initial random X and Y values to produce a new X, new Y. The program for this is:

```
CODE
  C1=61752512701268211 + A11*52512701268211 + A12*52512712-94213: -
  A14*52512712-94213:
  C2=3352517*91268211 + A22*52512701268211 + A23*52512712-94213: -
  A24*52512712-94213:
  W1=0: W2=0: W3=0: MOD 1
  newx=0: newy=0: newz=0
  for i=0 to 1000
    newx=0: newy=0: newz=0
  next i
```

The A and B variables are predefined in the program, PP is $2*PI$ and E, W1, and W2 are the three variables that produce the display. MOD means to divide and use the remainder, so MOD 1 means the whole number portion and uses only the decimal. The points actually plotted are $(639*X, 359*Y)$. There are twelve Chaos data lines at the end of the listing.

When you start the program, CHAOS, there is a reminder of what the hot keys are. Using the RMB you'll see that there are two groups of displays, Symmetry and Chaos. You can switch at any time to any menu item. Each drawing starts with its own palette but you can press Δ through F10 to change palettes. And, at any time, you can press the up-arrow key to cycle the palette colors except for the background color.

HOW TO COLOR

A key question was how to color the display. Using the distance from a fixed point produced in a particular color and changing color every 255 colors produced real chaos. I finally decided to color a point depending on how many times it's been PSET. This requires an array for each pixel on the screen—all 639*359 of them! Every time a point on the screen is set the same location in the array is increased by 1. The value in the array is used to look up the corresponding value in COLORSCALE, an array of colors. If a point has been set 102 times, the 102nd value in COLORSCALE is 5, so that color is used to PSET that point. The maximum number of times a point is set is 255. While this doesn't seem like very many times, it takes quite a while for the entire display to become colorful. By the way, some pixel colors with very low counts so it may look like a blank screen, but don't worry, they're on their way. I would let each display run for at least 10 minutes or more to get the full effect let each display run for about an hour. While the picture is drawing try all the palettes and color cycle each. Oh, the names for the displays are entirely my own and reflect the author's opinion.

Now let's look at the program, Listing 1. Notice that my include files are in quotes. All the variables for both halves of the listing, Symmetry and Chaos, are equated or listed. The actual A and B values for Chaos are shown but the B values are multiplied by PP(2*PI) before storing them at the end of the program. Look at the P1 and P2 formulas again and you'll see why that's such a joke. After opening a 640*400 screen and window, the listsize and a 639*359 array the program reminds you of the hot keys and waits for a menu selection. Notice that for the Symmetry portion variable V1 is stored in a5 since it's followed by all the Symmetry variables. In Chaos variable V2 is stored in a5. The starting X and Y location can be changed for either program but will eventually produce the same pattern but not necessarily in the same order. You'll notice that some of the patterns have a few data areas that never get set again. This is because most Chaos equations take up to 100 iterations before they finally settle down to a pattern. Rather than just compute 100 blank points, I wait ahead and PSET all of them.

CONVERTED is used by both programs to convert the variables to double-precision numbers. Since XSCALE and YSCALE for Chaos are always 639 and 359, their decimal values have been precomputed and stored in the V2 variable array. Also, E goes divided by PP before it's value is saved since that would have to be done twice during every newX and newY computation. And, X and Y are also multiplied by PP but at the start of each computation rather than doing that eight different times during the computations.

After newX and newY coordinates have been computed the color is looked up and that location is PSET. Then a menu check is made to see if you want to change palettes, color cycle, pick a new menu item, or quit. If you choose a new item the program first checks what menu it's in and then branches to the menu check for that menu. To color cycle, all palettes go into a general location called COLORTABLE as you use them. When you press the up-arrow key color is stored in c3 then each color value decreases by 1; at the end, color1 is reset as color3.

SYMMETRY

Now let's discuss the actual computations in each program. Both free the memory array first since there may be values in there from a previous display. This is immediately followed by a new array call. This seemed easier and quicker than clearing the entire array to 0. When you start either program, fp7 contains the initial X location, fp8 contains the initial Y location, a5 is the variable array address, and the COLORSCALE address, and a7 the COLORS array address.

Programming the Amiga in Assembly Language

In Symmetry, X is moved to fp0 and Y moved to fp2. Each is multiplied by itself, added together and stored in fp2 as ZBAR (X*X+Y*Y). X is then moved to fp5 as ZREAL and Y to fp4 as ZIMAG. You can already begin to see the advantage of having eight more registers and the ability to perform any operation on any combination of registers. Also, having eight registers lets us leave some often used values in a register rather than calling them each time they're used.

The degree of rotation (R) is stored in d0 as a counter. Next, Y and ZIMAG are multiplied, X and ZREAL multiplied, subtracted from the previous operation and saved in fp3 as ZA. Then X and ZIMAG are multiplied, Y and ZREAL are multiplied replacing the old ZREAL and ZIMAG. fp5 is saved as the new ZIMAG and ZA as the new ZREAL. This repeats until d0 decreases to below 0.

Now multiply Y times ZIMAG, X times ZREAL, and subtract them. Multiply this by variable B using its local address B(a5); multiply ZZBAR (in fp2) by A using A(a5) and finally, add 1(a5). This is the temporary value P in fp3. To get the new X location, multiply G times ZREAL, O times Y, and subtract; then add P times X. fp5 now contains the new X coordinate. At this point, fp0 contains G, fp2 contains O, and fp3 contains P. We can then directly multiply O times X, G times ZREAL, and P times Y. fp6 will contain the new Y and then move fp5 to fp7 as the new X, by planning ahead, all the variables can be used at most of the registers at least once.

To compute the points that will be plotted, multiply X by XSCALE and store the result in ACROSS, adding 120 to center it. Multiply Y by YSCALE and store the result in both d0 and DOWN adding 200 to center it. The color to be used is in the 640x400 array COLORS (a: a7). Multiply the lower location (r: d0) by 640 and add ACROSS. Add this distance to the value in a4 and r are the contents of that location in COUNT - MOVE.B(B(a5),DELI,COUNT). Add 1 to COUNT; if the result is 0, we've

already set the point 255 times so skip directly to computing the next point. If it's not 0, replace the increased COUNT back in the array - MOVE.B(COUNT,DELI,COUNT). Now get the COLOR value from the COLORSCALE array in a4 - MOVE.B(0(A4,COUNT),D0). Remember that COUNT was equated to register d4 back at the beginning of the program. Use the color value in d0 to PSET the point.

This is followed by a message check. Since one of my DUMP flags was RAWKEY, the routine looks to see if you have pressed F1 through F10 (in key #33 - #42) or the up-arrow (#4C). If you have, the program installs a new palette and continues drawing or cycles the colors by 1. RAWKEY values are different from HANDLEKEY values. While the later is usually the ASCII value for a character, RAWKEY values are based more on that key's placement and location on the keyboard, using RAWKEY lets you test for any key or combination of keys as "hot keys". When you choose a menu, the program goes all the way back to HANDLE_MENU or HANDLE_MENU1, you can't do anything the display keeps drawing.

CHAOS

The Chaos program initially trues, then resets the COLORS array, gets XSTART in fp7, YSTART in fp6, P in fp5, and #1 in fp2. The array locations are V2 in a5, COLORSCALE in a4, and COUNTS in a7. Then P is moved to fp0, divided by PP, and stored back in P. This is because the Chaos formulas both use a times a value divided PP. After clearing the screen the actual computations begin.

First, multiply X and Y by PP and save their product in fp9 (PPX) and fp3 (PPY). Move PPX to fp1 and add B11(a5). Remember that B11 has already been multiplied by PP. Get the sine of this value and then multiply by A11(a5); keep this result (A11*SIN(C1(X+B11))) in fp1. Now, add PPX and B12, get the sine, multiply by A12, and add this to the

TABLE I FP Commands

SINGLE REGISTER

FABS - absolute value
 FACOS - arc cosine
 FASIN - arc sine
 FATAN - arc tangent
 FATANH - arc tangent hyperbolic
 FCOS - cosine
 FCOSH - cosine hyperbolic
 FETOX - E to the X power
 FETOXM1 - E to the X-1 power
 FGETEXP - get exponent
 FGETMAN - get mantissa
 FINT - integer value
 FLOG10 - log, base 10
 FLOG2 - log, base 2
 FLOGN - log, base E
 FLOGNP1 - log, base E of X+1
 FNEG - negate
 PSIN - sine

PSINH - sine hyperbolic
 PSQRT - square root
 FTAN - tangent
 FTANH - tangent hyperbolic
 FTENTOX - 10 to the X power
 FTWOTOX - 2 to the X power

MULTIPLE REGISTERS

FADD - add registers
 FCMP - compare registers
 FDIV - divide registers
 FMOD - modulo remainder
 FMUL - multiply registers
 FSUB - subtract registers

SPECIAL COMMANDS

FBcx - branch conditionally
 FDBcx - decrease register, branch
 FMOVE - move data
 FNOP - no operation
 FScx - set according to condition
 PSINCO - get both sine and cosine
 FTST - test for 0, positive, or negative

Programming the Amiga in Assembly Language

```

b73  eqv  152
b21  eqv  100

```

```

;allib equ.d  .26813663648754
;allib equ.d  .9135949955700
;allib equ.d  .31170926392753
;allib equ.d  .0909977635476
;allib equ.d  .89540094298116
;allib equ.d  .53440041809951
;allib equ.d  .94909477629078
;allib equ.d  .23390185508507
;allib equ.d  .03818611571512
;allib equ.d  .5550305990449
;allib equ.d  .13299543212399
;allib equ.d  .90198881978116
;allib equ.d  .49010722869509
;allib equ.d  .33630899012358
;allib equ.d  .29804907733971
;allib equ.d  .15616467277777

```

```

;macro
gfxlib macro      ; (rounding)
    move.l  #0,sp(0),a0
    inc     v1(a0)
endm

```

```

;proc macro
    move.l  sp(0),a1
    move.w  aa(0),d0
    move.w  #300,d1
    sub.w   #down,d1
    gfxlib  writepixel
endm

```

```

;colormacro
    move.l  v1(a0),a1
    gfxlib  setcolor
endm

```

```

;palette macro
    move.w  sp(0),a0 ; (color table)
    lea    v1(sp),a1
    moveq   #15,d0
    gfxlib  loadrgbld
endm

```

```

;newpalette macro ; (color table)
    lea    v1(sp),a1
    lea    colortab(a0),a0
    move.w  #7,d0 ; # long word values
endm

```

```

;proc
    move.l  (a1)-(a5)+
    move.w  d0,aa(a0)
    write.le colorable ; use the new palette
endm

```

```

;plot macro
    moveq   #0,d1
    move.l  sp(0),a1
    gfxlib  setcolor
endm

```

```

;getnt macro ; (x,y,d0),reg,length
    move.l  sp(0),a1
    move.w  #1,d0

```

```

    move.w  #0,d1
    gfxlib  move
    moveq   #1,d0
    callr
    move.w  sp(0),a1
    lea    v1(sp),a0
    moveq   #15,d0
    gfxlib  text
endm

```

```

main:
    move.l  sp,stack
open file:
    openlib int,done
    openlib gfx,close_int
    openlib opr,ht,close_int
set_up:

```

```

make_screen:
    openmacro  system,close_lib
    openmacro  window,close_screen
    openmacro  menu0
    move.l  sp(0),a1
    move.l  #1,d0
    gfxlib  setcolor
endmacro

```

```

;macro
    array  #0,aa,close_window
    qword  100,100,2,11,reg,7
    qword  100,200,2,6,reg,20
    qword  100,250,1,drawsg,25
    reg     #0
    qword  #0,check
    qword  #0,check,d2
    beg     check_menus
    lea     #0,check
endmacro

```

```

;check_menus
    move.w  #0,aa(0) ; #0-menu,4,d1-item
    sub.w   #0
    beg     handle_menu0 ; geometry
    move.w  #1,d0
    and     handle_menu1 ; check
    lea     #0,check
endmacro

```

```

;write menu0
    move.w  #0,d1
    beg     do_data0
    move.w  #1,d1
    beg     do_data1
    move.w  #2,d1
    and     do_data2
    move.w  #3,d1
    and     do_data3
    move.w  #4,d1
    beg     do_data4
    move.w  #5,d1
    beg     do_data5
    move.w  #6,d1
    beg     do_data6
    move.w  #7,d1
    beg     do_data7
    move.w  #8,d1
    beg     do_data8

```

Programming the Amiga in Assembly Language

```

copy.w  a0,d1
lea     d0,data0
copy.w  #10,d1
lea     d0,data0
copy.w  #11,d1
lea     d0,data0
copy.w  #12,d1
lea     d0,data0
brs     end_check

do_data1      ;square
move.w  # color0,d0
lea     data0(pc),d1
brs     get_values

do_data2      ;rhombus
move.w  # color0,d0
lea     data0(pc),d1
brs     get_values

do_data3      ;rectangle
move.w  # color0,d0
lea     data0(pc),d1
brs     get_values

do_data4      ;triangle
move.w  # color0,d0
lea     data0(pc),d1
brs     get_values

do_data5      ;diamond
move.w  # color0,d0
lea     data0(pc),d1
brs     get_values

do_data6      ;circle
move.w  # color0,d0
lea     data0(pc),d1
brs     get_values

do_data7      ;pentagon
move.w  # color0,d0
lea     data0(pc),d1
brs     get_values

do_data8      ;square
move.w  # color0,d0
lea     data0(pc),d1
brs     get_values

do_data9      ;three field
move.w  # color0,d0
lea     data0(pc),d1
brs     get_values

do_data10     ;ring
move.w  # color0,d0
lea     data0(pc),d1
brs     get_values

do_data11     ;circle
move.w  # color0,d0
lea     data0(pc),d1
brs     get_values

end_vision:
lea     d0,data0
move.w  #color0,d0
move.w  #0,d1

```

```

move.w  a0,a0
lea     d0,data0
move.w  #0,d1

do_data1      ;square
move.w  # color0,d0
lea     data0(pc),d1
brs     get_values

do_data2      ;rhombus
move.w  # color0,d0
lea     data0(pc),d1
brs     get_values

do_data3      ;rectangle
move.w  # color0,d0
lea     data0(pc),d1
brs     get_values

do_data4      ;triangle
move.w  # color0,d0
lea     data0(pc),d1
brs     get_values

do_data5      ;diamond
move.w  # color0,d0
lea     data0(pc),d1
brs     get_values

do_data6      ;circle
move.w  # color0,d0
lea     data0(pc),d1
brs     get_values

do_data7      ;pentagon
move.w  # color0,d0
lea     data0(pc),d1
brs     get_values

do_data8      ;square
move.w  # color0,d0
lea     data0(pc),d1
brs     get_values

do_data9      ;three field
move.w  # color0,d0
lea     data0(pc),d1
brs     get_values

do_data10     ;ring
move.w  # color0,d0
lea     data0(pc),d1
brs     get_values

do_data11     ;circle
move.w  # color0,d0
lea     data0(pc),d1
brs     get_values

end_vision:
lea     d0,data0
move.w  #color0,d0
move.w  #0,d1

```

```

lea     d0,d0      ;clear previous values
move.w  #0,d0,d1  ;start new
move.w  #0,d0,d1  ;start
move.w  #color0,d0
lea     data0(pc),d1
brs     get_values

do_data1      ;square
move.w  # color0,d0
lea     data0(pc),d1
brs     get_values

do_data2      ;rhombus
move.w  # color0,d0
lea     data0(pc),d1
brs     get_values

do_data3      ;rectangle
move.w  # color0,d0
lea     data0(pc),d1
brs     get_values

do_data4      ;triangle
move.w  # color0,d0
lea     data0(pc),d1
brs     get_values

do_data5      ;diamond
move.w  # color0,d0
lea     data0(pc),d1
brs     get_values

do_data6      ;circle
move.w  # color0,d0
lea     data0(pc),d1
brs     get_values

do_data7      ;pentagon
move.w  # color0,d0
lea     data0(pc),d1
brs     get_values

do_data8      ;square
move.w  # color0,d0
lea     data0(pc),d1
brs     get_values

do_data9      ;three field
move.w  # color0,d0
lea     data0(pc),d1
brs     get_values

do_data10     ;ring
move.w  # color0,d0
lea     data0(pc),d1
brs     get_values

do_data11     ;circle
move.w  # color0,d0
lea     data0(pc),d1
brs     get_values

end_vision:
lea     d0,data0
move.w  #color0,d0
move.w  #0,d1

```

Programming the Amiga in Assembly Language

<pre> cmovl.w r9,d1 org db chbase9 movl.w #10,d1 movl db_chbase10 movl.w #11,d1 movl db_chbase11 cmovl.w r12,d1 hrr quit orr msg_chbase </pre> <pre> db_chbase0 ;read done newpalette colortable2 lex chbase3(pcl,a0) orr get_values1 </pre> <pre> db_chbase7 ;save frame newpalette colortable2 lex chbase4(pcl,a0) hrr get_values1 </pre> <pre> db_chbase8 ;write newpalette colortable1 lex chbase2(pcl,a0) orr get_values1 </pre> <pre> db_chbase1 ;parent wait newpalette colortable0 lex chbase3(pcl,a0) hrr get_values1 </pre> <pre> db_chbase4 ;diagon cell newpalette colortable1 lex chbase3(pcl,a0) hrr get_values1 </pre> <pre> db_chbase6 ;bottom floor newpalette colortable6 lex chbase3(pcl,a0) hrr get_values1 </pre> <pre> db_chbase5 ;room newpalette colortable7 lex chbase3(pcl,a0) hrr get_values1 </pre> <pre> db_chbase7 ;third or a scanner newpalette colortable5 lex chbase3(pcl,a0) orr get_values1 </pre> <pre> db_chbase8 ;swinging floors newpalette colortable8 lex chbase3(pcl,a0) hrr get_values1 </pre> <pre> db_chbase9 ;banked wire newpalette colortable1 lex chbase3(pcl,a0) hrr get_values1 </pre> <pre> db_chbase10 ;corridor newpalette colortable0 lex chbase10(pcl,a0) hrr get_values1 </pre> <pre> db_chbase11 ;profile newpalette colortable0 lex chbase11(pcl,a0) </pre> <pre> get_values1: orr convertdp moveq a0 </pre>	<pre> moveq #5,a0 hrr convertdp moveq wide moveq a1,a0 hrr convertdp moveq w2,a0 free colbase ar.lay colbase.close_window fmove.d f124741224,fp0 ;start x fmove.d f124741224,fp4 ;start y fmove.d f124741224,fp8 ;start z fmove.l #1,fp2 lex colbase.colbase moveq colbase(pcl,a0) fmove.d a165,fp0 fdir.lx f0,fp0 fmove.d fp0,a16 ; ;start z*fp1 hrr convertdp </pre> <pre> convertdp moveq.l #0,d0 moveq.l #0,d1 moveq.l #0,d2 moveq #0,d3 sub.l a2,a2 ;padding in dest cmovl.b 1,fp0,fp1 ;negative ? hrr.a positive cmovl #1,fp1 ;not negative sign bit subq #1,fp1 ;next ? positive getdigit moveq.b a25,fp0 ;decimal ? cmovl.b #1,fp0,fp1 ;decimal ? hrr.a handoffb moveq.w #1,a2 ;decimal flag moveq #0,d7 hrr.a getdigit </pre> <pre> fdir.digit cmpl.b #5,fp0 hl.l zerocheck cmpl.b #0,fp0 hl.l zerocheck and.l #3,fp0 moveq a1,d2 moveq a1,d3 cmovl #1,d0 cmovl #1,d1 cmovl #1,d2 cmovl #1,d3 cmovl #1,d4 cmovl #1,d5 cmovl #1,d6 cmovl #1,d7 moveq.l #0,d8 cmovl #0,d1 ;00 = 00 * 10 </pre>
---	--

Programming the Amiga in Assembly Language

```

add.l   d5,d1
addx.l  d6,d0    ;00 = 00 * 10 = 000
addq.w  d1,d7
movi.w  f16,d7    ;get up to 10 digits
mov.s   qntadigit

scratch
movw.l  d0,d4
lsl.l   d1
lsl.l   '4
lsl.l   d0
beq.s   @p_done

;
move.l  f$415,d5 ;maximum exponent
;
stopy.l r1,d6
cal.l   r1,d7
cost.l  r1,d0
bcv.s   r3
moveq.l #11,d5    ;2 times to shift
shiftdown
lsl.l   r1,d0
rotr.l  r1,d1
dbra   d5,shiftdown
swp    d6    ;exponent to high bits
cal.l   r1,d6
or.l    d6,d8
caga   #0,d7    ;any decimal
beq.s   @p_sign
subq.l  r1,d7    ;any more digits?
lml.s   @p_sign

fractionalize
move.l  f$0240000,d2
moveq.l #0,d1    ;10dp
movw.l  dmanabase(r0),d6
j&     F4(a5)    ;dpdtrv
db.v   d7,fractionalize

@p_sign
or.l    d1,d0

@p_done
moveq.l #0,d6    ;optional UK check
rta

;integer program
calc(rnd)
move.x  fp7,fp0    ;x
move.x  fp6,fp2    ;y
fmul.x  fp6,fp0    ;x * x
smul.x  fp2,fp2    ;y * y
tadd.x  fp0,fp2    ;x^2+y^2

move.x  fp7,fp5    ;x > zero
fmov.x  fp6,fp1    ;y > imaginary
move.l  @fp0,d0

iterate
fmov.x  fp6,fp0    ;y
fmul.x  fp4,fp0    ;y * x
fmov.x  fp7,fp1    ;x
fmul.x  fp5,fp1    ;x * x
fsub.x  fp0,fp1    ;(x * x) - (y * y)

```

```

fmov.x  fp7,fp3    ;x^2
fmul.x  fp7,fp4    ;x * z
fmul.x  fp6,fp5    ;y * z
fadd.x  fp5,fp4    ;new imaginary
fmov.x  fp1,fp0    ;new real
dbf.s   d0,iterate

@p1
fmov   r1(x * x), r2(y * y) + 0 = (x * x) + y
fmovw.l  fp6,fp0    ;y
fmul.x  fp7,fp0    ;y * z
fmovw.l  fp7,fp1    ;x
fmul.x  fp5,fp1    ;x * z
fsub.x  fp0,fp1    ;(x * x) - (y * z)
fmul.d  b(a0),fp1
fmul.d  @a0,fp2
radd.x  fp2,r0    ;(x * x) + b((x * x) - (y *
@p1)
fmovw.l  f(a5),fp3
fmovs.x  fp1,fp7    ;y

get_new_x    ;(y * x) - (x * y) + (x * x)
fmovw.d  g(a5),fp0    ;z
fmul.x  fp5,fp5    ;z * z
fmovw.x  fp0,fp1    ;y
fmovw.c  d(a5),r02    ;b
fmul.x  fp2,fp1    ;z * y
fsub.x  fp1,fp5    ;(y * x) - (x * y)
fmovw.x  fp7,fp0    ;x
fmul.x  fp2,fp1    ;x * y
fadd.x  fp1,fp5    ;newx

get_new_y    ;(x * x) - (y * y) + (y * y)
fmul.x  fp2,fp7    ;x * x
fmovw.x  fp0,r04    ;z
fmovw.x  fp2,fp5    ;z * y
radd.x  fp2,r03    ;(x * x) + (y * y)
fsub.x  fp7,fp5    ;newy
fmovw.x  fp5,fp7    ;newz

@pint1
fmovw.d  xscale(a5),fp0 ;yscale
fmul.x  fp7,fp0    ;x * xscale
fmovw.l  fp0,r03    ;int(x * xscale)
addi.l  #375,r03    ;ray area

@pout1
fmovw.d  yscale(a5),fp0 ;yscale
fmul.x  fp6,fp0    ;y * yscale
fmovw.l  fp0,d0    ;int(y * yscale)
addi.l  #375,d0
move.l  d0,r03

nlls   #610,d0
add.l  across,d0
moveq  #0,count
move.b  @a0,(d0+),count
stopy  #1,count
beq.s   mag_done

@p10-1
moveq  count,(a5+0,1)

```


Programming the Amiga in Assembly Language

```

movew.l #0,d0
movew.l #404,colortbl.d0
or and
xor
mov ahead
lrl #0,l0,r1
orpi.l #memupick,d5
beq check_memory
trtlr 0,
nop continue1
and.l #0111,d5
neg.w #50,d5 ;palette01
beq.s del_palette1
movew #81,d5
beq.s del_palette2
movew #52,d5
orq del_palette3
movew #82,d5
neg del_palette4
orpi.w #51,d5
beq del_palette5
movew #55,d5
orq del_palette6
orpi.w #56,d5
orq del_palette7
orpi.w #57,d5
neg del_palette8
orpi.w #58,d5
beq del_palette9
orpi.w #50,d5
beq del_palette9
movew #56,d5
beq color_palette1
nop continue1
del_palette1
;palette colorizable1
bra . ;continue1
del_palette2
;palette color ab1A3
bra . ;continue1
del_palette3
;palette colorizable3
bra . ;continue1
del_palette4
;palette colorizable4
bra . ;continue1
del_palette5
;palette color ab1A5
bra . ;continue1
del_palette6
;palette colorizable6
bra . ;continue1
del_palette7
;palette colorizable7
nop ;continue1
del_palette8
;palette color ab1A8
bra . ;continue1
del_palette9
;palette colorizable9

```

```

bra . ;continue1
del_palette1
;palette colorizable1
orq del_palette1
movew #0,d0
movew #1,d0
movew #1,d0 ;if 0-14 changed
cont1
movew #0,d0,d5,d1 ;palette up 20
;del.w #0,d1 ;next, color
;del.w #0,d0,d0
movew #2,d0,d0 ;row + 15
unrolled1
selecte del_palette1
nop ;continue1
end ;cont1
;del_palette1
del.w #0
beq handle_palette
movew #1,d0
beq handle_palette
nop ;continue1
;palette up 20
cont100
movex #1,d0 ;d0
movex #1,5,d0 ;x + 20
movex #0,7,5 ;d0
movex #5,d0 ;y + 20
palette2
movex #0,d0 ;ppx
movew #1,d0,d0 ;ppp = B1
movew #0,d0 ;ppp = B1
movex #1,d0,d0 ;ppx + a + ppp = B11
movew #5,d0 ;ppp
movex #2,d0,d0 ;ppp = B2
movex #1,d0 ;ppp = B21
movex #10+5,d0 ;y12 + a + ppp = B22
;add.w #1,d0,d0
movex #1,d0 ;ppx
;add.w #1,d0,d0 ;ppp + ppp
movex #0,d0,d0 ;ppp + ppp = B11
movex #0,d0,d0 ;ppp + a + ppp = B11
movex #1,d0,d0 ;ppp
movex #2,d0,d0 ;ppp
movex #1,d0,d0 ;ppp = B1
movex #1,d0,d0 ;ppp = B11
movex #0,d0 ;ppp = B11
movex #1,d0 ;ppp = B111
movex #1,d0 ;ppp = B111
movex #1,d0 ;ppp = B111
movex #1,d0 ;ppp = B111
movex #1,d0 ;ppp = B111
movex #1,d0 ;ppp = B111
movex #1,d0 ;ppp = B111
movex #1,d0 ;ppp = B111
movex #1,d0 ;ppp = B111
movex #1,d0 ;ppp = B111
movex #1,d0 ;ppp = B111

```


Programming the Amiga in Assembly Language

```

dc.w $000,$000,$000,$000
even
colortab a3
dc.w $000,$000,$000,$000
dc.w $000,$000,$000,$000
dc.w $010,$000,$000,$000
dc.w $020,$000,$000,$000
even
colortab104
dc.w $020,$000,$000,$000
dc.w $080,$000,$000,$000
dc.w $100,$000,$000,$000
dc.w $150,$000,$000,$000
even
colortab105
dc.w $000,$000,$000,$000
dc.w $000,$000,$000,$000
dc.w $040,$000,$000,$000
dc.w $080,$000,$000,$000
even
colortab106
dc.w $000,$000,$000,$000
dc.w $000,$000,$000,$000
dc.w $040,$000,$000,$000
dc.w $080,$000,$000,$000
even
colortab107
dc.w $000,$000,$000,$000
dc.w $000,$000,$000,$000
dc.w $040,$000,$000,$000
dc.w $080,$000,$000,$000
even
colortab108
dc.w $000,$000,$000,$000
dc.w $040,$000,$000,$000
dc.w $080,$000,$000,$000
dc.w $0C0,$000,$000,$000
even
colortab109
dc.w $000,$000,$000,$000
dc.w $040,$000,$000,$000
dc.w $080,$000,$000,$000
dc.w $0C0,$000,$000,$000
even
colortab110
dc.w $000,$000,$000,$000
dc.w $040,$000,$000,$000
dc.w $080,$000,$000,$000
dc.w $0C0,$000,$000,$000
even
colorscale
dcb.b 0,0
dcb.b 1,1
dcb.b 2,2
dcb.b 3,3
dcb.b 4,4
dcb.b 5,5

```

```

dcb.b 6,6
dcb.b 7,7
dcb.b 8,8
dcb.b 9,9
dcb.b 10,10
dcb.b 11,11
dcb.b 12,12
dcb.b 13,13
dcb.b 14,14
dcb.b 15,15
even
table
makelabel mem0, 'Secondary', mem0, 1, 1
makelabel mem1, 'Primary', mem1, 1, 0, $00
makelabel mem2, 'Printer', mem2, 0, 0, $00, 0, 0, $00, 0, 0
makelabel mem3, 'Mouse', mem3, 0, 0, $00
file1 mem0, mem1, 20, 55, 9000
makelabel mem4, 'Stained
Glass', mem4, 0, 50, $000
makelabel mem5, 'Ornament', mem5, 10, 55, $00
makelabel mem6, 'Marble', mem6, 50, 55, $00
makelabel mem7, 'Crystal
Ball', mem7, 60, 55, $00
makelabel
mem8, 0, 0, $00, 0, 0, $00, 0, 0, $00
makelabel mem9, 'Crystal', mem9, 0, 0, $00, 0, 0, $00
makelabel mem10, 'Three
Fold', mem10, 0, 0, $00, $00
makelabel
mem11, 0, 0, $00, $00, $00
makelabel mem12, 'Star',
mem12, 10, 55, $00
makelabel mem13, 'COTD', mem13, 0, 100, 50
even
makelabel mem14, 'Glass', mem14, 100, 0
makelabel mem15, 'Sand
Dune', mem15, 0, 50, $00
makelabel mem16, 'Lava
Flow', mem16, 10, 50, $00
makelabel mem17, 'Snow', mem17, 10, 50, $00
makelabel mem18, 'Snow
Wall', mem18, 10, 50, $00
makelabel mem19, 'Iceberg',
mem19, 10, 50, $00
makelabel mem20, 'Ocean
Trailer', mem20, 10, 50, $00
makelabel mem21, 'Ocean
Floor', mem21, 10, 50, $00
makelabel mem22, 'Green', mem22, 0, 50, $00
makelabel mem23, 'Green at a
Distance', mem23, 0, 50, $00
makelabel mem24, 'Swirling
Flowers', mem24, 0, 50, $00
makelabel mem25, 'Starbed
Dune', mem25, 0, 50, $00, $00
even
mem26, 0, 0, $00, 0, 0, $00, 0, 0, $00
makelabel mem27, 'COTD', mem27, 0, 100, 50
makelabel mem28, 'COTD', mem28, 0, 100, 50

```


A Guide to AmigaDOS Shared Libraries

By Daniel Stenberg

The examples of this article are written in assembler and C and require some knowledge of the languages to fully understand what they are all about. They are written only to illustrate the explanations and are only parts of larger source codes. They may not be accurate and I take no responsibility for the correctness or function of the examples.

Shared Library Overview

To be able to learn how to make a shared library, it's important to have the knowledge about what it is all about. In this article I'll take you through all steps, from the most basic ones down to the ones dealing with low level library programming.

Shared Library

First, an answer to the question, what is a shared library? As the name says, it is a function library shared by several simultaneous tasks and processes. The shared library code is not present in the executable image on disk, but in a separate file. The shared code is not loaded together with the executable. It is loaded into memory only when a program requires it.

On Amiga, the naming convention says that a shared library should be in lowercase letters with a ".library" ending, and the directory to put them in is "LIBS".

Link Library

A link library is used to be mixed up with a shared library. A link library is a function library that is linked into the executable at compile time. A link library becomes a part of an executable image.

ROM Based/Disk Based Libraries

The AmigaDOS system consists of several shared libraries, whose names you recognize: dos.library, exec.library, graphics.library, only to mention a few. These libraries won't be found in the LIBS directory, they reside in ROM. Whether in ROM or on disk, shared libraries work and are used the same way.

Memory Usage

As mentioned, shared libraries are loaded when a program requests, i.e. opens, it. When the program has finished using the library, it closes the library. The library remains in memory even though its process is using it, until the operating system requires the memory it occupies or is forced to remove itself by a program, such as "aval" or "EXIT" on the shell prompt in AmigaDOS 2.0 or later.

Other Operating Systems

Shared libraries are not AmigaDOS specific. Such are also found under UNIX and OS/2, only to mention the most obvious and common.

Advantages

The reasons why so many systems are using shared libraries are among others: less disk space is used because the shared library code is not included in the executable programs, less memory is used because the shared library code is only loaded once, load time may be reduced because the shared library code may already be in memory when a program starts it, and that programs using shared libraries are very easily updated.

Calling Shared Library Functions

We've been looking at what a shared library is, a little about how it works, and some of its advantages. Now it's time to see how a library is used and accessed.

Address Library Functions

To be able to handle library calls, we must know how to address library functions. To describe it to a small computer is to describe non-shared functions. The most significant difference is in the way the functions are addressed. A standard function calling program is aware of the address to which the program wants to get when we want to jump to it. A shared library function is on the other hand addressed by adding a number to the address of the library's base.

When using standard function calls, the compiler or assembler arrange so that e.g. the function "getname" is associated with the particular static address in memory where the "getname" function starts. If the same "getname" function would be a shared library function, the compiler wouldn't know the actual address of it, but dynamically add a certain number (index) to the library's base address to access it.

As you see, we must know the index of the function and the library base address to be able to call a shared library function.

Library Base

To find out the library base of a shared library, you must call `OpenLibrary()` which will return the library base of the specified library in register `D0`. All library bases are found like that except `exec.library's`, which is found by reading the pointer stored at the absolute address 4.

Index

Whenever you want to call a function in a shared library you (or the compiler) have to know the index to add to the library's base address.

E.g. to call `OpenLibrary()` you must know the index of the function and the library base itself (`OpenLibrary()` is an `exec.library` function and we know that `exec.library's` base address is found at address 4). A call to `OpenLibrary()` could look like this in assembly:

```
MOVE.L
R0,R0
; R0base is the base of
; the library (exec.library)
; see Parameters left out in this example <<<
;04
;02100
; R0R1 to point out into R0
; Value at the current index. The index
; is +756 in this case
```

Parameters

OK, we know how to call a library function and we know that we must call `OpenLibrary()` to get a library's base address. To find out `OpenLibrary()` which library we want to open, we must send it some parameters. The documentation tells us that `OpenLibrary()` wants the library name in `D0` and the lowest acceptable version in `D1`. Parameters to the library functions are always stored in registers. See the library reference documentation for closer information exactly which registers.

This example opens a library with the name `an.libName` with version 31 or higher:

```
MOVE.L #an.libName,D0
; Load name parameter
MOVE.L #31,D1
; Load function index
PUSHM0
;04
;02100
; R0base is
; the library base
;04
;02100
; R0base, D1
; Lowest usable version
;04
;02100
; R0base, D1
; OpenLibrary()
; R0base, D1, D0
```

Libraries

The operating system provides facilities for the creation, use and access of shared libraries. The functions that let the programmer consult and access libraries are of different levels to give different possibilities. Low level function where you can change every single parameter and more high level functions that do a lot without the programmer exact specification.

I'll describe the functions of the highest level that also are the most frequently used:

`OpenLibrary()` Grants access to a named library of a given version number.

Always open libraries with the lowest version which includes the functions you need. To open inclusion library for 2.1+ (version 36) only, try something like:

```
; Load exec.library
; Address D0, version 36
; D0 = 2, D1 = 36
; exec.library's base address is found at 4
; R0 = 0, D1 = 36
;
; The System should be in order to allow this.
; If it is not, startup screen will do this for you.
;
; This is how to call IncludeLib()
OpenLibrary("include.lib", 36)
; R0 = include.lib's
; R0 = include.lib's open definition version 36 in D0, version 36
; R0 = 0
;
; The name using definition.library 36 - follows here!
```

AmigaDOS file names are not case sensitive, but two lists are. 1. The library name is specified in a different case than it exists on disk, unexpected results may occur.

A Guide to AmigaDOS Shared Libraries

CloseLibrary() Concludes access to a library. Whenever your program has finished using the functions of a shared library, there should be a call to **CloseLibrary()** for every call to **OpenLibrary()**. Simply like this:

```
CloseLibrary (currentLibrary *);
```

ReadLibrary() Calls the **Expunged()** function of the specified library. If the library isn't open, it will delete itself from memory. This is not typically called by user code.

```
/* Example: to Close the shared library open at library.c */
#include <exec/types.h>
#include <exec/errno.h>
void ReadLibrary (OS2323name)
{
    currentLibrary *result;
    result = ReadLibrary ("");
    if (result != currentLibrary) * (void *) 0; /* success - do not return */
    return (result);
}

```

With these three functions in mind, we'll continue.

Return Code

The return code of a shared library function call is always received in a register. (Today, I don't think there is a single function not using DL for that purpose.)

Glue Code

The parameter storage in registers is not that comfortable in all occasions and some compilers (in all kinds of programming languages) don't even have the ability to store parameters in (pre-defined) registers. Then, glue code is required. Glue code (also known as "stub functions" or simply "stubs") is simply a set of functions that you get, call instead of the shared library functions. The stub function reads the parameters from the stack and stores them in registers and then calls the shared library function. That makes the use of the glue code functions identical to other functions. Glue code is compiled into a kind of object file, using the suffix ".lib", and is stored in LIB; (not to be confused with LIBS, where the shared libraries are stored). All stub functions for the standard AmigaDOS libraries are found in the "amiga.lib" file that comes with most compilers.

C and Register Parameters

C language compilers are in general using the stack to pass parameters between functions, but to be able to use shared libraries smoothly, several compilers offer ways to force parameters in registers and automatically use the right library base and function index.

The two largest commercial C compilers on Amiga, SAS/C and Aztec C, both provide such solutions by special pragma instructions. A pragma instruction is a line starting with "#pragma", which is a compiler instruction keyword, followed by the compiler specific text. Such a pragma defines the function, which library base it needs and in which registers the parameters must be stored. By using such pragmas you don't have to call or link any glue code within your program.

The GNU C compiler, which is a freely distributable C and C++ compiler, has a very complicated way to solve this problem. It declares and uses inlined functions that use GNU's own "asm" instruction to set the proper registers to the right values.

SAS/C pragmas are built up like this:

```
#pragma name of call with base name, index, registers
which needs pragma
Compiler function name, name, index of call
```

Which kind of library call should this pragma generate? There are three different ones:

"libcall" makes a standard library call

"tagcall" makes a standard library call where the last parameter points to a tag list

"syscall" makes a call to exec.library <lib base> The library base name to use. Not specified for "syscall" calls.

Example: "DiskfontBase" (The name of diskfont.library's library base.) <name>

Function name identifier

Example: "MyFunction" <index>

Function index of the library. A hexadecimal, positive number (which is turned negative by the compiler when it generates the indexed library call). **Example:** "1A" (The first library function. Index of all normal libraries) <register>

Register/parameter information in a special format, a sequence of hexadecimal numbers. Reading from the right, each digit has the following meaning:

1. Number of parameters.
2. Result code register (0-6 means register D0-D6 and 8-9, A-C means register A0-A3)
- 3-4. The parameter registers, read from the left (!). The numbers are associated with the registers as in paragraph 2 above.

Example: #pragma libcall SysBase OpenLibrary 228 09D2

When using this information, a compiled result uses SysBase, the index and the parameters in registers just as we did in the assembler examples above. C language usage:

```
#include <exec/errno.h>
/* This includes the pragma too */
#include <exec/pragma.h>
#include <exec/errno.h>
openLibrary ("Diskfont", 09D2);
```

(Generate pragma files with the SAS/C utility "hd2pragma" which uses a function descriptor file as source of information. Read about function descriptor files further on.)

Indexing Effects

Compilers of different programming languages often create machine language instructions that address data indexed by a 16-bit register, instead of straight 32-bit addressing, to increase execution speed and decrease the code size.

Some libraries might request or offer a "callback function", a function supplied by you in the form of a function pointer that might get called from inside the library. A call from within a library may not have that index register set properly and therefore you must set it before you can access any data that requires that register.

In SAS/C, this is simply done by defining the function like:

```
void saved_callback(void)
{ if (index 0020, __saved_callback) return; }
```

(In the SAS and Aztec compilers, it can also be done by calling **get34()** first in the callback function.)

From version 36/37 some of the AmigaDOS system libraries feature hook abilities, which is a kind of callback function. They are also called from inside the library and then of course also demand loading of the index register the same way.

Registers

Library functions should preserve the a2-a7 and d2-d7 registers. The rest must be stored in a safe place and then brought back after the library call if you wish to be sure of their contents.

Parts of an AmigaDOS Shared Library Image

A Guide to AmigaDOS Shared Libraries

If we were content with only using shared libraries, we would have enough information by now to use all kinds of library calls.

Only scratching the surface isn't enough if we want to create something by ourselves. We must instead start digging into detailed information. How is a shared library constructed? Of which parts? How do you combine those parts to make your own shared library?

First we take a look at the parts of a shared library. A shared library does not look the same when compiled/assembled as when loaded into memory and added to the system's list. That is because when the library is loaded/added it is also modified and initialized in a few ways to make the system able to use it. But let's not haste to:

A shared library image is built up by a few different parts.

- Code preventing execution

- ROMTag structure with sub_data:

- Init table

- Function pointer table

- Data table

- Init routine

- Functions Prevent Execution

The first thing the disk image contains is a piece of code that prevent users from trying to execute the library as an executable file. That piece of code should preferably return an error code to the calling environment (that most possibly is a shell).

Example:

```
0000
0001
0002
0003
0004
0005
```

Coming up next is a ROMTag structure. ROMTags are used to link system resident modules together. The ROMTag looks like:

```
1000
1001
1002
1003
1004
1005
1006
1007
1008
1009
1010
1011
1012
1013
1014
1015
1016
1017
1018
1019
1020
```

Used by exec to find this structure when it is about to link us into the ROMTag list. This must contain RTC_MATCHWORD (the hexadecimal number 4AFC, which is a M68000 "ILLEGAL" instruction).

- rt MatchTag - This must contain a pointer to this struct
- rt Endfskip - Pointer to end of library init code.
- rt Flags - RTP AUTONIT informs exec that the structures it hit member points to an init table.
- rt Version - Library version number
- rt Type - Should contain NL_LIBRARY (found in exec/nodes.h), which informs exec about the fact that this is a shared library image.
- rt Pri - Initialization priority. 0(zero) is perfectly ok.
- rt Name - Pointer to the zero terminated library name
- rt IDString - Standard name/version/date ID string

Example:

```
1200
1201
1202
1203
1204
1205
1206
1207
1208
1209
```

The data points to an init table if RTP AUTONIT is set in structure member rt Flags.

As you can see, this structure requires some more information stored. You must have the library name and a standard IDstring stored, and the last structure member should point to a "init table".

Init Table

The init table is a table of four long words. I try to visualize them as a structure like this:

(A struct of this kind is not found in any standard include file, this is written by me.)

```
struct InitTable {
  int size;
  void (*fnPtrTable);
  void (*dataTable);
  void (*initRoutine);
};
```

it_LibBaseSize - Size of your library base structure. In common situations it is no need to use anything else but a straight struct Library as library base. I trust not be smaller than that!

it_FnPtrTable - This should contain a pointer to an array of function pointers.

it_DataTable - Pointer to a data table to exec/InitBlock format for initialization of the Library base structure.

it_InitRoutine - Pointer to a library initialization routine or NULL.

Once again we have a structure that needs more data. The function pointer table, the data table and the init routine is left.

Function Pointer Table

This should be a table of function pointers to the different functions in the library. They can be specified in two ways:

- 1) By setting the first word in the list to -1, you specify that the table is a list with 16-bit addresses relative to the start of the list. End the table with a 1 word.
- 2) By starting absolute 32 bit pointers to the functions and ending with a 1 long word. My examples will use the second way.

The pointers should point to the functions of the library. All libraries should still have a few standard functions used by exec and must not be left out. The first four entries are dedicated to such functions.

The list must look like:

```
- Open()
- Open library routine.
- Close()
- Close library routine.
- Copy()
- Copy library routine.
- Execute()
- Execute file before execution.
- Read()
- Read file routine.
- Read()
- Read second routine.
- ...
- the rest of the table, etc.
- End of table
```

How to program such functions is discussed further on. Let's continue, we have the data table and the init routine left to look at.

Data Table

The data table is used to initialize the library base structure when it's linked into the system list of shared libraries. The base is in the so called "exec/InitStruct" format. A data table is controlling a number of different initializing methods. In our case we just use a number of offsets (relative to the library base) and their initialization values.

```
1400
1401
1402
1403
1404
1405
1406
1407
1408
1409
1410
```

A Guide to AmigaDOS Shared Libraries

```

; lib name of the library
;*****
; ***** LIB_INITIALIZATION ROUTINE *****
; Set the flags that below exec will have changed
; the library and that we allow check existing.
;*****
; (A) VERSION, VERSION
; (A) VERSION
;*****
LIB_INITIALIZATION_ROUTINE
; init routine
;*****
LIB_INITIALIZATION_ROUTINE
; (A) VERSION, VERSION
; (A) VERSION
;*****

```

If you have a larger library base than a `lib` structure, you might want to add more initialize entries to this table. The only thing left now to complete our ROMTag structure is the `init` routine.

Init Routine

This routine gets called after the library has been allocated by `exec`. The library base pointer is in `D0`, the segment list is in `A0` and `SysBase` is in `A6`. This function must return the library base in `D0` to be linked into the library list. If this initialization function fails, the library memory must be manually deallocated, then `NULL` returned in `D0`.

Deallocate library memory by using something like

```

move.l D0,0
moveq #0,d0
move.l D0,0
move.l D0,0
move.l D0,0
move.l D0,0
; (A) VERSION, VERSION
; (A) VERSION
;*****

```

The segment list that we receive in `A0`, should be stored somewhere for later access. We'll need it when the library is to be removed from memory. Note that this routine will be called only once for every time the library is being loaded into memory. That makes it perfectly ok to store the segment list simply like:

```

lea segment(pcl),a0
move.l a0,d0
;*****
;*****
;*****

```

A nice way to store this data is to extend the library base structure to hold the segment list pointer too. This was the last of the initialization work. The ROMTag structure is complete. Left in the library are the functions that it should contain.

Functions

As mentioned before, there are four required functions that should be in all shared libraries. The rest of the functions are up to you to decide, design and make sure they receive proper data. How to code the functions and what to think of when doing so, is discussed in a chapter below.

Libraries in the System

We know what shared libraries are and we are familiar with all data stored in the library image. We know what functions to use when we want to access libraries and we know how to call library functions. What about low level information? What is done in the system when we call `OpenLibrary()`? How can I check if library already is loaded and

which version number that library has? How can I patch a function of an already loaded library?

Library Opening Details

When a single `OpenLibrary()` is called, a lot of things happen:

1. `Exec` checks the already loaded libraries to see if the requested library is there. If it is, go to step 6.
2. If the library name is specified without path, it is searched for in ROM, LIBS and then current directory, otherwise simply in the specified path. The first directory that holds a library with the name it searches for, will be the one it loads from. If the library wasn't found, return `NULL`. If the library was found anywhere else but in ROM, it's LoadSeg'd into memory. ROM libraries are already accessible.

3. `Exec` scans the library for the `BASE` word with a following 32-bit pointer back to it. That would be the beginning of a `ROMTag` structure!
4. `InitResident()` is called, which hopefully finds the `RTP_ALTOINIT` flag set in the `struct` member of the `ROMTag` structure and therefore calls `MakeLibrary()` which performs Memory is allocated to fit a jump table and the library base structure. The size of the library base structure is found in the first long word of the data table. The jump table is created by a call to `MakeJumps()` and is placed just before the library base in memory. The size of the allocation can be read in the library base structure (`lib_NegSize + lib_Posize`).

The library base structure is initialized using the data table list and an `initStructure()` call. The `init` routine is called with the library base pointer in `D0`, `SysBase` in `A6` and the segment list pointer in `A0`. If `NULL` is returned, then `OpenLibrary()` fails and returns `NULL`. (Deserve that any kind of failure in `InitResident()` means that the library is never added to the system.)

5. `AddLibrary()` adds the library to the system list, making it available to programs. The checksum of the library entries will be calculated.

6. The `OpenLibrary()` call's version number parameter is checked against the version number of the library base (`lib_Version`). If the requested number is higher than the library version, `OpenLibrary()` fails and returns `NULL`.

7. The open function of the library is called. If that fails `NULL` is returned, otherwise the library base is returned in `D0`.

If the same library exists in LIBS with one version and in current directory with a later version, `OpenLibrary()` will always go for the one that it finds first. In this case that is the library in LIBS. If that library has a too low version number, `OpenLibrary()` fails.

As you can see, `OpenLibrary()` is a rather tight level function. By using the other mentioned functions you can add a library to the system without going the way I describe in this article. But that wouldn't make it a standard shared library.

Library List

`Exec` keeps track of all libraries that are opened. We can take part of `exec`'s library list information by studying the linked list starting at `SysBase->LibList`. That pointer points to a `struct List`, whose `struct Node` pointers point to the `struct Library` of all libraries that are currently in memory. This sounds more difficult than it is. Take a look at this small example.

To find a certain library name in the library list, we can write:

```

struct Library *lib;
struct Library *lib;
PatchLib();
lib = struct Library *lib;
PatchLib();
struct LibList;
PatchLib();

```

All libraries that are opened get a jump table created. That means that even ROM based libraries get a jump table in RAM. When using functions in any library, we always go through that jump table which consists of nothing but a number of `JMP ADDRESS`. As you unsee-

A Guide to AmigaDOS Shared Libraries

stead, these jumps are only used to jump into the library to perform whatever they are designed to. By changing an entry in that jump table, we can make a real library call to call our own function instead of the original! But to change an entry is more than just storing in the list (since there are checksums and things that have to be correct). The correct way to do it, is to use SetFunction(), which can make one of those JMP's jump to our own code.

To replace OpenLibrary() with our own function, we can do it like:

```
#include <exec/types.h>
#include <exec/errno.h>
#include <exec/semaphore.h>
void patch(void)
{
    ULONG address;
    address = (ULONG)(&OpenLibrary);
    EXEC_OpenLibrary();
}
/*
 * We would call this call to OpenLibrary() with it
 * call our own function instead
 */
/*
 * To test this, we simply use SetFunction()
 * again, we really should be careful, but we
 * don't see a reason someone else might have
 * patched the function after we call it so
 * this is a test of our original, we could still
 * patch patch.
 */
SetFunction(&patch, -128, 0, 0);

/*
 * This is the original library loader __all.lib's
 * register __all variable
 */
/*
 * Note any one of these options. To remember that
 * our library register is not initialized now, and
 * if you were to call exec you can restore the
 * previous value before returning from this
 * function. We don't want to crash any programs.
 */
/*
 * If you call exec register __all
 */
```

Patching libraries are often used when creating debugging tools such as the well known "Mungwall" which patches AllocMem and FreeMem, "Snowder" which is a debugger to most of the library's functions and others) and for programs that otherwise or somehow changes the functionality of a function system wide (such as "ExpandWindows" which patches OpenWindow() and how it files window opening, "RTPatch" or "bechange" which catches different requester calls to bring up a particular library requester instead). NCL's SetFunction() can not be used on non-standard libraries like desktop! If you want to patch exec library, you must manually (Forbid), preserve all 6 original bytes of the jump table entry, find library() to evaluate the new checksum and then Patch().

Programming Functions

Shared Libraries must be programmed by someone. Until now you've assumed you can control, play around and change already existing libraries. Now, we'll check out more of what there is to know to be able to program a library. The ROMTag initializing is of course required when programming a library, but the biggest part and the part that really makes the library is still the functions.

You're not restricted to anything when it comes to the location of the routines you want to put in a shared library. What must be thought of when creating tools for a shared library using a copy file, is that there is no main function or start-up routines, and therefore so one of the symbols declared in those modules will be declared if you don't do it yourself.

There are always four functions required that have to be in every library. They are Open(), Close(), Expunge() and Remove() and are called by exec when the library is to be opened, closed and removed

from memory (the fourth is reserved for future use). Exec runs off task switching while executing these routines (via TaskID), so we should make them not take too long. (When using SAS/C these functions won't be necessary to code, see the "Compiling" and "Linking" chapters.)

```
- Open()
  (Library base, int, void *addr)
```

This routine is called by exec when OpenLibrary() (or more correct InitResident()) is called. Open should return the library pointer in L0 if the open was successful. If the open fails, NULL should be returned. It might fail in cases where we allocate memory on each open, or if the library only can be open once at a time.

Example:

```
/*
 * This is the library's open routine
 */
addge
/*
 * EXEC_OPENLIB()
 * Check off delayed expunge
 */
beq
EXEC_REMOVE_DELAY_EXPUNGE
/*
 * Return library base
 */
move.l
d0,d0
rte
/*
 * (Library base, int)
 */
```

This routine is called by exec when CloseLibrary() is called. If the library is no longer open and there is a delayed expunge, then Expunge! Otherwise Close should return NULL.

Example:

```
/*
 * This is the library's open routine
 */
addge
/*
 * EXEC_CLOSELIB()
 * If there is a delayed expunge, return
 */
beq
relabel
/*
 * If there is a delayed expunge, set the
 */
move
EXEC_REMOVE_DELAY_EXPUNGE
beq
relabel
/*
 * Do the expunge
 */
move
Expunge
relabel
/*
 * Set the return value
 */
move
d0,d0
rte
/*
 * (Library base, int)
 */
```

This routine is called by exec when RemoveLibrary() is called, or from Close when there was a delayed expunge. If the library is no longer open then Expunge should Remove() itself from the library list, freeMem() the InitResident()'s allocation and return the segment L0 (which was given to the InitModule). Otherwise Expunge should set the delayed expunge flag and return NULL.

Because Expunge might be called from the memory allocator, it may NEVER WAIT or otherwise take long time to complete.

Example:

```
/*
 * This is the library's open routine
 */
addge
/*
 * EXEC_REMOVELIB()
 */
beq
/*
 * Do the expunge
 */
move
EXEC_REMOVE_DELAY_EXPUNGE
beq
relabel
/*
 * Set the return value
 */
move
d0,d0
rte
/*
 * (Library base, int)
 */
```


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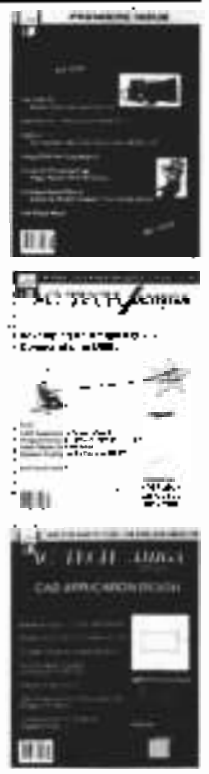
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